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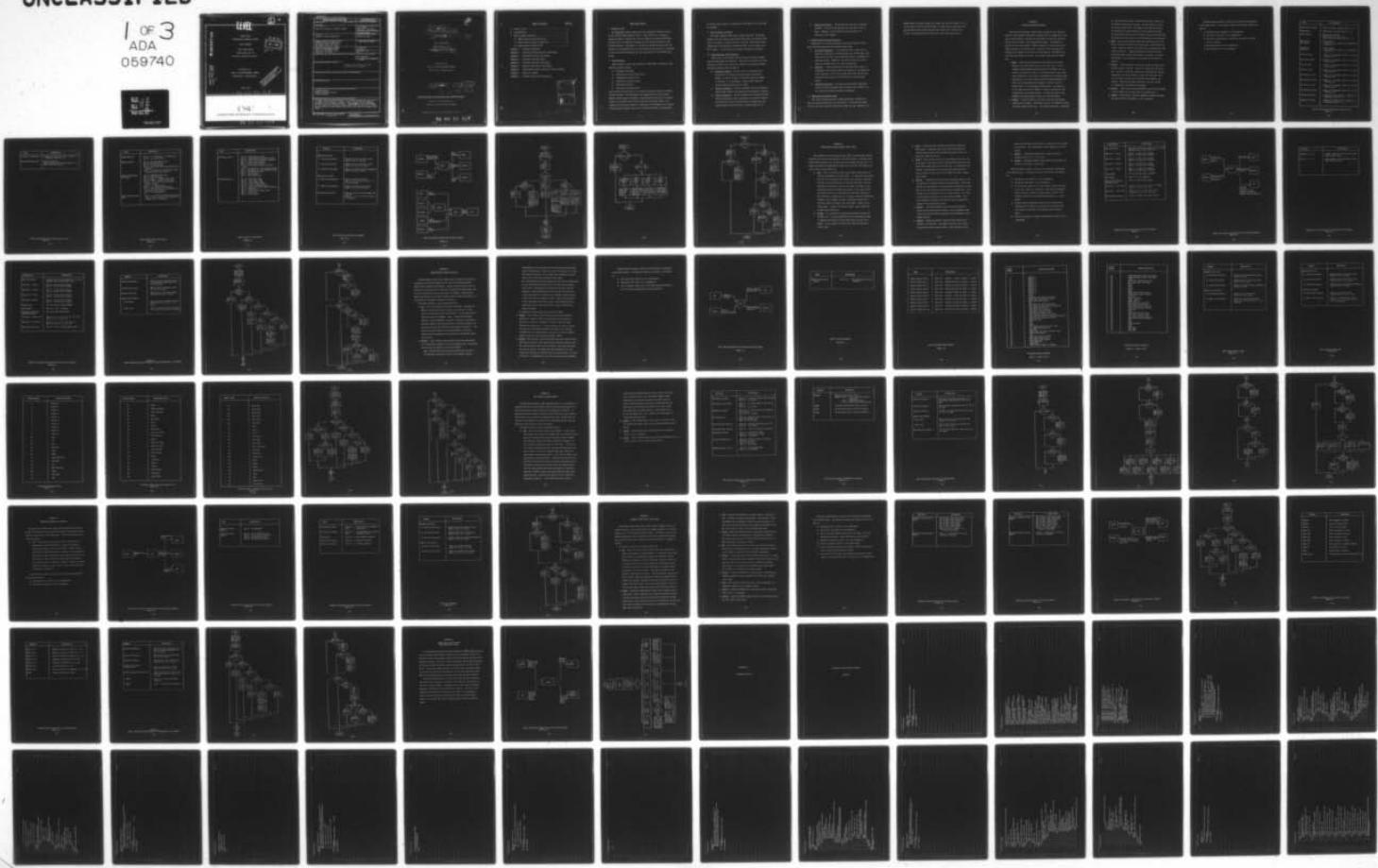
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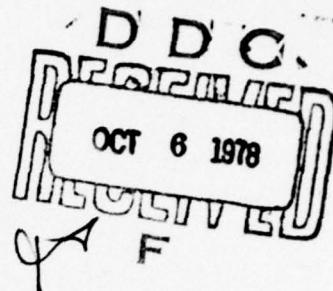
SIMULATION SOFTWARE SUPPORT

FINAL REPORT

CDRL ITEM #A004

Task Order No. 55

Contract N62269-75-C-0001



Prepared for  
NAVAL AIR DEVELOPMENT CENTER  
Warminster, Pennsylvania

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20. ABSTRACT (Continue on reverse side if necessary and identify by block number)  The report contains a description of the software modules that were written in support of the LAMPS SEAS Program. Most of these modules represent simulated avionics hardware devices. In addition there is an Input/Output Executive and a Data Collection module. Included in the body of the report are descriptions of each module, flow charts, and a profile listing of each module.		

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LAMPS FINAL REPORT

**1 SUMMARY OF TASK**

The LAMPS SEAS software support task was performed to simulate several of the avionics remote terminals (RT's). Their function is to supply a simulated hardware interface for those RTs between the Avionics Operational Program (AOP) in the AN/AYK-14 computer and the overall simulation in the CDC 6600 computer. Additionally, a routine was included to provide for the routing of AOP commands and data to the various RTs and provide for collection of data that passes through the data bus from the AOP to the CDC-6600 simulation.

**2 ACCOMPLISHMENTS**

The end product of this task provides for LAMPS SEAS a simulation of the following hardware modules:

- Converter Multiplexer
- Communication System Control Group
- Navigational Interface Unit
- Multifunction Control System
- MAD Signal Processor
- Ordnance Launch Control Set.

Also included in this product is a combined input/output Executive and Data Collection module. The development and implementation of each of these modules includes general flowcharts, design/coding, definition of variables unique to each module, batch drivers and batch environment debug. Descriptions of the various modules is contained in the Appendices (by direction of the cognizant engineer work on the MAD Signal Processor was terminated

as of April 1978, however, a description of the module as of that date is included).

### 3 REMOTE TERMINAL PROCESSING

The Remote Terminals (RTs) share a common structure - processing commands from the Avionics Operational Program (AOP), RT internal operations, and output of status and data to the AOP. Within these three subdivisions the processing of information which is not unique to the RT is similar. In this section the common processing is described.

#### 3.1 Remote Terminal Input Processing

Each RT has an input buffer from the AOP which contains command words and data words for processing. Those RTs in the 40 ms loop have non-circular buffers, the others have circular or wrap-around buffers. The common transfers from the AOP are:

- Initialize Terminal - The RT is put in a quiescent state during which all internal and input/output processing is halted. If the RT is under a "self-test" when the command is received, it is terminated. Output buffer flags that may have been previously set are reset.
- Initiate Processing - The RT's quiescent state is terminated, allows normal internal and input/output processing to commence.
- Initiate Self-Test - The RT is placed in a simulated self-test state by ceasing all normal processing, the self-test counter is initialized, and the RT status word is inserted into the output buffer to the AOP with the "receive busy" bit set.

- Normal Data Transfer - The RT determines the type of transfer required. If an RT to AOP transfer, the "data sent" flag is reset. Otherwise, the RT processes the input data as is required by that terminal.

### 3.2 Remote Terminal Internal Operations

In addition to its unique operations, each RT processes the self-test, BIT status monitoring and quiescent state check.

- Bit Status Monitoring - If a transition from a logic zero to logic one is detected in the BIT status word, the RT status word (with the T/F bit set) and the BIT status word is transferred to the output buffer. Otherwise, the new BIT status is saved to reset any possible logic 1 to logic 0 transitions.
- Self-Test - During a self-test the RT's self-test counter is decremented and the result tested for completion. On completion of the self-test, the RT status (with the T/F bit set) and the current BIT status words are transferred to the RT's output buffer.
- Quiescent State Test - Upon entering the internal operations section, the RT's quiescent state is tested, and if found to be on, further operational processing is bypassed.

### 3.3 Remote Terminal Output to AOP

The output processing section involves testing for completion of previous output acceptance by the IIU and AOP. If the previous output has not been taken, then appropriate error flags are set, otherwise, the

PACKPP routine is called to pack the current data into the format of 2-1/2  
-16 bit words per 60 bit CDC 6600 words, a header word is constructed for  
the PP program, and the data available and "status sent" flags are set.  
If data is also being sent this cycle, the "data sent" flag is set.

APPENDIX A  
CONVERTER MULTIPLEXER MODULE

The Converter Multiplexer (CMUX) module provides for the simulated control of AOP commands, formating of display data for refreshing the ATO and SO display buffers, building the data buffer for the AOP, reading of ATO and SO hook signals, and computes TACAN signals. The module is divided into two main routines - CMUX1 (resident in the 40 ms loop) and CMUX2 (resident in the 200 ms loop). Basically, CMUX1 processes AOP commands and refreshes the ATO and SO display buffers, and CMUX2 builds the output data buffer to the AOP. The routines comprising the module are:

- CMUX1 - This routine processes all AOP commands to the CMUX module and is the driving routine in the 40 ms loop. The AOP commands, MODE/DISCRETE DATA and NORMAL DATA TRANSFER, are processed as described in section 3, with the exception that normal data transferred to the module are transferred to a holding buffer. Additionally, the module accepts the MULTI-MESSAGE TRANSFER command, and on encountering this command, transfers the multi-message data to a multi-message holding buffer. On completion of its input buffer scan, CMUXCDT is called to process all data transferred to the holding buffers. On regaining control from CMUXCDT, Helo heading data is saved for later processing.
- CMUXCDT - Called by CMUX1, this routine processes the holding buffers built by CMUX1. CMUX header word one is decoded and tested for buffer count and IPL data. If a buffer count error is detected

or a bad IPL address exists, the Header Work Error flag is set, and further processing is bypassed. The data block is scanned for acoustic display data, MAD display data, ATO display data, or SO display data and transferred to the appropriate buffer.

If during this process an error in header word two is encountered, the Header Work Error flag is set and processing is discontinued.

- CMUX2 - This routine performs CMUX output processing to the AOP and is the driver routine in the 200 ms loop. Upon entering the routine, self-test and BIT status processing is performed as described in Section 3. Routine CMXDATA is called to build the CMUX normal data transfer output buffer to the AOP. On return from CMXDATA, output processing is performed as described in Section 3.
- CMXDATA - Called by CMUX2, this routine builds the normal data transfer buffer to the AOP. The data inserted into the buffer are: electronic altimeter, TACAN range, TACAN bearing, ATO hook coordinates, SO hook coordinates, pitch sine and cosine, roll sine and cosine, heading sine and cosine (four samples, two sources), indicated air speed, barometric altitude, outside air temperature, and latest MAD conversion.
- MUXPACK - This routine called by CMXDATA, packs (sign extended) a real variable into a binary value of requested size.
- KZSCOMP - This routine, called by CMXDATA, transforms the input variable from one's complement to two's complement.

The CMUX module performs a subset of the functional requirements of the CMUX hardware. The disparity between the hardware and the software is:

- The Master Clear function is not implemented.
- The manual "self-test" is not implemented.
- The Initial Program Load is tested but the actual load data is not processed.
- The AOP backup mode is not implemented.
- The backup CMUX is not implemented.

WORD	DESCRIPTION
Electronic Altimeter	Binary altitude, unsigned (bits 12 - 0)
TACAN Range	TACAN range, unsigned (bits 15 - 0)
TACAN Bearing	Bearing sign (bit 15) Status code (bits 14 - 13) TACAN bearing, unsigned (bits 12 - 1)
ATO STICK-X	X Displacement
ATO STICK-Y	Y Displacement + (signed, 2's complement) (bits 15 - 6)
SO STICK-X	X Displacement
SO STICK-Y	Y Displacement + (signed, 2's complement) (bits 15 - 6)
NIU Pitch Sine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
NIU Pitch Cosine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
NIU Roll Sine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
NIU Roll Cosine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
NIU Heading 1 Sine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
NIU Heading 1 Cosine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
NIU Heading 2 Sine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
NIU Heading 2 Cosine	Signed, 2's complement (bits 15 - 2, bit 0 validity bit)
Indicated Airspeed	Indicated airspeed (knots) - signed, 2's complement (bits 15 - 6)
Barometric Altitude	Barometric Altitude (feet), signed, 2's complement (bits 15 - 6)

CMUX to AOP Message Word Formats (Page 1 of 2)

Table A-1

WORD	DESCRIPTION
Outside Air Temperature	Outside Air Temperature (°C), signed, 2's complement (bits 15 - 6)
Latest MAD Conversion	Sign bit (bit 15) Digitized MAD Analog Signal (bits 14 - 6) New/Old MAD data (bit 0)

CMUX to AOP Message Word Formats (Page 2 of 2)  
Table A-1

WORD	DESCRIPTION
Header Word One	Bit 15, 1 = IPL data, 0 = 'display data Bits 8 - 0, Buffer count
Header Word Two	Bit 15, Acoustic Display Data Bit 14, ATO Display Data Bit 13, SO Display Data Bit 12, Header Word Three has MAD Display Command Bits 7 - 0, Number of words between this header Word Two and the next.
Acoustic/MAD Header Word Three	Bit 15, LOFAR/DIFAR ALI data Bit 14, DEMON ALI data Bit 13, Ranger - Doppler Raster data Bit 12, Ranger - Bearing Raster data Bits 11 - 7, Active Block Count for a Raster display Bits 6 - 5, Display zone Bits 4 - 3, Display zone blanking Bit 2 - Following data is continuation of previously received data Bits 1 - 0, MAD scaling
Buffer Address Header Word	Bits 15 - 0, Follows header word one during IPL, or header word two when ATO or SO display data is indicated.

AOP to CMUX Header Word Formats

Table A-2

WORD	DESCRIPTION
BIT Status Word 1	<p>Bit 15 - A/D Converter Fault          Bit 14 - Synchro/Digital Converter Fault          Bit 13 - Power Off-On Transient Occurred          Bit 12 - Block Count Anomaly          Bit 6 - TACAN Interface Fault          Bit 5 - Electronic Altimeter Interface Fault          Bit 4 - SO Symbol Gen. and Interface Fault          Bit 3 - ATO Symbol Gen. and Interface Fault          Bit 2 - Hook Control Fault          Bit 1 - Syncro Fault          Bit 0 - Vital CMUX Fault</p>
BIT Status Word 2	<p>Bit 15 - CMUX Temp. High          Bit 14 - SO CD Temp. High          Bit 13 - ATO CD Temp. High          Bit 12 - Invalid Header Word          Bit 11 - Memory Checksum Invalid          Bit 10 - Converter Display Buffer Overflow          Bit 3 - TACAN Fault          Bit 2 - Electronic Altimeter Fault          Bit 1 - SO CD Fault          Bit 0 - ATO CD Fault</p>

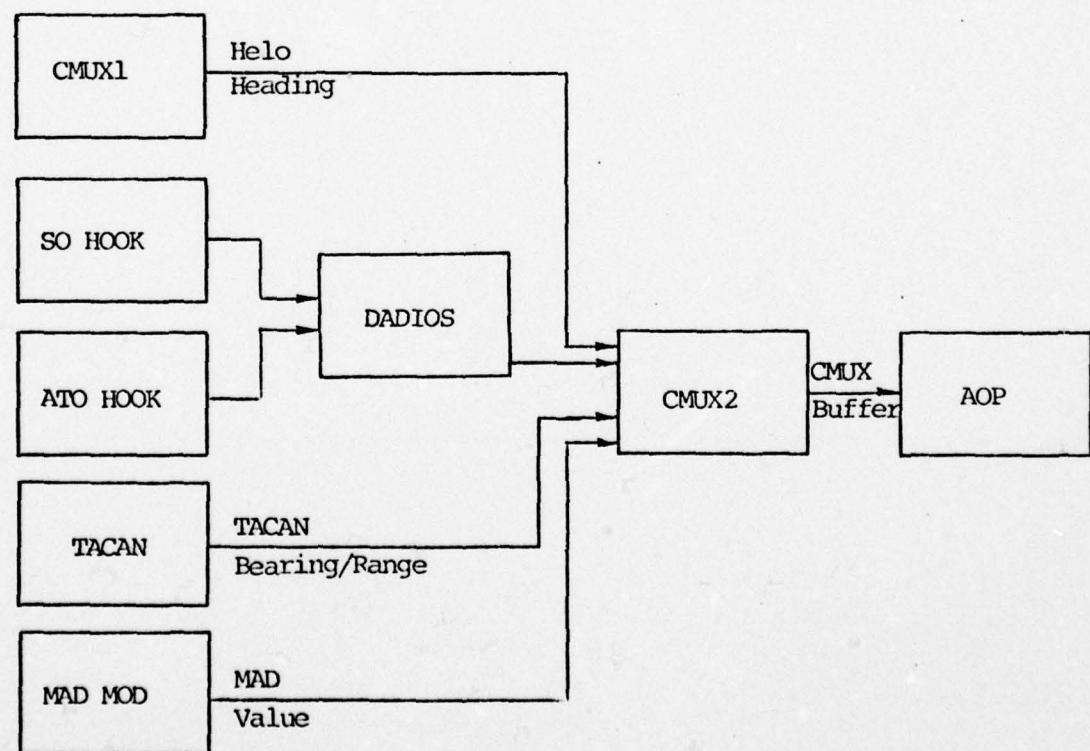
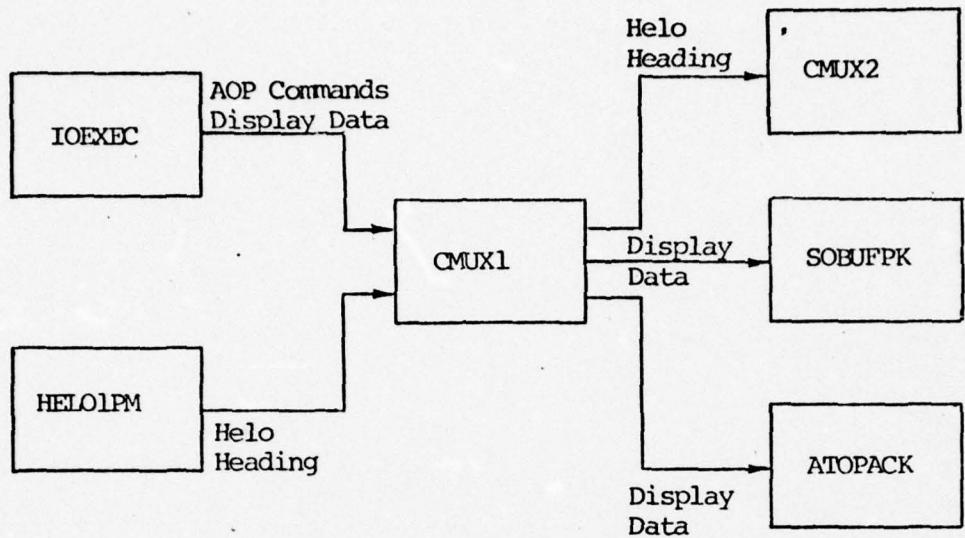
CMUX to AOP Bit Status Words

Table A-3

COMMAND	DESCRIPTION
<b>Mode/Discrete Data</b> <ul style="list-style-type: none"> <li data-bbox="376 451 703 487">● Initialize Terminal</li> <li data-bbox="376 536 703 572">● Initiate Self-Test</li> <li data-bbox="376 620 703 656">● Initiate Processing</li> </ul>	Module placed in quiescent state (bits 0, 11, 12, 14 set)  Module placed in self-test state (bits 0, 1, 11, 17, 14 set)  Modules internal processing commenced (bits 2, 11, 12, 14 set)
<b>Normal Data Transfer</b> <ul style="list-style-type: none"> <li data-bbox="376 811 703 840">● AOP to CMUX Transfer</li> <li data-bbox="376 925 703 954">● CMUX to AOP Transfer</li> </ul>	Module to receive AOP data (bits 5, 11, 12, 14 set; bits 0 - 4 set as required)  Module to transfer data to AOP (bits 5, 10, 11, 12, 14 set)
<b>Multi-Message Transfer</b>	Module to receive multi-message data from AOP (bits 6, 7, 11, 12, 14 set; bits 0 - 4 as required)

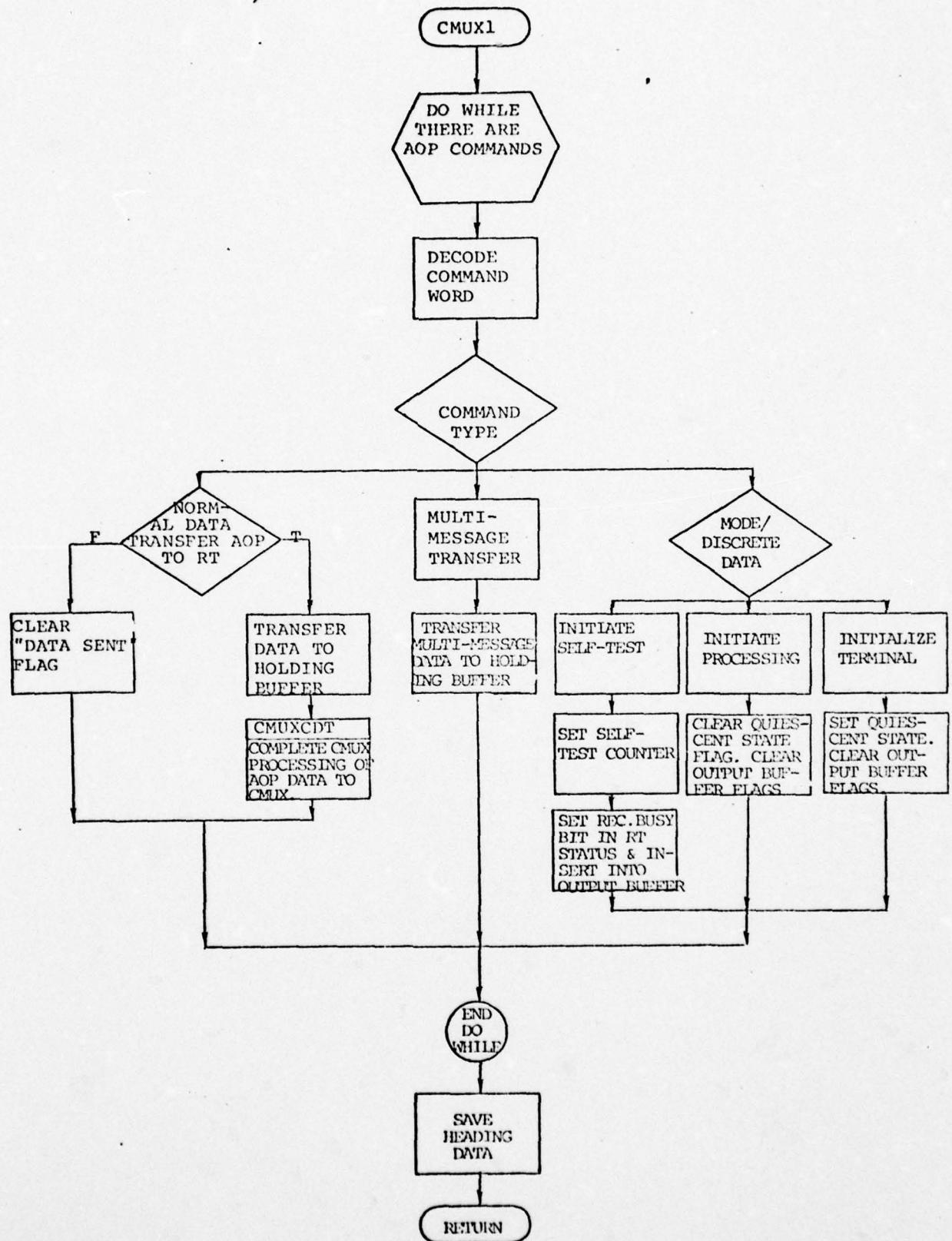
AOP to Converter Multiplexer Commands

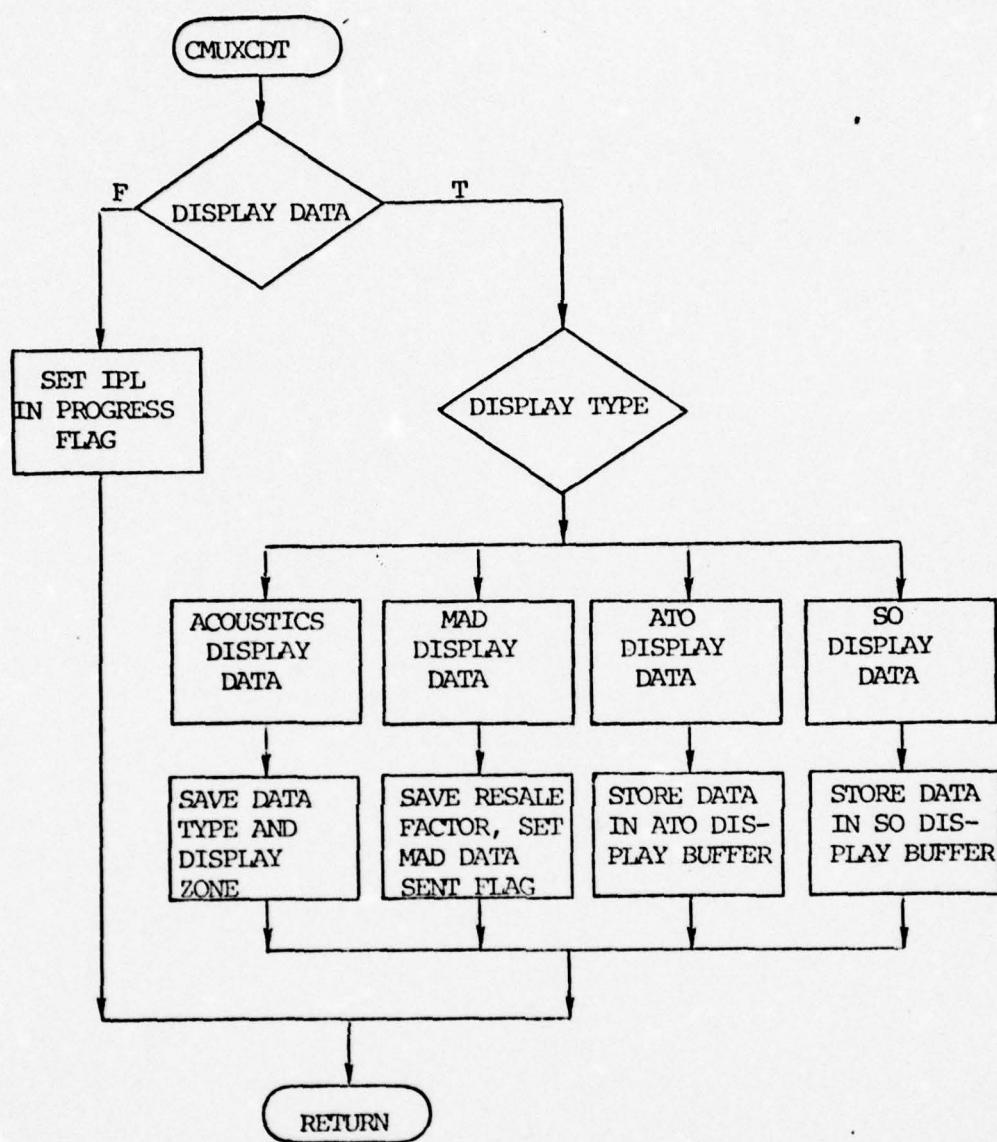
Table A-4

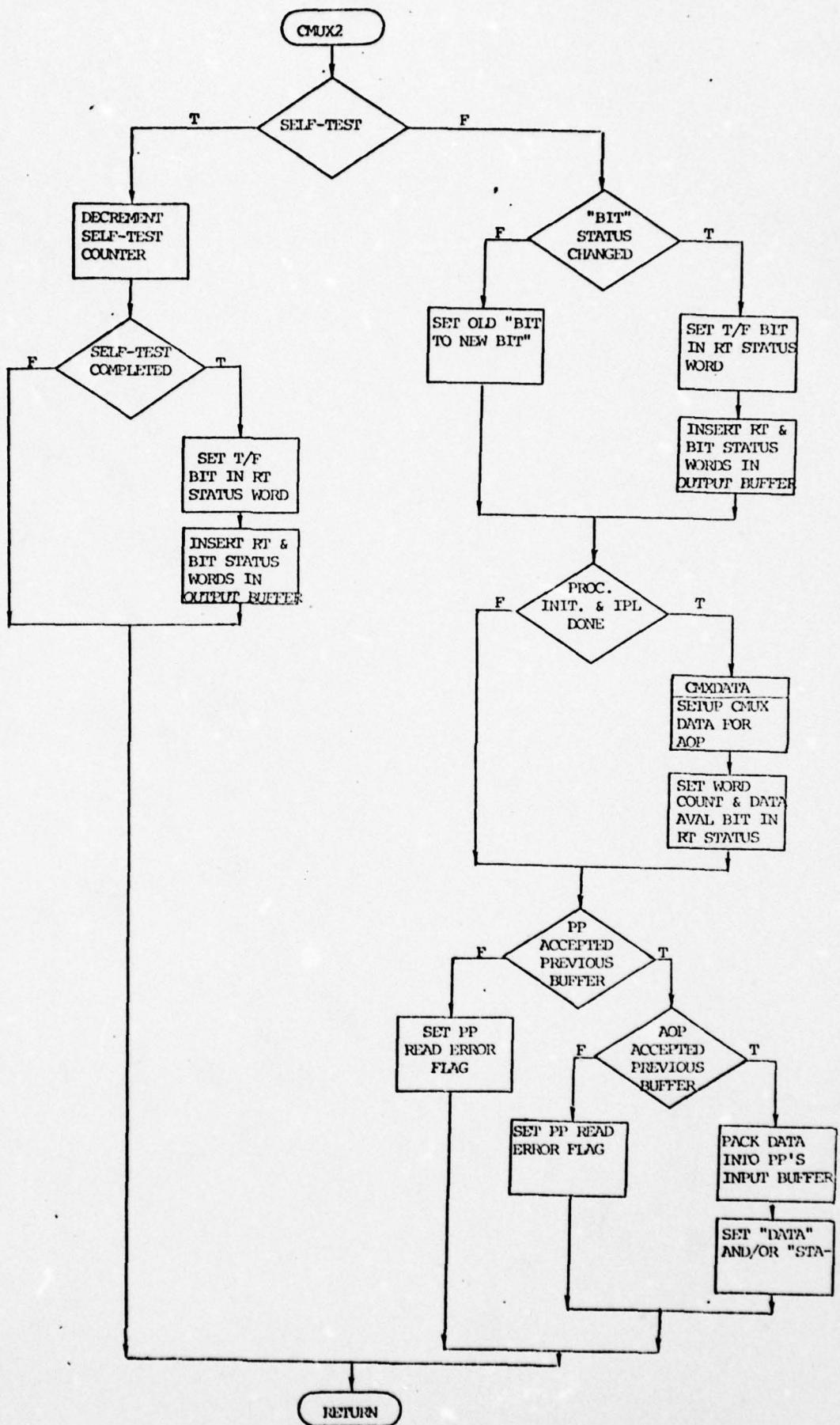


CMUX Input/Output to/from AOP and Other Modules

Figure A-1







APPENDIX B  
COMMUNICATION SYSTEM CONTROL GROUP MODULE

The Communication System Control Group (CSCG) software module handles simulation of the essential elements of the CSCG hardware. The module provides simulated control over the UHF radio and sonobuoy receiver units. It formats and outputs simulated CSCG status data to the AOP. The module consists of nine routines which are:

- CSCG - This is the main routine which directs and controls all functions performed in the CSCG module. It scans the input buffer from the AOP for command words (Normal Data Transfer, Initialize Terminal, Initiate Processing, or Initiate Self-Test), sets the appropriate operational status of the module, and sets an error flag should an invalid command word appear in the input stream. Self-test processing is then handled as described in Section 3. The CSCG module, through the use of several additional subroutines (CONTROL, UDICP, PERIPHL, SONOINF and DTOAINF) handles those functions which are unique to the CSCG module. These are described below. Finally, the routine handles output processing as described in Section 3.
- CSCGNDP - In the event of a Normal Data Transfer from the AOP to CSCG, this subroutine handles the task of removing the block of command (data) words from the input buffer for use by the module. If the transfer is CSCG to AOP, then the data sent flag is reset.

- UDICP - Subroutine UDICP updates inputs from the simulated CSCG Control - Indicator panel in the form of UHF mode and channel selection and resets the appropriate bits in the outgoing data words for the AOP.
- HEADER - This routine sets bits in the header word of the outgoing status (data) word block to indicate which outgoing status words have changed since the last CSCG call. It also checks for changes in the remainder of the status word block and sets a flag to indicate to the main routine (CSCG) when such a change has occurred.
- PERIPHL - Subroutine PERIPHL updates the present status of the D/L mode and the sonobuoy receivers signal strength. The signal strength is calculated by first determining the distance from the helo to the buoy assigned to the particular receiver unit. This distance is then associated with an integer (from 0 to 7) using a step-function approach to give the signal strength. After such information is determined, PERIPHL makes the appropriate changes in the outgoing data words.
- SONOINF - Subroutine SONOINF obtains the switch function values for the eight sonobuoy receiver units, translates these values into channel numbers and passes this information to the SONOBOY routine.
- DTOAINF - Subroutine DTOAINF calculates OTPI bearing, when the UHF is in OTPI mode. The routine searches for an active, in-water buoy with RF channel equal to that indicated in the

keyset and calculates the bearing to it relative to the current helo position. This information is then supplied to the DTOA module.

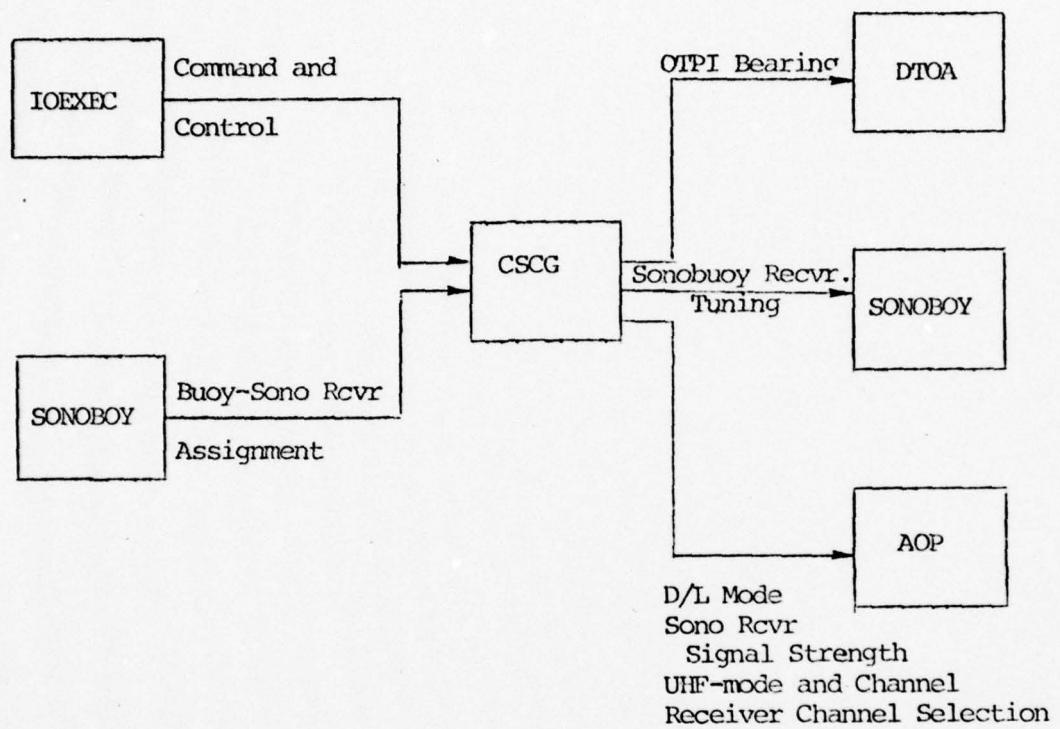
- SETABIT - Subroutine SETABIT sets a given bit within a specified word to 0 or 1 as desired.
- READBIT - Subroutine READBIT right-justifies and returns the value of a bit within a given word.

The CSCG module performs a subset of the functional requirements of the CSCG hardware. The disparity between the software and hardware is:

- The Master Clear function is not implemented.
- The manual "self-test" is not implemented.
- Of the two UHF radios only the UHF channel and mode settings of the UHF-1 radic are implemented. UHF antenna assignment, keyset loading of channel-frequency memory, squelch, tone, volume and CASS down-link command processing are not implemented.
- Sonobuoy Receiver processing does not route audio output signals from the sonobuoy receiver units to the data link, nor provide for the use of the sonobuoy receiver backup panel.
- The IFF interrogator, internal communications system are not implemented.

STATUS WORD	DESCRIPTION
Cmd. Word Status	Indicates which status words (1 to 16) have changed since the last CSCG call.
Sono Rcvr - 1 Chan	Bits 0 - 4 sono rcvr A tuning. Bits 8 - 12 sono rcvr B tuning.
Sono Rcvr - 1 Chan	Bits 0 - 4 sono rcvr E tuning. Bits 8 - 12 sono rcvr F tuning.
Sono Rcvr - 2 Chan	Bits 0 - 4 sono rcvr C tuning. Bits 8 - 12 sono rcvr D tuning.
Sono Rcvr - 2 Chan	Bits 0 - 4 sono rcvr G tuning. Bits 8 - 12 sono rcvr H tuning.
Switch Cmds.	Bit 15 UHF mode (AUTO or MANUAL)
UHF Channel	Bits 0 - 7 UHF-1 channel.
Peripheral Equipment Operating Stat.	Bit 0 D/L Mode (ASW or ASST)
Sono Rcvr - 1 Sig. Stg.	Bits 0 - 2, 4 - 6, 8 - 10, 12 - 14 Sono Rcvrs. F, E, B, A sig. stg.
Sono Rcvr - 2 Sig. Str.	Bits 0 - 2, 4 - 6, 8 - 10, 12 - 14 Sono Rcvrs. H, G, D, C sig. stg.
UHF Radio Mode Status	Bits 4, 15 UHF-1 mode (OTPI or ADF)

Communication System Control Group to AOP Formats  
Table B-1



Inputs and Outputs to and from the AOP and Other Modules  
Figure B-1

VARIABLE	DESCRIPTION
IRFCH(K) K = 1, 8	Channel number for each of eight sonobuoy receiver units.
ICH (K) K = 1, 8	Chute number of buoy assigned to sonobuoy receiver unit K.

Communication System Control Group/Sonobuoy Data Formats  
Table B-2

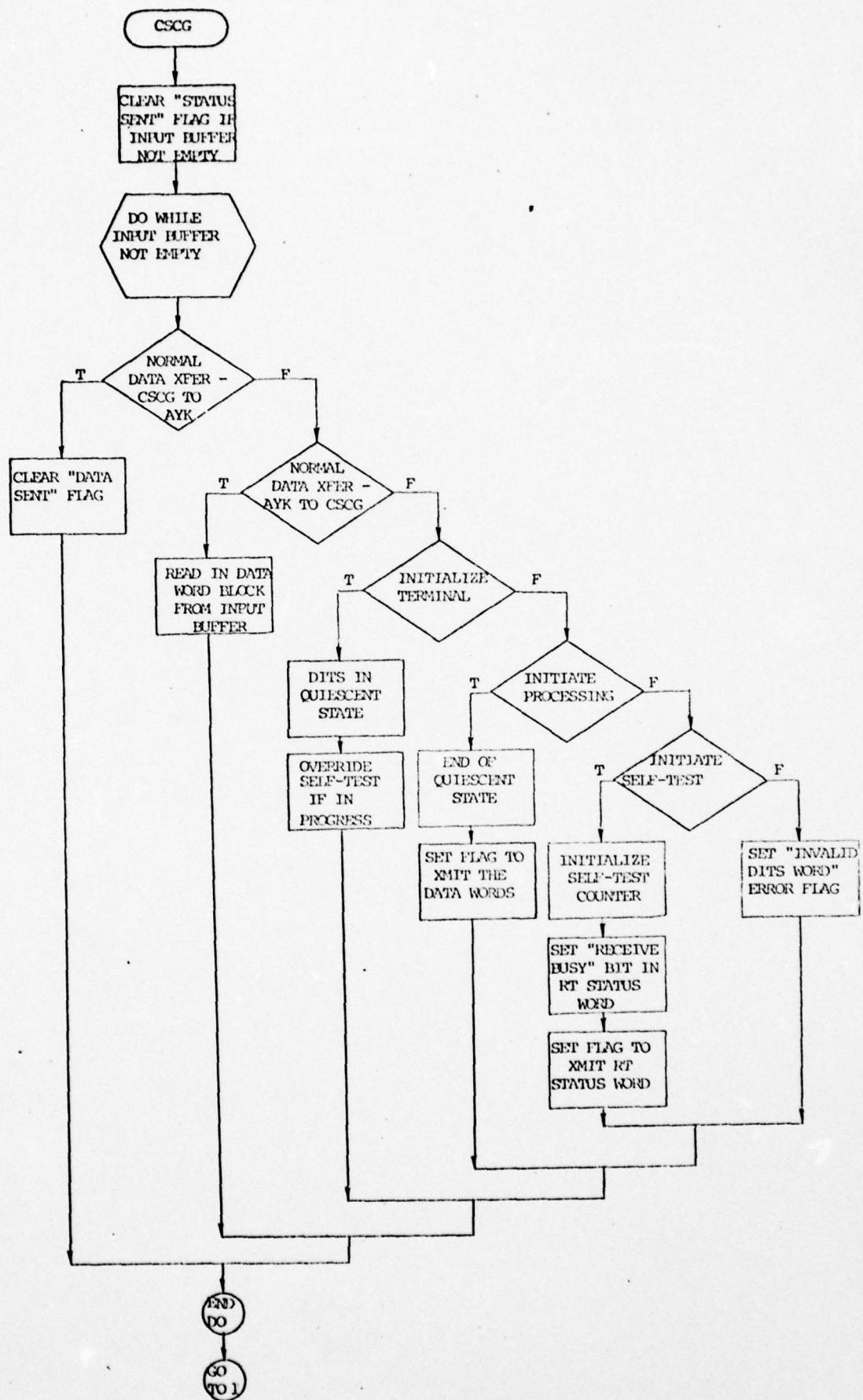
COMMAND WORD	DESCRIPTION
Cmd. Word Status	Indicates which status words (1 to 16) have changed since the last CSCG call.
Sono Rcvr - 1 Chan	Bits 0 - 4 sono rcvr A runing. Bits 8 - 12 sono rcvr B tuning.
Sono Rcvr - 1 Chan	Bits 0 - 4 sono rcvr E tuning. Bits 8 - 12 sono rcvr F tuning.
Sono Rcvr - 2 Chan	Bits 0 - 4 sono rcvr C tuning. Bits 8 - 12 sono rcvr D tuning.
Sono Rcvr - 2 Chan	Bits 0 - 4 sono rcvr G tuning. Bits 8 - 12 sono rcvr H tuning.
Switch Cmds	Bit 15 UHF mode (AUTO or MANUAL)
UHF Channel	Bits 0 - 7 UHF - 1 channel
Peripheral Equipment Operating Status	Bit 0 D/L Mode (ASW or ASST)
Sono Rcvr - 1 Sig. Stg.	Bits 0 - 2, 4 - 6, 8 - 10, 12 - 14 sono rcvrs F, E, B, A sig. stg.
Sono Rcvr - 2 Sig. Str.	Bits 0 - 2, 4 - 6, 8 - 10, 12 - 14 Sono rcvrs H, G, D, C sig. stg.
UHF Radio Mode Status	Bits 4, 15 UHF - 1 mode (OTPI or ADF)

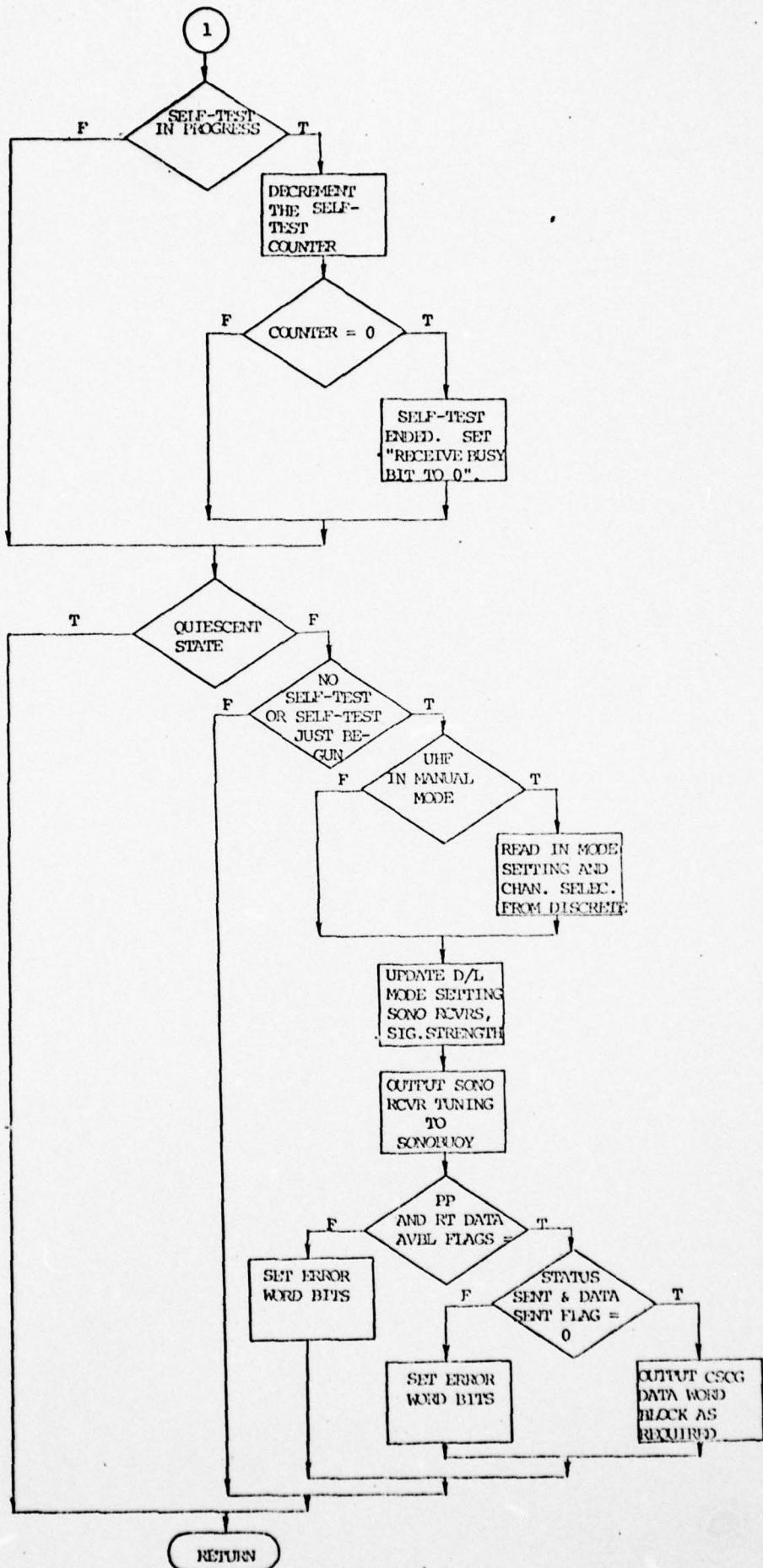
IOEXEC to Communication System Control Group Data Formats

Table B-3

COMMAND	DESCRIPTION
Initialize Terminal	CSCG forced into quiescent state, all processing halted (bits 13, 12, 11, 0 set).
Initiate Processing	CSCG processing commenced (bits 13, 12, 11, 2 set).
Initiate Self-Test	CSCG Built in Test (BIT) forced (bits 13, 12, 11, 1, 0 set).
Normal Data Transfer	
AOP to CSCG	CSCG to process new data from the AOP (bits 13, 12, 11, 5, 4, 0, set).
CSCG to AOP	CSCG to send new data to AOP (bits 13, 12, 11, 10, 5, 4, 3, 2, 0 set)

Table B-4  
AOP to Communication System Control Group Command Words (via IOEXEC)





APPENDIX C  
MULTIFUNCTION CONTROL SET MODULE

The Multifunction Control Set (MFCS) module simulates the processing of discrete switch data between the AOP, and the Air Tactical Officer (ATO) and Sono Operator (SO) keysets. Switch closure discretes from the keysets are encoded and sent to the AOP, and keyswitch lighting data from the AOP is decoded and sent to the keysets via DADIOS. Communication between the keysets and the AOP, including output buffer error checks and the self-test, are covered in detail in section 3.

The module consists of four routines which are:

- MFCS - This is the driver routine for the module. Everytime the module is called each keyset is fully processed one at a time (first the ATO keyset, then the SO keyset). It scans the keyset's AOP input buffer for commands. When a "Normal Data Transfer" command is received MFCSNDT is called to complete the processing. The other commands (Initialize Terminal, Initiate Processing and Initiate Self-test) are processed as described in section 3. Completing the input buffer scan, routine MFCSPRC is called to continue normal processing if the quiescent and self-test states are inactive.
- MFCSNDT - This routine, called by MFCS, scans the data portion of a "normal data transfer" for switch lighting data. The routine has two distinct sections, one for each keyset:

ATO - The ATO keyset section functions with only one set of out discretes (available inactive, and available active),

consequently, only the second half of the data words (available active) are processed. During the scan if the data bit is logic zero the out discrete is set to logic zero, available inactive state, and if logic one, available active state.

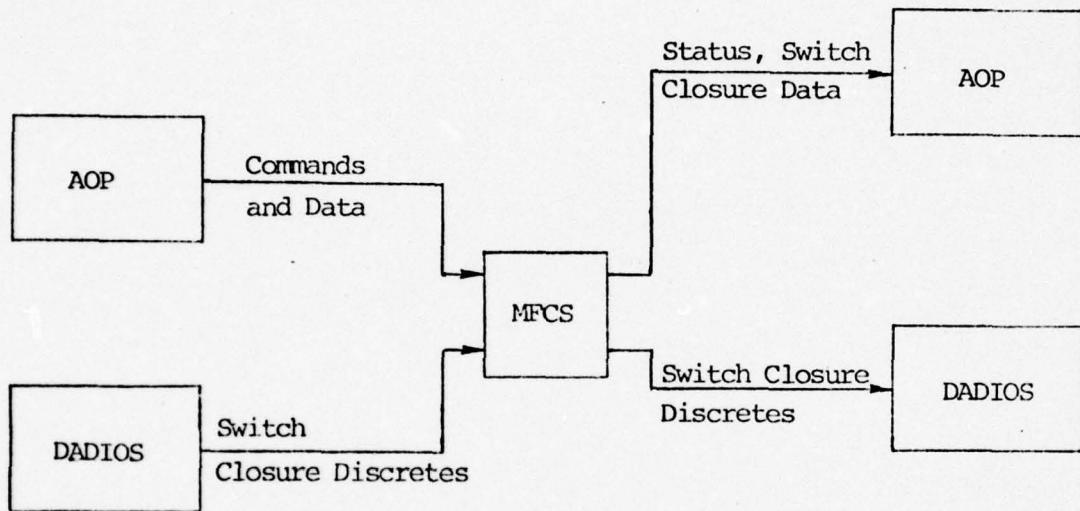
SO - The SO keyset section functions with two sets of outdiscretes - one set the available inactive state, the other the available active state - consequently both halves of the data words are processed. While processing the first half of the data words, a logic one places the outdiscrete to available inactive state; a logic zero does not change the state. During the processing of the second half of the data words, a logic one places the outdiscrete to available actual state; a logic zero does not change the state.

On completion of processing control returns to MFCS.

- MFCSPRC - This routine, called by MFCS, continues the module's processing. Change in "BIT" status processing is performed as described in section 3. MFCSIND is called to test for switch closures from the keyset. If there is data to be sent to the AOP and previous data has been processed (see section 3), the data is packed into the output buffer to the AOP via a call to PACKPP, output flag(s) are set and control returns to MFCS.
- MFCSIND - This routine, called by MFCSPRC, processes switch closure data from the keysets. The routine has two distinct portions, one for the ATO and the other for the SO keyset, since the indiscretes for each are unique. The indiscretes are scanned for up to two closures and the data is formatted into the output buffer to be sent to the AOP. On completion of its scan, control returns to MFCSPRC.

The MFCS module performs a subset of the functional requirements of the MFCS hardware. The disparity between the software and hardware is:

- The Master Clear function is not implemented.
- The manual "self-test" is not implemented.
- Due to hardware limitations in the LAMPS simulation hardware, not all of the keyswitches have been implemented.



MFCS INPUT AND OUTPUT TO AND FROM THE AOP AND DADIOS

Figure C-1

<u>Word</u>	<u>Description</u>
ATO/SO Keyset Switch Closure	Bits 15-9      Key Identification Code (unsigned)

MFCS TO AOP DATA FORMATS

Table C-1

<u>Word</u>	<u>Description</u>	
Keyset Control Word 1	Bits 15-0	Switches 0 thru 15 (Logic 1 = Green)
Keyset Control Word 2	Bits 15-0	Switches 16 thru 31 (Logic 1 = Green)
Keyset Control Word 3	Bits 15-0	Switches 32 thru 47 (Logic 1 = Green)
Keyset Control Word 4	Bits 15-0	Switches 48 thru 63 (Logic 1 = Green)
Keyset Control Word 5	Bits 15-6	Switches 64 thru 73 (Logic 1 = Green)
Keyset Control Word 6	Bits 15-0	Switches 0 thru 15 (Logic 1 = Amber)
Keyset Control Word 7	Bits 15-0	Switches 16 thru 31 (Logic 1 = Amber)
Keyset Control Word 8	Bits 15-0	Switches 32 thru 47 (Logic 1 = Amber)
Keyset Control Word 9	Bits 15-0	Switches 48 thru 63 (Logic 1 = Amber)
Keyset Control Word 10	Bits 15-6	Switches 64 thru 73 (Logic 1 = Amber)

AOP TO MFCS DATA WORD FORMATS

Table C-2

SWITCH NUMBER	SWITCH DESCRIPTION
0	Numeric 0
1	Numeric 1
2	Numeric 2
3	Numeric 3
4	Numeric 4
5	Numeric 5
6	Numeric 6
7	Numeric 7
8	Numeric 8
9	Numeric 9
10	FLY TO
11	DATUM
12	ESM SCAN CNTRL (ESM Scan Control)
13	EXPND CIRCL (Expanding Circle)
14	MARK CURSR (Mark Cursor)
15	FIX
16	PRED POSIT (Predicted Position)
17	HOOK LAT/LONG (Hook Latitude/Longitude)
18	SEND SYMBL (Send Symbol)
19	SEND POINT (Send Pointer)
20	DECR RANGE (Decrease Range)
21	INCR RANGE (Increase Range)
22	RECTR ON HELO (Recenter on Helo)
23	HELO CNTR STAB (Helo Centered Stabilization)
24	RECTR ON HOOK (Recenter on Hook)
25	TACT (Tactical)
26	TABLE
27	ESM
28	RADAR
29	IFF (Identification Friend or Foe)
30	RPT OTHER (Repeat Other)
31	NEXT PAGE
32	RADAR RCVR GAIN (Radar Receiver Gain)
33	PERST (Persistence)
34	RPM
35	DEST SYMB (Destroy Symbol)
36	HOOK VERIFY (Hook Verify)
37	HELO CONTR (Helo Control)
38	CLEAR ALERT CUE
39	BACK SPACE
40	ENTER NO CHNG (Enter No Change)

#### ATO KEYSET SWITCH ALLOCATION

Table C-3 (Page 1 of 2)

SWITCH NUMBER	SWITCH DESCRIPTION
41	CURSR FROM HOOK (Cursor from Hook)
42	CURSR FROM HELO (Cursor from Helo)
43	ON TOP
44	TACAN CORR (TACAN Correction)
45	SHIP CORR (Ship Correction)
46	Spare
47	Spare
48	Spare
49	Spare
50	Spare
51	RANGE CIRCL (Range Circle)
52	SENSR HORIZ (Sensor Horizon)
53	ALL BUT
54	INHIB (Inhibit)
55	INVRS (Inverse)
56	TRACK CLASS
57	TRACK SYMB (Track Symbol)
58	REF MARK (Reference Mark)
59	SENSR CNCT (Sensor Contact)
60	VISUL CNCT (Visual Contact)
61	LOAD CMUX
62	LINK
63	INIT SYNC (Initiate Sync)
64	RCOVR DATA (Recover Data)
65	INIT HELO (Initialize Helo)
66	INSERT SONO (Insert Sonobuoy)
67	VHF
68	DEEP
69	SCUTL (Scuttle)
70	Spare
71	Spare
72	LAMP TEST
73	SELF TEST

#### ATO KEYSET SWITCH ALLOCATION

Table C-3 (Page 2 of 2)

COMMAND	DESCRIPTION
Mode/Discrete Data <ul style="list-style-type: none"> <li data-bbox="355 445 682 481">• Initialize Terminal</li> <li data-bbox="355 530 682 566">• Initiate Self-Test</li> <li data-bbox="355 614 682 650">• Initiate Processing</li> </ul>	Module placed in quiescent state (bits 15, 0 set)  Module placed in self-test state (bits 15, 1, 0 set)  Modules internal processing commenced (bits 15, 2 set)
Normal Data Transfer <ul style="list-style-type: none"> <li data-bbox="355 772 698 808">• AOP to MFCS Transfer</li> <li data-bbox="355 857 698 893">• MFCS to AOP Transfer</li> </ul>	Module to receive AOP data (bits 15, 5, 3, 1 set)  Module to transfer data to AOP (bits 15, 10, 5 set; bits 4 - 0 as required)

AOP to MFCS Commands (ATO)  
Table C-4

COMMAND	DESCRIPTION
Mode/Discrete Data	
<ul style="list-style-type: none"> <li>● Initialize Terminal</li> <li>● Initiate Self-Test</li> <li>● Initiate Processing</li> </ul>	<p>Module placed in quiescent state (bits 15, 14, 13, 0 set)</p> <p>Module placed in self-test state (bits 15, 14, 13, 1, 0 set)</p> <p>Modules internal processing commenced (bits 15, 14, 13, 2 set)</p>
Normal Data Transfer	<ul style="list-style-type: none"> <li>● AOP to MFCS Transfer</li> <li>● MFCS to AOP Transfer</li> </ul>
	<p>Module to receive AOP data (bits 15, 14, 13, 5, 3, 1 set)</p> <p>Module to transfer data to AOP (bits 15, 14, 13, 10, 1 set; bits 4 - 0 as required)</p>

AOP to MFCS Commands (SO)  
Table C-5

SWITCH NUMBER	SWITCH DESCRIPTION
0	Numeric 0
1	Numeric 1
2	Numeric 2
3	Numeric 3
4	Numeric 4
5	Numeric 5
6	Numeric 6
7	Numeric 7
8	Numeric 8
9	Numeric 9
10	Radar
11	IFF
12	ESM
13	RPT Other
14	Spare
15	ACSTS
16	ACSTS PROC OPTN
17	Tune RCVR
18	MAD
19	MAD Scale Chng
20	Table
21	Next Page
22	RPM

SO Keyset Switch Allocation  
Table C-6

SWITCH NUMBER	SWITCH DESCRIPTION
23	PERST
24	CURSR from Helo
25	Cursr from Hook
26	Spare
27	Reset Chan
28	Chan A
29	Chan E
30	Disp Zone 1
31	Cursr Sel Audio
32	Mark ESM Line
33	Spare
34	Radar Rcvr Gain
35	Helo Cntr Stab
36	Rctr on Helo
37	Rctr on Hook
38	Spare
39	Intg Time
40	Chan B
41	Chan F
42	Displ Zone 2
43	Ping Rate
44	Hook Verify

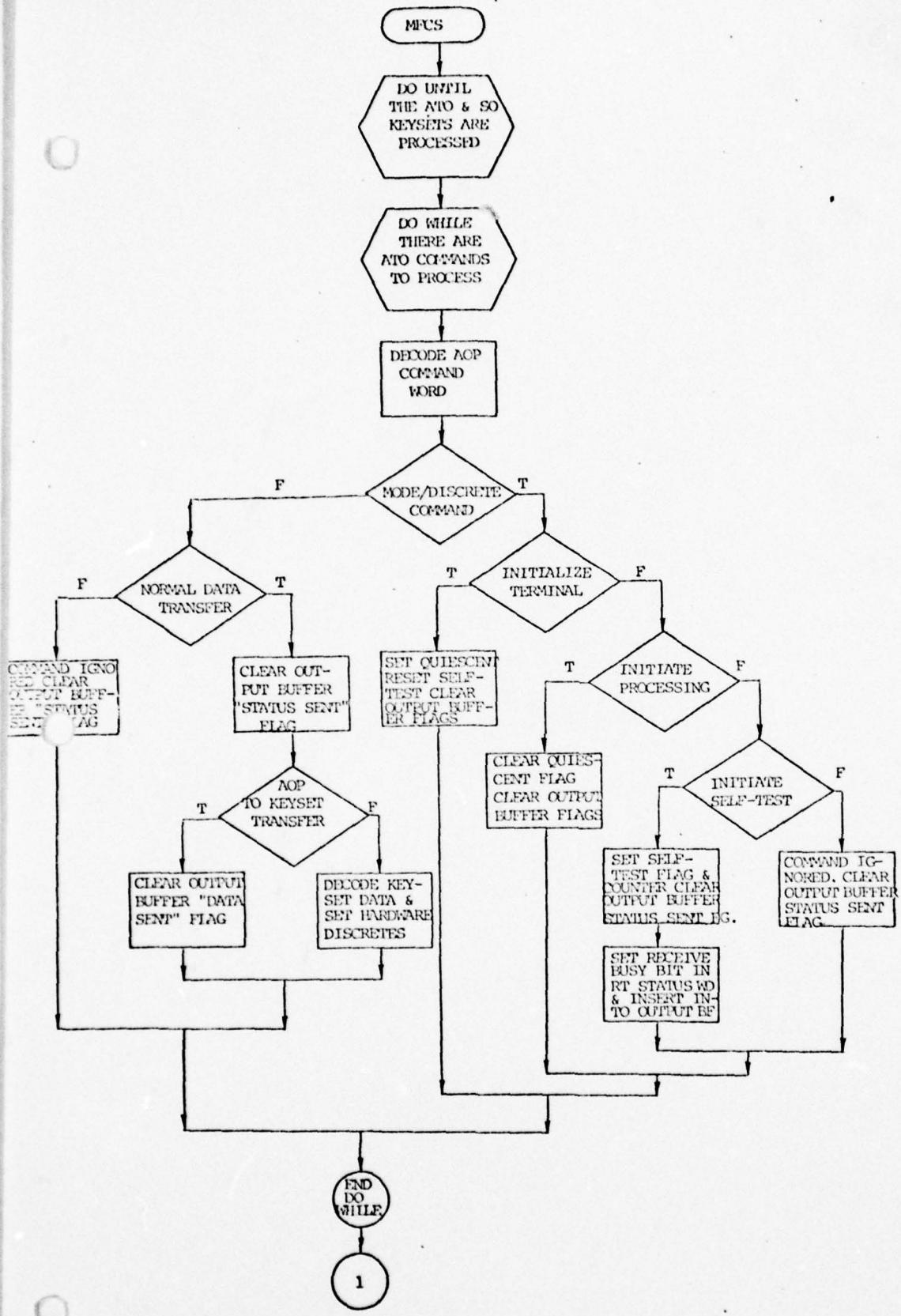
SO Keyset Switch Allocation (Page 2 of 3)  
Table C-6

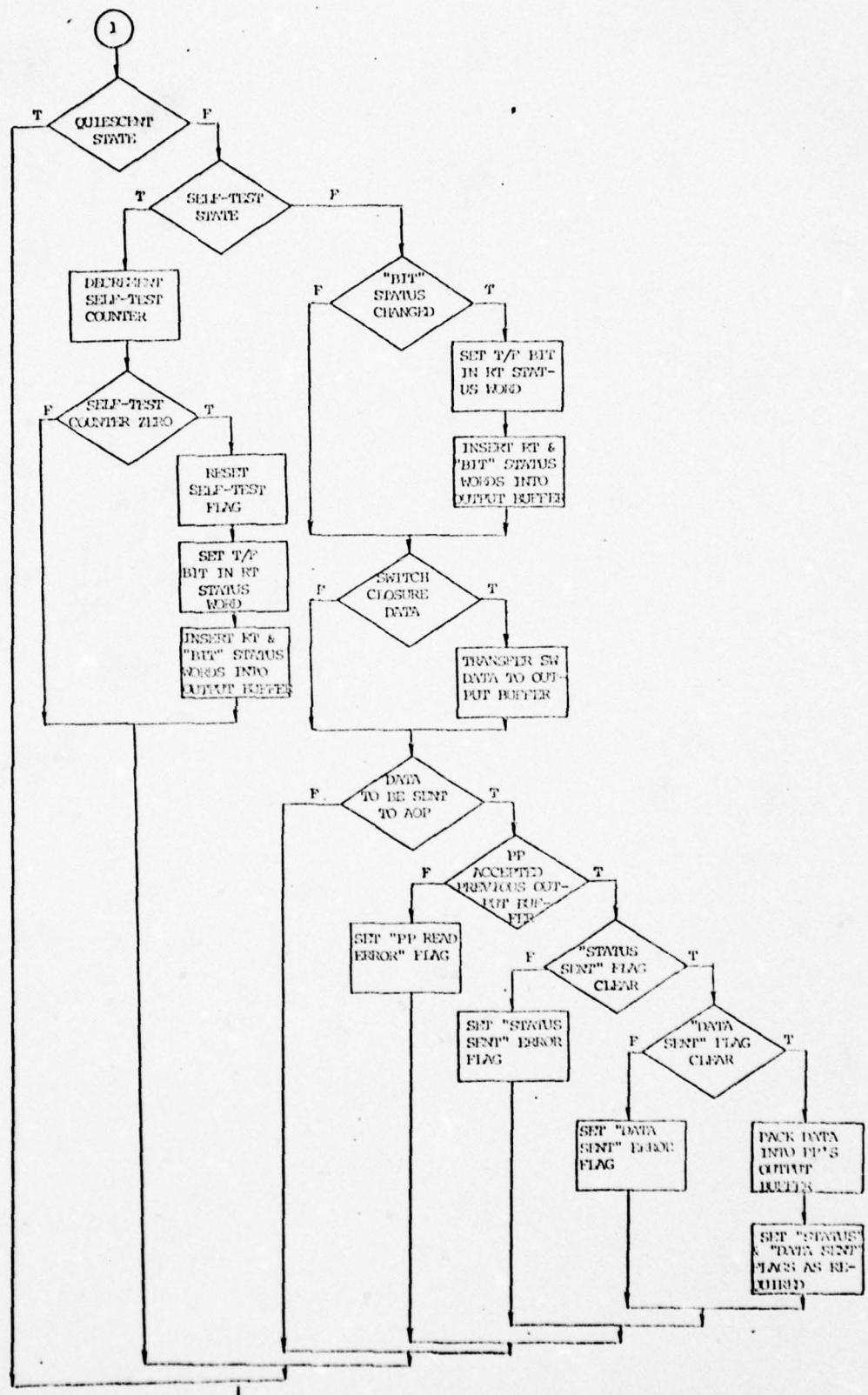
SWITCH NUMBER	SWITCH DESCRIPTION
45	Dest Symb
46	Incr Range
47	Decr Range
48	New Track
49	Edit Track
50	Insp Chng
51	Vern
52	Chan C
53	Chan G
54	Disp Zone 3
55	Ping Type
56	Back Space
57	Enter No Change
58	Lamp Test
59	Self Test
60	Track Class
61	Spare
62	Chan D
63	Chan H
64	Displ Zone 4
65	Gram
66	Fix
67	Sensr Cntct
68	Clear Alert

SO Keyset Switch Allocation (Page 3 of 3)

Table C-6

C-13





APPENDIX D  
MAD SIGNAL PROCESSOR MODULE

The MAD Signal Processor (MSP) module provides for the reception of simulated MAD data from the MADMOD subroutine and the processing of this data into event and contact messages for transmission to the AOP. In addition the module compares simulator values of helo altitude, heading, ground speed, rroll, latitude and longitude with those received from the AOP and if the difference is greater than a prescribed amount, sets the appropriate bits within an error status word.

The module consists of three routines which are:

- MSP - This is the main routine of the module. It scans the input buffer from the AOP for command words (Initialize Terminal, Initiate Processing, Multi-message Transfer, Control Command Data Transfer, Initiate Self-test, Normal Data Transfer) and sets the proper operational state of the module. In the case of an initial program load (IPL) sequence, MSP ignores the IPL words, checks to see if the observed word count matches the multi-message word count specified in the control command word, and continues normal processing. Subroutine MSP then extracts the data word count field from the current command word and if the count is non-zero, the routine checks the identification field for each incoming data word and branches to individual sections of coding to check and compare helo data and output processing mode. Self-test processing for MSP is handled as described in Section 3. After checking to make sure the

initiate processing/mode discrete is not active, the lockon is set, and the trail is out, the routine handles output processing in the manner described in Section 3 with the output processing option as previously selected by the AOP.

(The output processing options differ in the type of MAD data loaded into the output buffer.) Additionally, bit 2 in the BIT STATUS word is set if there was a previously detected multi-message error.

- MSPPACK - This routine packs a real value in a binary field of requested size when called by the output processing section of MSP.
- SETBIT - This routine sets a given bit within a specified word to 0 or 1 as desired.
- LOCATE - This routine translates latitude and longitude, given x and y values, into the grid reference point.

DATA WORD	DESCRIPTION
Helicopter Altitude	Bits 12 - 0 Binary value of helo altitude Bits 15 - 13 ID Code
Helicopter Ground Speed	Bits 12 - 0 Binary value of helo ground speed Bits 15 - 13 ID Code
Helicopter Heading	Bits 12 - 0 Binary value of helo magnetic heading Bits 15 - 13 ID/Code
Helicopter Roll	Bits 12 - 2 Binary value of helo roll in two's complement form Bits 15 - 13 ID Code
Total Mad Field (Word 1)	Bits 12 - 0 Total Field MAD sensor data Bits 15 - 13 ID Code
Total Mad Field (Word 2)	Bits 15 - 3 Total field MAD sensor data
Helicopter Heading	Bits 6 - 1 Latitude in BAMS Bits 12 - 7 Longitude in BAMS Bits 15 - 13 ID Code
Altitude Compensation	Bits 11 - 2 Binary value of altitude compensation signal Bit 12 - Sign bit Bits 15 - 13 ID Code
Processor Option Select	Bits 12 - 11 Processor Mode Bits 15 - 13 ID Code

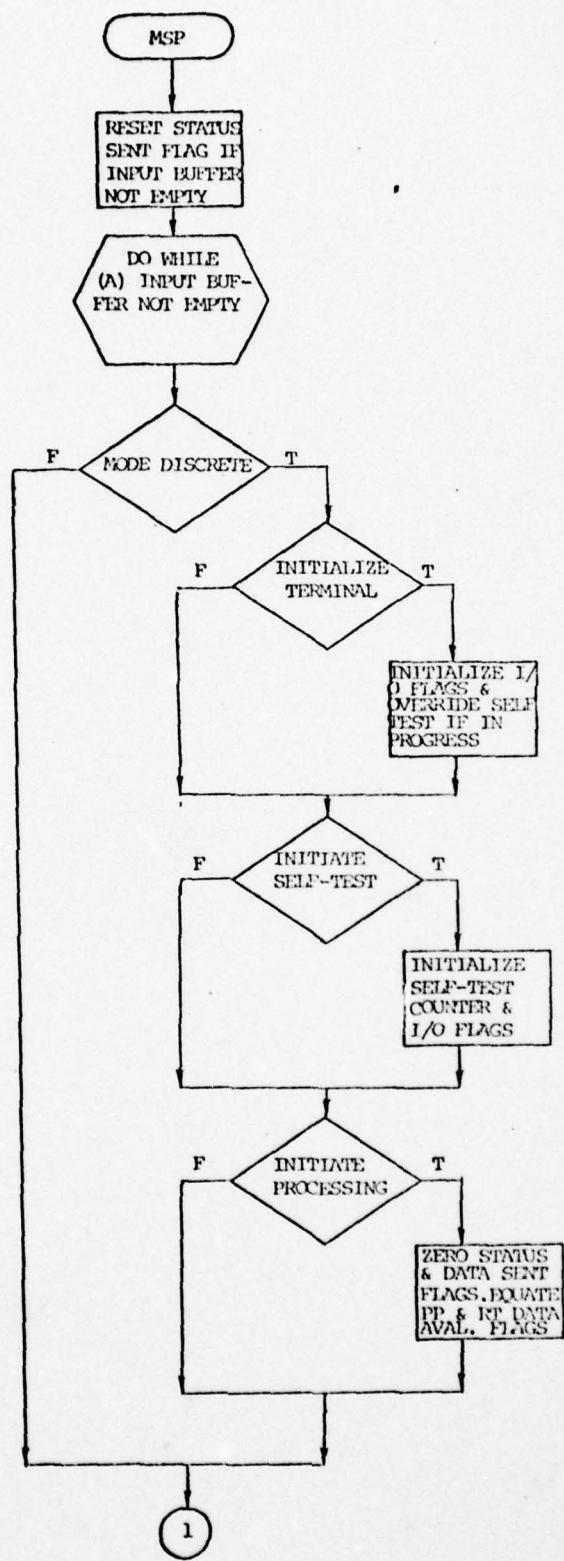
MAD Signal Processor Set to AOP Data Word Formats  
Table D-1

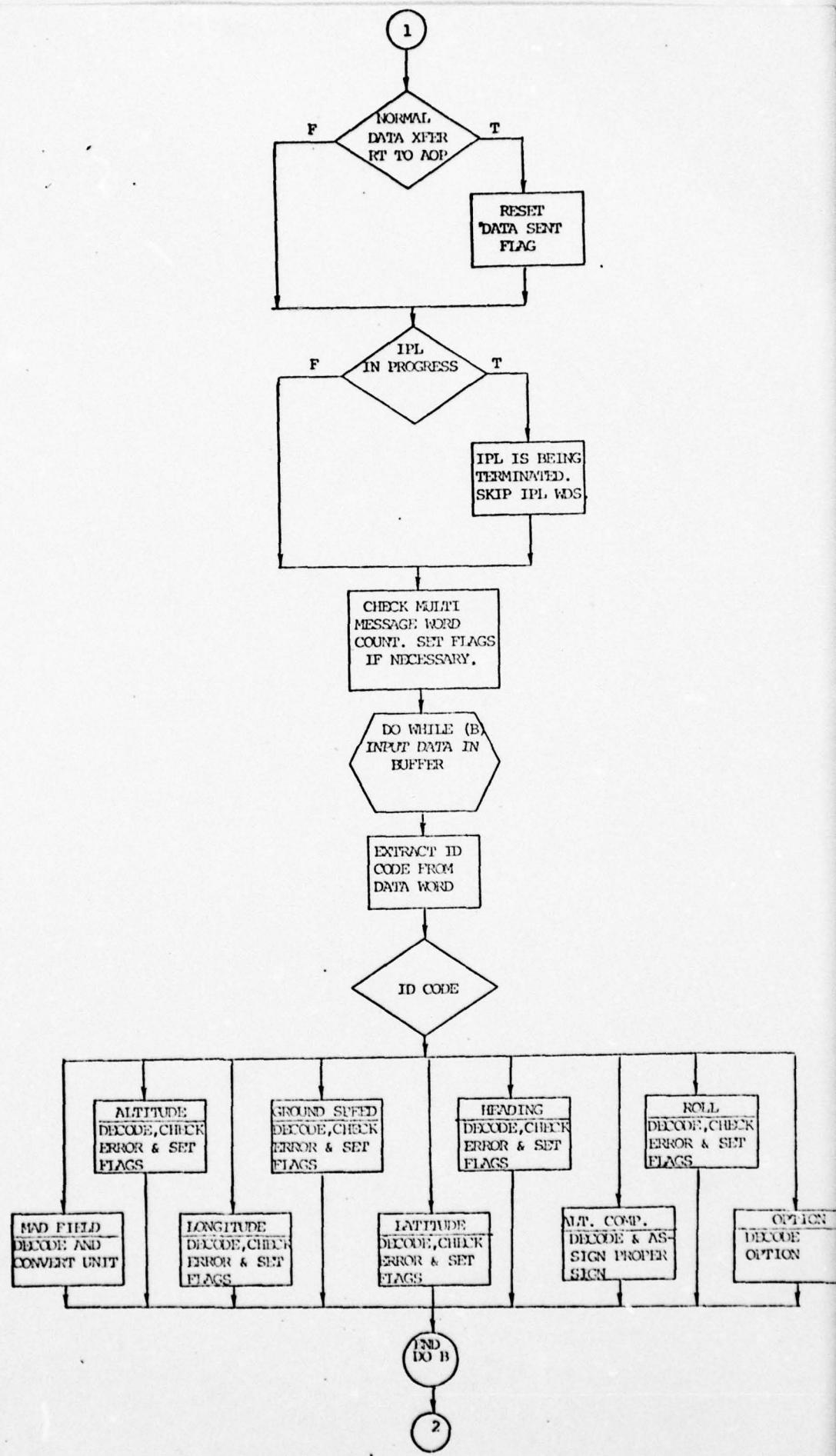
VARIABLE	DESCRIPTION
AMADDET	MAD processor storage array AMADDET (J,9) J = 1, 3 for three possible MAD marks (J,1) = Predetection Flag (J,8) = Predetection Confirmed Flag
IEVENT	Flag that predetection event is active
GRPLAT	Grid reference point latitude (degrees)
GRLONG	Grid reference point longitude (degrees)

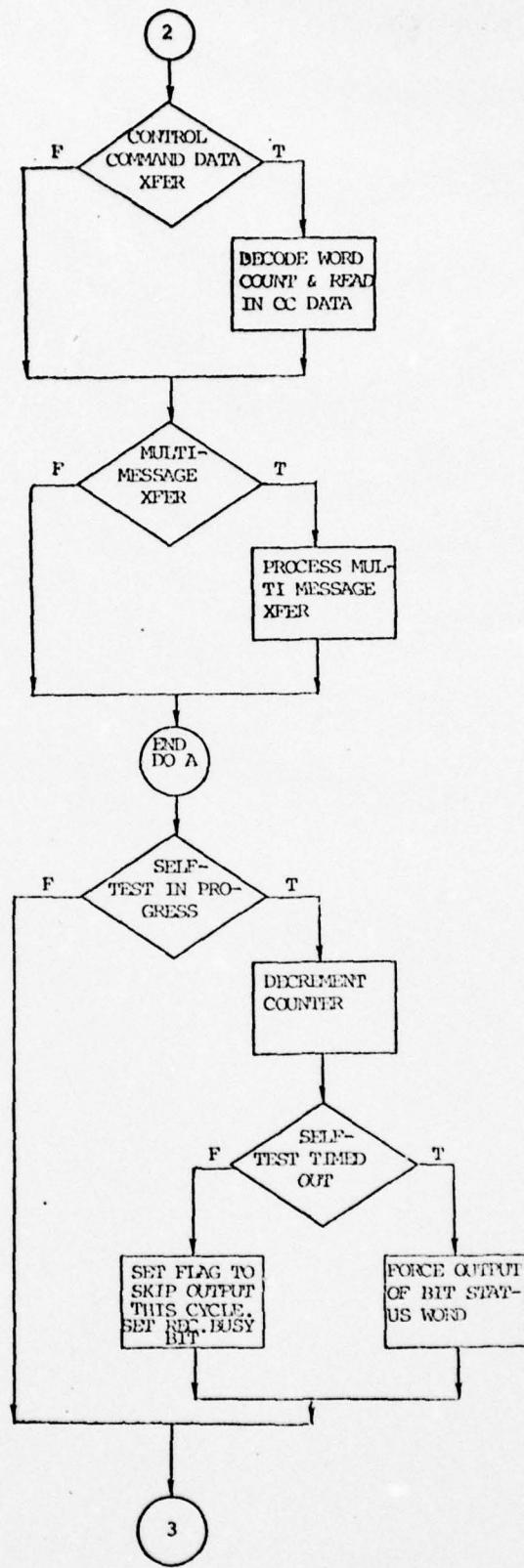
MAD Signal Processor Set/MADMOD Data Formats  
Table D-2

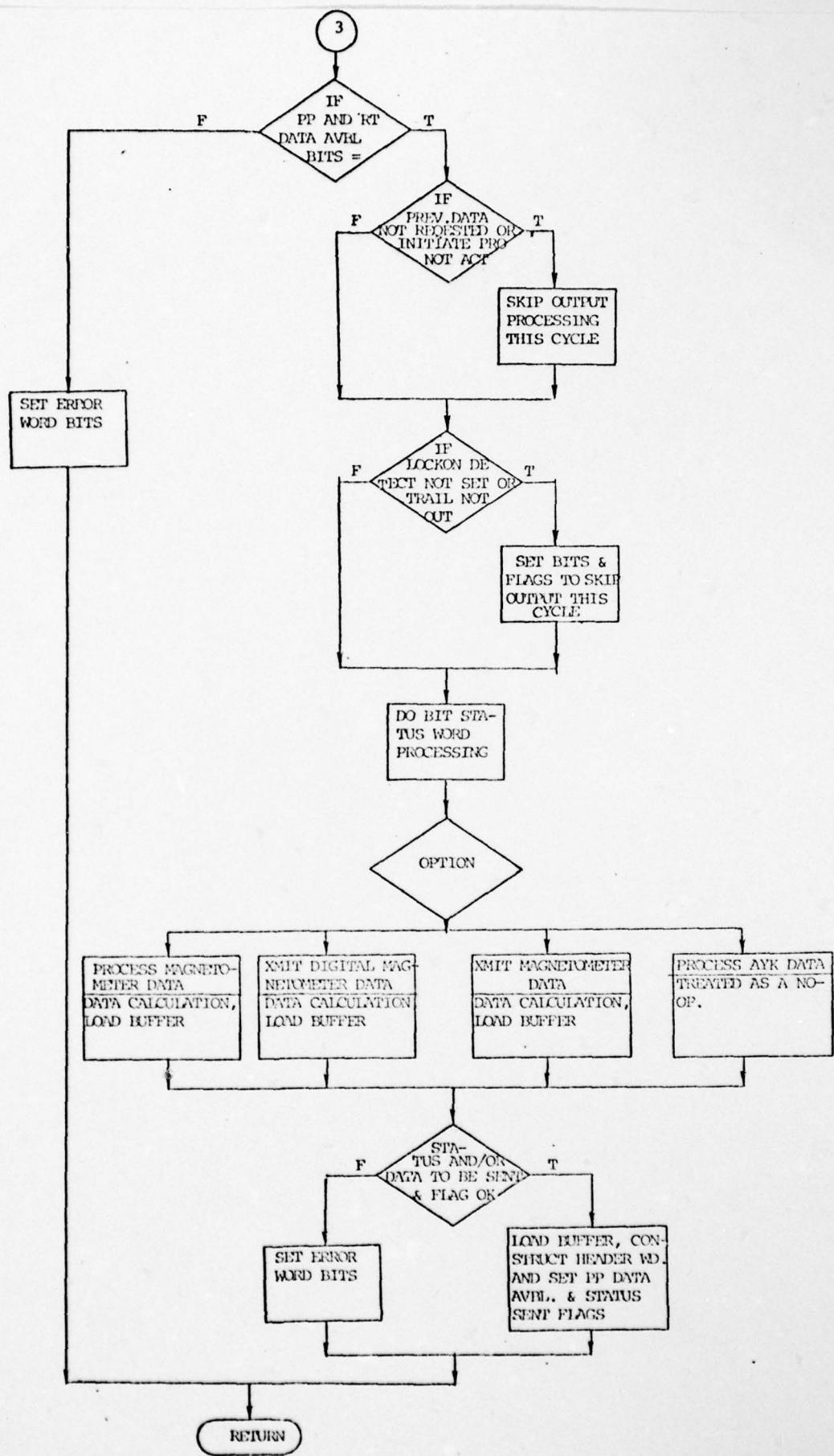
COMMAND	DESCRIPTION
Initialize Terminal	MSP forced into quiescent state, all processing halted (bits 14, 13, 11, 0 set)
Initiate Processing	MSP processing commenced (bits 14, 13, 11, 2, set)
Initiate Self-Test	MSP Built In Test (BIT) forced (bits 14, 13, 11, 1, 0 set)
Normal Data Transfer	
AOP to MSP	MSP to process new data from the AOP (bits 14, 13, 11, 5)
MSP to AOP	MSP to send new data to AOP (bits 14, 13, 11, 10, 5 set)
Multi-Message Transfer	MSP to process new data (bits 14, 13, 11, 7, 6 set)

AOP to MAD Signal Processor Set Command Words  
Table D-3









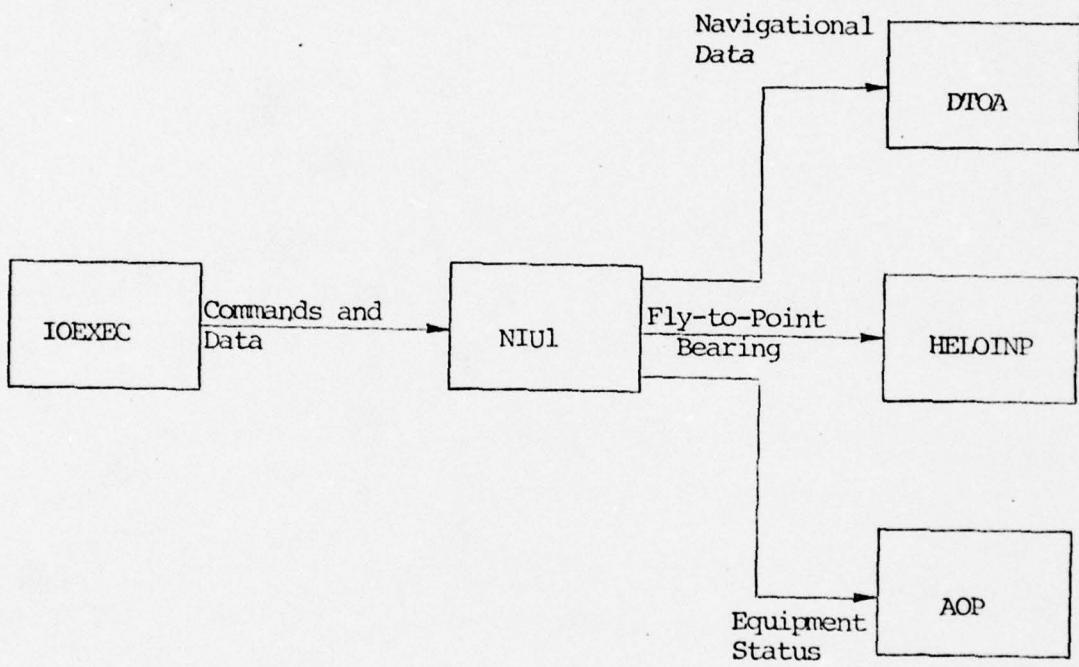
APPENDIX E  
NAVIGATION INTERFACE UNIT MODULE

The Navigation Interface Unit (NIU) Module performs the simulated control of AOP commands, updating of fly-to-point bearings and transfer of AOP navigation data to the DTOA module. The module consists of the following routine:

- NIU1 - The routine scans the input buffer from the AOP for command words (Normal Data Transfer, Initialize Terminal, Initiate Processing, or Initiate Self-Test). When a normal Data Transfer (AOP sending data) is received, the navigational data (tactical range and bearing, drift angle and heading) are transferred to DTOA and the fly-to-point bearing is decoded for the Helo routines. The other commands, internal operation states and output of status and data to the AOP are processed as described in Section 3.

The NIU module performs a subset of the functional requirements of the NIU hardware is:

- The Master Clear function is not implemented.
- The manual "self-test" is not implemented.



NIU Inputs and Outputs to and from the AOP and Other Modules  
Figure E-1

WORD	DESCRIPTION
Equipment Status Word 1	Bit 13 - PLT Selected
Equipment Status Word 2	Bit 15 - Pilot TACAN Selected Bit 14 - Pilot Computer Selected Bit 12 - ATO TACAN Selected Bit 11 - ATO Computer Selected

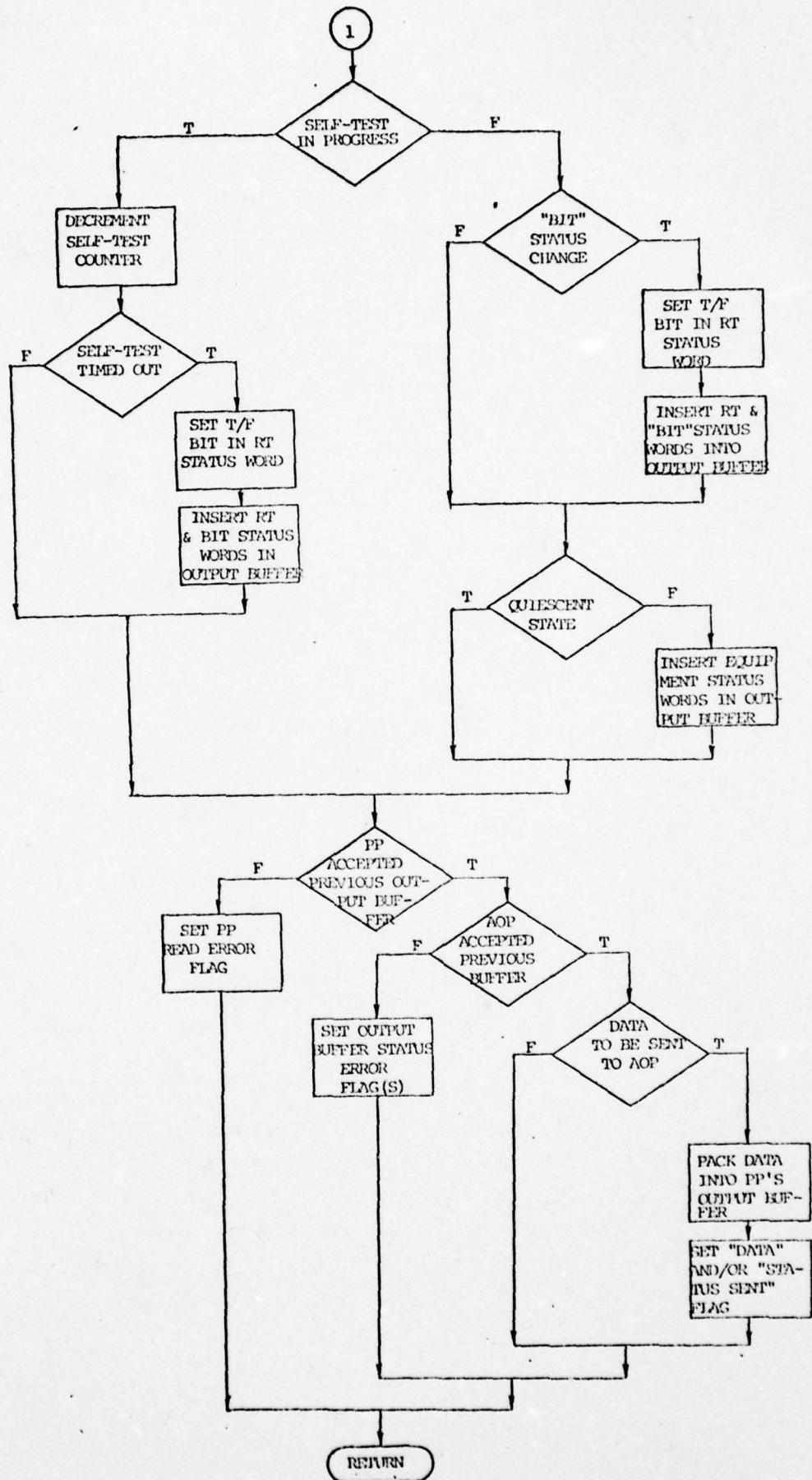
Navigational Interface Unit to AOP Status Formats  
Table E-1

WORD	DESCRIPTION
FTP Tactical Range	Bits 15 - 1 Tactical Range, unsigned Bit 0 Range Flag
FTP Tactical Bearing	Bits 15 - 1 Tactical Bearing, unsigned Bit 0 Navigation Flag
Drift Angle	Bits 15 - 1 Drift Angle, unsigned
Pilot's True Heading	Bits 15 - 1 Heading, unsigned
ATO's True Heading	Bits 15 - 1 Heading, unsigned

IOEXEC to Navigation Interface Unit Data Formats  
Table E-2

COMMAND	DESCRIPTION
Mode/Discrete Data <ul style="list-style-type: none"> <li data-bbox="376 435 719 466">• Initialize Terminal</li> <li data-bbox="376 519 703 551">• Initiate Self-Test</li> <li data-bbox="376 604 719 635">• Initiate Processing</li> </ul>	Module placed in quiescent state (bits 14, 13, 12, 0 set)  Module placed in self-test state (bits 14, 13, 12, 1, 0 set)  Modules internal processing commenced (bits 14, 13, 12, 2 set)
Normal Data Transfer <ul style="list-style-type: none"> <li data-bbox="376 751 719 783">• AOP to NIU Transfer</li> <li data-bbox="376 846 719 878">• NIU to AOP Transfer</li> </ul>	Module to receive AOP data (bits 14, 13, 12, 5, 1 set)  Module to transfer data to AOP (bits 14, 13, 12, 5, 2, 1 set)

AOP to NIU Commands  
Table E-3



APPENDIX F  
ORDNANCE LAUNCH CONTROL SET MODULE

The Ordnance Launch Control Set (OLCS) software module provides for simulated sonobuoy and torpedo select and launch commands via a software command from the AOP and manual keyset inputs. In addition to the normal sonobuoy processing, OLCS provides the rest of the simulator with splash point and water entry time calculations upon the launch of a sonobuoy or torpedo.

The module consists of ten routines which are:

- OLCS - This is the main routine which directs and controls all functions performed in the OLCS module. It scans the input buffer from the AOP for command words (Normal Data Transfer, Control Command Data Transfer, Initialize Terminal, Initiate Processing, or Initiate Self-test), sets the appropriate operational states of the module, and sets an error flag should an invalid command word appear in the input stream. Self-test processing is then handled as described in section 3. The OLCS routine, through the use of several additional subroutines (subroutines UDOASP, UDOH, SPLASH, WET, TSPLASH, and TWET) handles those functions which are unique to the OLCS module. These are described below. Finally, the routine handles output processing as described in section 3.
- UDOASP - Subroutine UDOASP updates manual keyset inputs (select/launch mode, torpedo and master arm, torpedo and sonobuoy launch, and manual sonobuoy select) from the simulated Ordnance Arm and Select Panel, resets data word bits for transmission to the AOP, and sets flags to indicate the necessity of a splash point or water entry time calculation.

- UDOH - Subroutine UDOH contains a counter which is initialized when a sonobuoy or torpedo launch occurs. This counter is then decremented on each subsequent OLCS call until reaching a zero value and a torpedo or sonobuoy away signal is generated for the AOP in the form of a bit set in an outgoing data word.
- SPLASH - Subroutine SPLASH makes the splash point calculation for a launched sonobuoy and outputs this information to sonobuoy. The routine also sets an "in water" flag and resets bits in the OLCS data words to indicate a launch.
- WET - This subroutine calculates water entry times for launched sonobuoys for the sonobuoy routine (an existing routine currently in the simulator that performs all sonobuoy simulation).
- CONTROL - In the event of a Control Command Data Transfer, CONTROL extracts the sonobuoy launch information from the CC Data word and processes this data by setting flags, recording the selected chute number and initializing the sonobuoy away signal counter in the event of a sonobuoy auto launch command.
- TSPLASH - Subroutine TSPLASH makes splash point calculations for launched torpedoes for the sonobuoy routine and sets a torpedo active flag.
- TWET - This subroutine makes water entry time calculations for launched torpedoes for the sonobuoy routine.
- SETABIT - Subroutine SETABIT sets a given bit within a specified word to 0 or 1 as requested.
- READBIT - Subroutine READBIT right justifies and returns the value of a bit within a given word.

The OLCS module performs a subset of the functional requirements of the OLCS hardware. The disparity between the hardware and the software is:

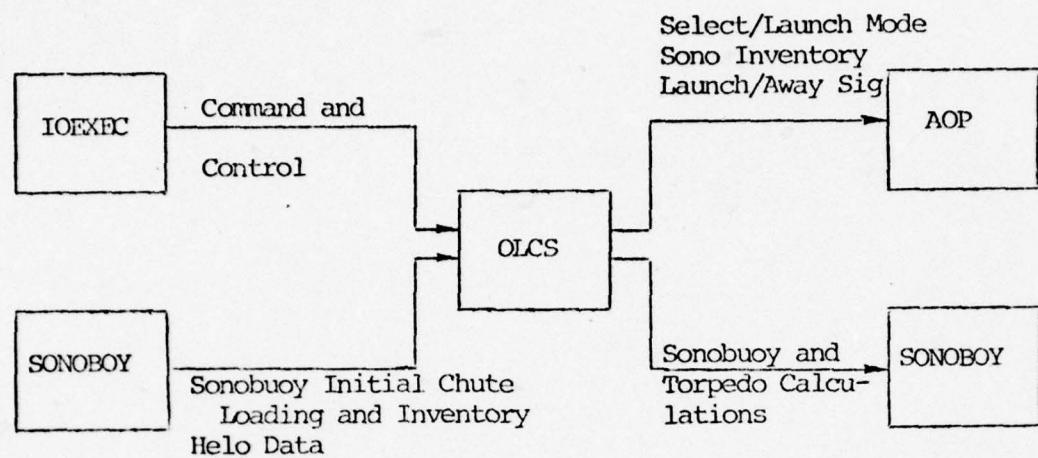
- The Master Clear function is not implemented.
- The manual "self-test" is not implemented.
- Due to simulator hardware limitations only buoys 1-19 can be manual/auto launched. Buoys 20-25 must be auto launched.
- Emergency jettison of sonobuoys is not implemented.
- Weight on wheels interlock is not implemented.
- Due to simulator hardware restrictions, sonobuoy manual/auto - select/launch commands cannot be mixed.
- Provision for left/right, search depth, mode/ceiling, course setting and emergency jettison of torpedoes is not implemented.

DATA WORD	DESCRIPTION
Sonobuoy Inventory Status Word 1	Bit 15 Sono. Auto Select Mode Bit 14 Sono. Auto Launch Mode Bit 13 Sono. Launch Signal Bit 12 Sono. Away Signal Bit 11 Torp. Launch Signal Bit 10 Torp. Away Signal Bits 8 - 0 Sono. Chutes 1 - 9 (loaded or unloaded)
Sonobuoy Inventory Status Word 2	Bits 15 - 0 Sono Chutes 10 to 25 (loaded or unloaded)

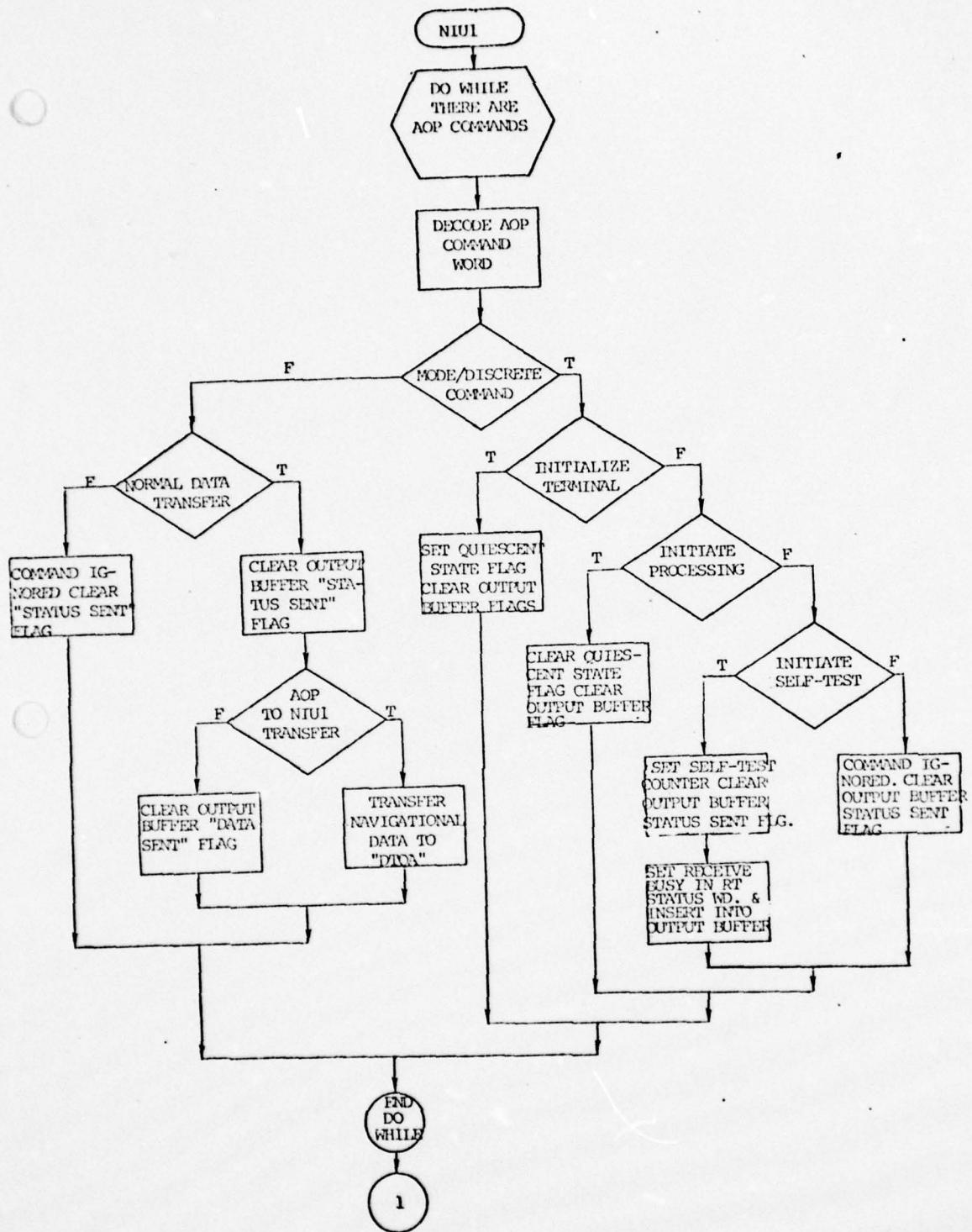
Ordnance Launch Control Set to AOP Data Formats  
Table G-1

DATA WORD	DESCRIPTION
Sonobuoy Inventory Status Word 1	Bit 15 Sono. Auto Select Mode Bit 14 Sono. Auto Launch Mode Bit 13 Sono. Launch Signal Bit 12 Sono. Away Signal Bit 11 Torp. Launch Signal Bit 10 Torp. Away Signal Bits 8 - 0 Sono. Chutes 1 - 9 (loaded or unloaded)
Sonobuoy Inventory Status Word 2	Bits 15 - 0 Sono Chutes 10 to 25 (loaded or unloaded)

Ordnance Launch Control Set to AOP Data Formats  
Table G-1



Inputs and Outputs to and from the AOP and other Modules  
Figure G-1



VARIABLE	DESCRIPTION
HELO(1)	Helo heading in radians
HELO(2)	Cosine of helo heading
HELO(3)	Sine of helo heading
HELO (13)	Helo x-coordinate in feet
HELO (14)	Helo Y-coordinate in feet
HELO (15)	Helo altitude in feet
HELO (21)	Helo air speed in ft/sec.
WIND (1)	Wind direction in angular degrees
WIND (2)	Wind speed in ft/sec.
TIME	Mission time in seconds
BUOYIC (1,J)	Buoy-type initial chute loading (J=1,25)

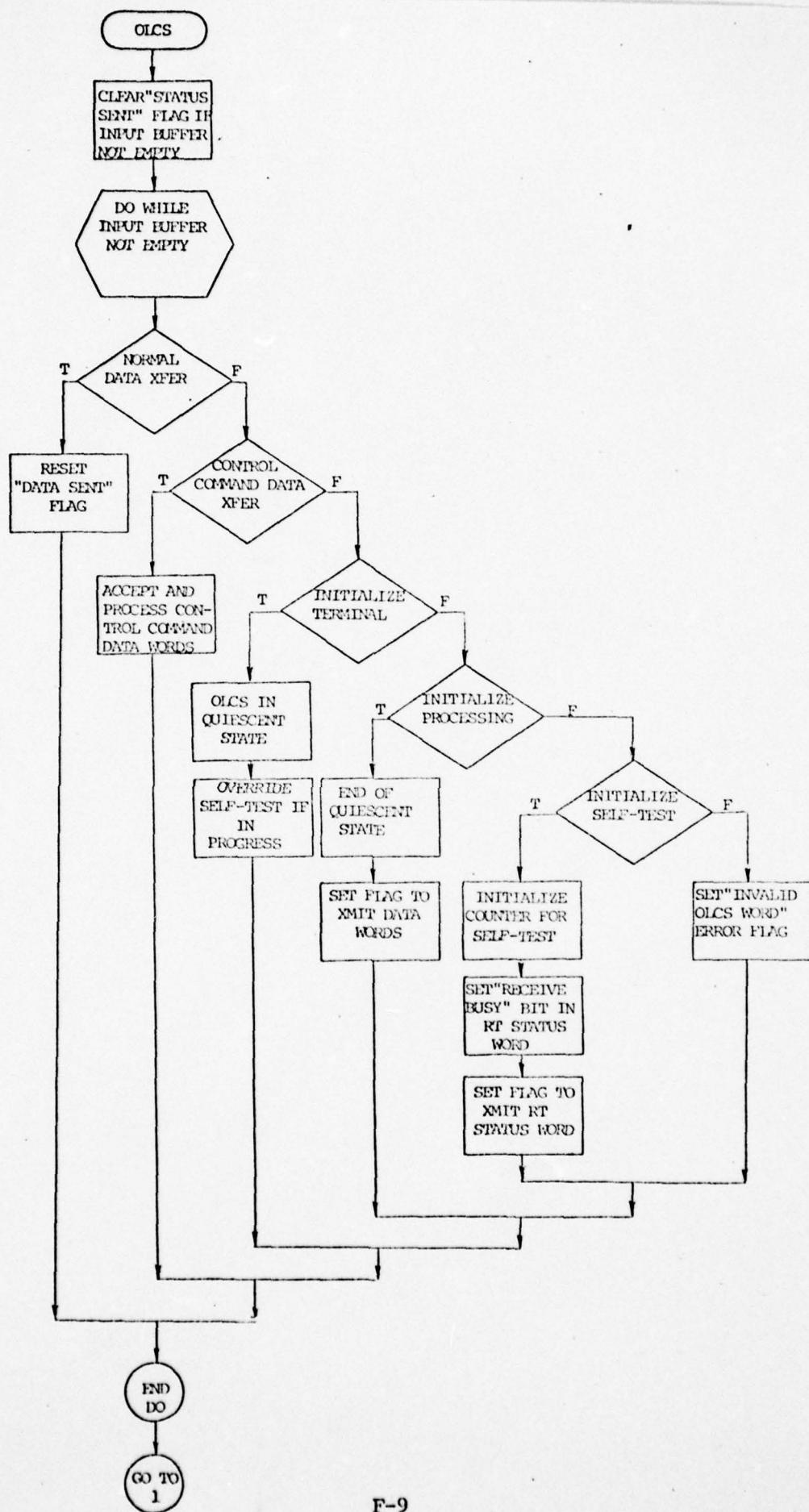
Sonoboy to Ordnance Launch Control Set Formats  
Table G-2

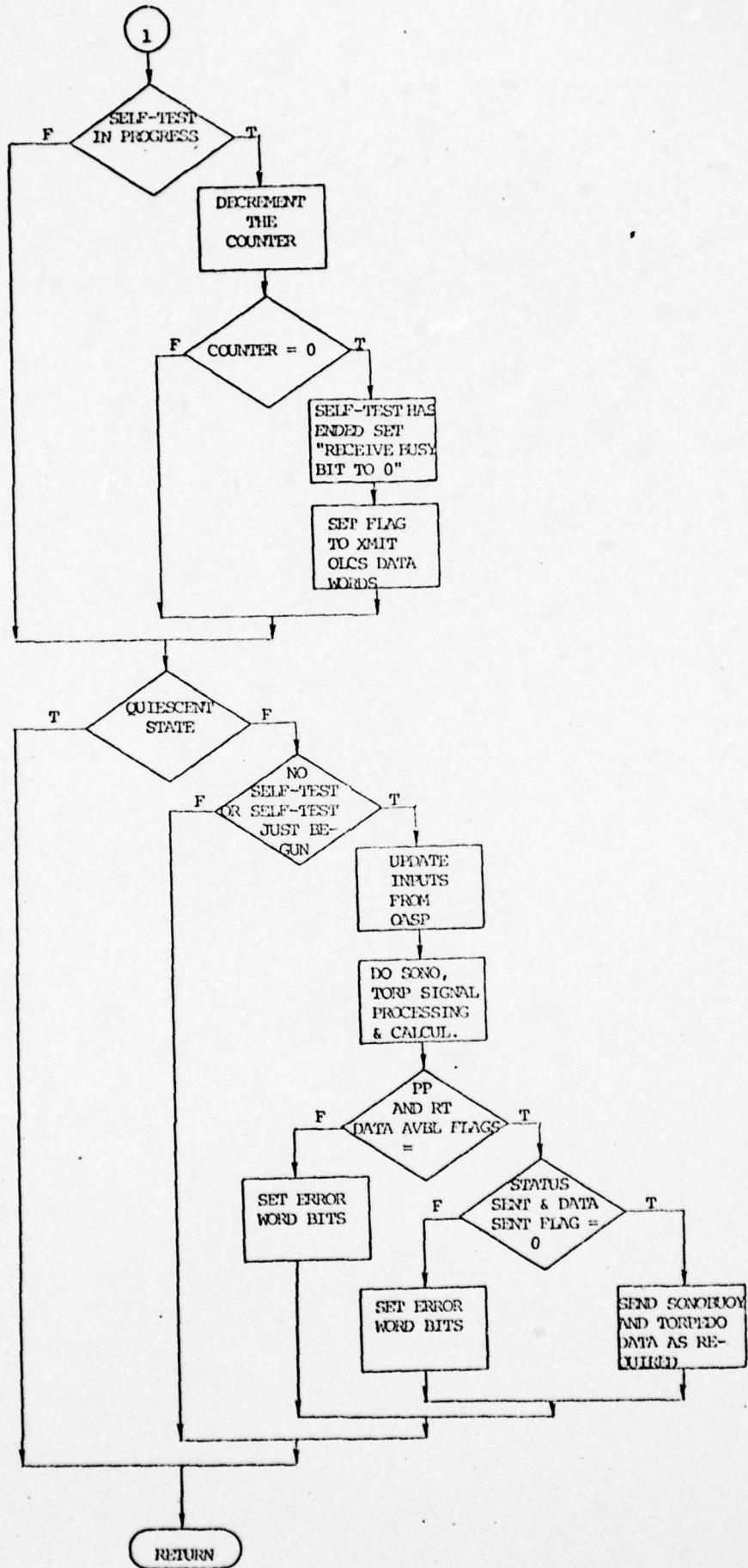
VARIABLE	DESCRIPTION
TOREP (1, I)	Torpedo X position in feet (I = 1,2)
TORPED (2, I)	Torpedo y position in feet (I = 1, 2)
TORPED (3, I)	Water entry time for torpedo (I = 1,2)
BUOYRW (2, I)	Sonobuoy x-coordinate (I = 1, 32)
BUOYRW (3, I)	Sonobuoy y-coordinate (I = 1, 32)
BUOYRW (4, I)	In water flag (I = 1, 32)
BUOYRW (11,I)	Water entry time for sonobuoy (I = 1, 32)
ITORDS	Torpedo symbol active flag

Ordnance Launch Control Set to Sonoboy Formats  
Table G-3

COMMAND	DESCRIPTION
Initialize Terminal	OLCS forced into quiescent state, all processing halted (bits 15, 14, 11, 0 set)
Initiate Processing	OLCS processing commenced (bits 15, 14, 11, 2 set)
Initiate Self-Test	OLCS Built in Test (BIT) forced (bits 15, 14, 11, 1, 0 set).
Normal Data Transfer OLCS to AOP	OLCS to send new data to AOP (bits 15, 14, 11, 5, 1 set)
Control Command Data Transfer	OLCS to process new control command data (bits 15, 14, 11, 7, 5, 0, set).
CCDW1	Bits 11 - 15 auto sono select commands.
CCDW2	Bits 5 - 9 auto launch commands.

Table G-4  
AOP to Ordnance Launch Control Set Command Words (via IOEXEC)



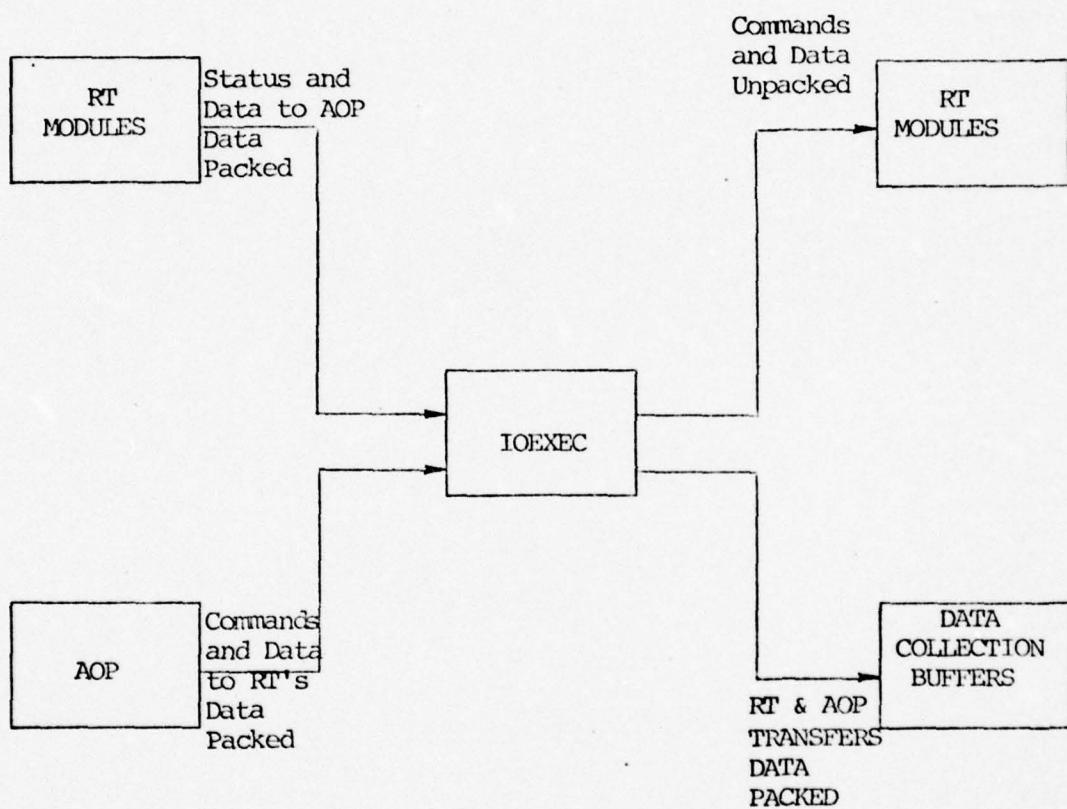


## APPENDIX G

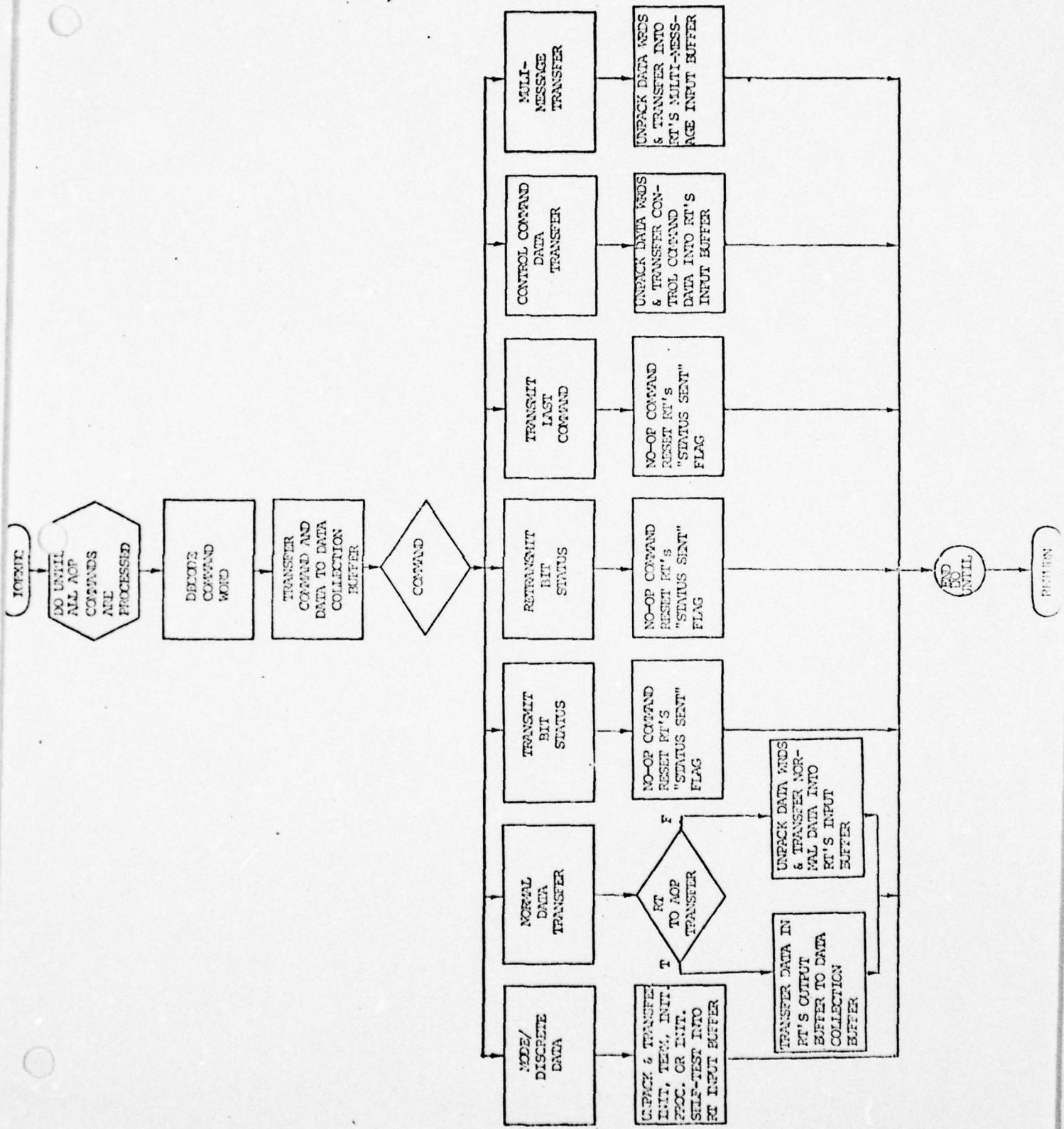
### INPUT/OUTPUT EXECUTIVE AND DATA COLLECTION MODULE

The Input/Output Executive and Data Collection (IOEXEC) module provides for the routing of AOP commands and data to the various RTs, and for the collection of data that passes through the data bus between the AOP and the CDC-6600 simulation. The former takes packed data from the AOP, determines the target RT, unpacks the data and inserts the result in the RT's input buffer. The latter removes the data in the RT's input and output buffers to the AOP and inserts the unpacked data into the data collection buffer which will be transferred to a historical data base for data reduction.

The routine interrogates the input buffer from the AOP to determine the target RT and command, and transfers the associated unpacked data to the data collection buffer. The command word is then used to determine the type of information to be transferred to the RT. The data is then unpacked and transferred to the RT's input buffer. If the command is a data transfer from the RT to the AOP, the data in the RT's output buffer is to the AOP, that data is transferred to the data collection buffer.



Inputs and Outputs Between the AOP and the RT Modules  
Figure G-1



**APPENDIX H**

**PROGRAM PROFILE**

CONVERTER MULTIPLEXER MODULE

(CMUX)

PROGRAM MUXDRIV

PROGRAM MUXDRIV

ABSTRACT  
THIS PROGRAM IS A DRIVER TO TEST THE CMUX MODULE.

CODING HISTORY  
1. PROGRAMMED--ALEX POOLECKI (CSC) 01/12/78

END OF ABSTRACT

PAGE 1

INITIALIZE BUFFERS, FLAGS, ETC.  
ZERO THE MUX INPUT BUFFER  
DO WHILE INPUT BUFFER NOT INITIALIZED  
• INSERT ZERO VALUE  
ENDDO  
ZERO THE ATO.SO DISPLAY BUFFERS  
DO WHILE DISPLAY BUFFER NOT INITIALIZED  
• INSERT ZERO VALUE  
ENDDO  
ZERO THE MUX ALTERNATE INPUT BUFFER  
DO WHILE ALTERNATE BUFFER NOT INITIALIZED  
• INSERT ZERO VALUE  
ENDDO  
ZERO THE DATA TRANSFER HOLDING BUFFER  
DO UNTIL HOLDING BUFFER EXHAUSTED  
• INSERT ZERO WORD  
ENDDO  
NO INITIAL FAULTS  
ZERO MAD, ACOUSTICS DISPLAY WORDS  
ALTITUDE = 512 FEET  
DUMMY UP PITCH/ROLL SINE/COSINE  
GAMMAS = 511  
TACAN RANGE = 5.13 NMI  
INDICATED AIRSPEED = 37.5 KNOTS  
VALID BEARING = 225 DEGREES  
ATO STICK VOLTAGES - X=4.992, Y=2.496  
SO STICK VOLTAGES - X=1.248, Y=0.624  
ZERO DATA AVAILABLE WORDS  
ALLOW PRINTING INFORMATIVE MESSAGES  
RESPONSE TO NO COMMANDS  
SELF-TEST SEQUENCE  
1. INITIATE SELF-TEST MODE/DISCRETE  
2. IDLE PERIOD  
DO WHILE CMUX SAYS ITS BUSY  
• EXECUTE CMUX  
ENDDO  
3. TRANSMIT \*BIT\* STATUS COMMAND  
INITIALIZATION SEQUENCE  
-INITIALIZE TERMINAL MODE/DISCRETE  
-TRANSMIT BIT STATUS COMMAND  
-INITIATE PROCESSING MODE/DISCRETE  
REQUEST FOR DATA  
1. NULL INPUT  
2. NORMAL DATA TRANSFER WITH T/R = 1  
3. NULL INPUT  
DATA TRANSFER < 32 WORDS  
1. DATA TRANSFER COMMAND WITH COUNT = 15  
• HEADER WORD 1 - IPL WITH COUNT = 15  
• HEADER WORD 2 - ADDRESS = 1  
DO WHILE IPL WORDS REQUIRED  
• INSERT DUMMY IPL WORD = POSITION IN BUFFER  
ENDDO  
2. NULL INPUT 4 TIMES  
DATA TRANSFER > 32 WORDS  
1. MULTI-MESSAGE COMMAND  
• HEADER WORD 1 - DISPLAY DATA WITH COUNT = 42

```
* HEADER WORD 2 - ACOUSTICS DATA WITH COUNT = 1
* HEADER WORD 3 - LOFAP, DIFAR ALI DATA IN ZONE 1
* HEADER WORD 2 - ACOUSTICS DATA WITH COUNT = 1
* HEADER WORD 3 - DEMON ALI DATA IN ZONE 2
* HEADER WORD 2 - ACOUSTICS DATA WITH COUNT = 1
* HEADER WORD 3 - RANGE DOPPLER DATA IN ZONE 4
* HEADER WORD 2 - MAD DATA WITH COUNT = 1
* HEADER WORD 3 - FULL SCALE
* HEADER WORD 2 - ATO DISPLAY DATA WITH COUNT = 16
* HEADER WORD 3 - ADDRESS = 2001B
DOWHILE ATO DATA REQUIRED
    * INSERT DUMMY DATA = POSITION WITHIN BLOCK
ENDDO
* HEADER WORD 2 - SO DISPLAY DATA WITH COUNT = 13
* HEADER WORD 3 - ADDRESS = 3001B
    * DUMMY SO DATA TO PAD OUT MULTI-MESSAGE BLOCK
        2. TRANSMIT STATUS WORD
        3. NORMAL DATA TRANSFER OF 10 WORDS
DOWHILE SO DATA REQUIRED
    * INSERT DUMMY DATA = POSITION IN TRANSFER
ENDDO
```

**SUBROUTINE XCMUX****ABSTRACT**

THIS ROUTINE MONITORS EXECUTION OF THE CMUX MODULES FOR THE CMUX DRIVER.

1. IT PRINTS CONTENTS OF CURRENT INPUT BUFFER
2. IT PRINTS CHANGES WITHIN ALTERNATE INPUT BUFFER
3. IT EXECUTES THE CMUX1 MODULE
4. IT PRINTS CHANGES TO THE DATA TRANSFER HOLDING BUFFER
5. EVERY 5TH CYCLE, IT EXECUTES CNUX2
6. IT PRINTS THE CONTENTS OF THE RESULTANT OUTPUT BUFFER AND RESETS THE PP BIT TO SIGNIFY ACCEPTANCE
7. IT PRINTS CHANGES TO THE ATO/SO BUFFERS
8. IT PRINTS MAC, ACOUSTICS FLAGS/DATA

**CODING HISTORY**

1. PROGRAMMED--ALEX PODLECKI (CSC) 01/16/78

**END OF ABSTRACT**

```
PRINT INPUT BUFFER
DO WHILE SOMETHING IN INPUT BUFFER
    • EXPAND INPUT WORD
    • PRINT INPUT WORD BIT-BY-BIT
ENDDO
IF EMPTY INPUT BUFFER AND MESSAGES REQUESTED
    • THEN
        • PRINT INFORMATIVE MESSAGE
    • ELSE
        • OMIT MESSAGE
ENDIF
DO UNTIL ALTERNATE BUFFER EXHAUSTED
    • IF THE ALTERNATE BUFFER HAS CHANGED
    • • THEN
        • • IF THIS IS THE INITIAL CHANGE
        • • • THEN
            • • • • PRINT HEADINGS FOR NEW VALUES
        • • • ELSE
            • • • • OMIT HEADING MESSAGE
        • • • ENDIF
        • • • • PRINT POSITION AND NEW VALUE
        • • • • SAVE NEW VALUE
    • • ELSE
        • • • OMIT PRINTING
    • • ENDIF
ENDDO
SET UP DUMMY HEADING SIN/COS
EXECUTE THE CMUX1 MODULE
DO UNTIL HOLDING BUFFER EXHAUSTED
    • IF THE HOLDING BUFFER HAS CHANGED
    • • THEN
        • • • IF THIS IS THE INITIAL CHANGE
        • • • • THEN
            • • • • • PRINT HEADINGS FOR NEW VALUES
        • • • • ELSE
            • • • • • OMIT MESSAGE
        • • • • ENDIF
        • • • • • PRINT POSITION AND NEW VALUE
        • • • • • SAVE NEW VALUE
    • • ELSE
        • • • OMIT PRINTING
    • • ENDIF
ENDDO
IF 5TH CYCLE
    • THEN
        • EXECUTE THE CMUX2 MODULE
        • • IF SOMETHING IN OUTPUT BUFFER
        • • • THEN
            • • • • PRINT HEADER WORD
            • • • • COMPILE SOMETHING IN OUTPUT BUFFER
            • • • • • EXPAND OUTPUT WORD
            • • • • • IF THIS WORD IS A BIT STATUS WORD
            • • • • • THEN
                • • • • • • INDICATE BY *
            • • • • ELSE
                • • • • • INDICATE BY BLANK
```

```
      * PRINT OUTPUT WORD BIT-BY-BIT
      * VARIOUS THE PP DATA AVAILABLE BY
      * IF MESSAGES REQUESTED
      *   THEN
      *     * PRINT INFORMATIVE MESSAGE
      *   ELSE
      *     * OMIT INFORMATIVE MESSAGE
      *   ENDIF

      * COUNT UNTIL AT&T/SO BUFFERS EXHAUSTED
      * IF EITHER AT&T OR SO BUFFER HAS CHANGED
      *   THEN
      *     * IF THIS IS THE INITIAL CHANGE
      *       * THEN
      *         * PRINT HEADINGS
      *       * ELSE
      *         * OMIT HEADINGS
      *     * ENDIF
      *     * PRINT POSITION AND CURRENT VALUES
      *     * SAVE CURRENT VALUES
      *   ELSE
      *     * OMIT PRINTING
      *   ENDIF
      * ENDDO
      * IF MAD DATA AVAILABLE
      *   THEN
      *     * PRINT MAD SCALE FACTOR, DISPLAY ZONE
      *   ELSE
      *     * OMIT PRINTING
      *   ENDIF
      * DOFOR EACH DISPLAY ZONE
      *   * IF ACOUSTICS DATA PRESENT
      *     * THEN
      *       * PRINT ZONE AND TYPE
      *     * ELSE
      *       * OMIT PRINTING
      *     * ENDIF
      *   ENDDO
      * ELSE
      *   * DO NOT EXECUTE THE CMUX2 MODULE
      * ENDIF
```

SUBROUTINE ADVANCE (POINTER,LWA)

ABSTRACT

THIS ROUTINE INCREMENTS A POINTER BY 1. IF THE POINTER WAS  
ALREADY SET TO AN LWA, THE POINTER IS RESET TO 1.

POINTER - CURRENT VALUE OF POINTER

LWA - LAST WORD ADDRESS FOR POINTER

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

11/04/77

END OF ABSTRACT

IF POINTER IS LESS THAN LWA  
THEN  
  • INCREMENT POINTER  
  • ELSE  
  • SET POINTER TO FWA  
ENDIF

SUBROUTINE EXPAND

SUBROUTINE EXPAND(N,IN,OUT)

ABSTRACT

THIS ROUTINE EXPANDS A WORD INTO AN N WORD ARRAY SUCH THAT  
WORD 1 CONTAINS BIT N-1, WORD 2 CONTAINS BIT N-2, \*\*\*,  
AND WORD N CONTAINS BIT 0 ( RIGHT JUSTIFIED WITH ZERO FILL )

N - NUMBER OF BITS TO BE EXPANDED

IN - INPUT WORD TO BE EXPANDED

OUT - OUTPUT ARRAY TO RECEIVE EXPANSION

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

11/07/77

END OF ABSTRACT

SUBROUTINE EXPAND

DO WHILE ANOTHER BIT TO BE EXPANDED  
    • • MASK OUT DESIRED BIT  
    • • SET UP FOR NEXT BIT  
ENDDO

PAGE 2

SUBROUTINE PACKPP( NRT, N )  
ABSTRACT  
THIS ROUTINE IS A DUMMY SUBSTITUTE FOR THE ACTUAL PACKPP.

NRT - NUMBER CORRESPONDING TO RT

N - NUMBER OF WORDS TO BE \*PACKED\*

CODING HISTORY  
1. PROGRAMMED--ALEX PODLECKI      11/07/77

END OF ABSTRACT

SUBROUTINE PACKPF

EXIT

PAGE 2

SUBROUTINE CMUX1

ABSTRACT

THIS PROGRAM PROCESSES ALL AYK COMMANDS TO THE CMUX,  
BUILDS A HOLDING BUFFER FOR ALL DATA TRANSFERS,  
CALLS CMUXCUT TO UPDATE DISPLAY BUFFERS, TABLES AND FLAGS  
AND SAVES 4 SETS OF HELO HEADING SINE AND COSINE.

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI 12/28/77

END OF ABSTRACT

```
MAIN LOOP FOR INPUT PROCESSING
  IF SOMETHING IN THE INPUT BUFFER
    . THEN
      • RESET STATUS SENT FLAG
    . ELSE
      ENDIF
      DOWHILE SOMETHING IN INPUT BUFFER
        CRACK COMMAND INTO BASIC FIELDS
        • CASE OF AOP COMMAND WORD (COMMAND)
          • • *COMMAND EQ. 0
          • • CASE OF MOVE/DISCRETE COMMAND (DATAWC)
            • • • *DATAWC EQ. 1
              INITIALIZE TERMINAL
              RESET SELF-TEST COUNTER/FLAG
            • • • *DATAWC EQ. 3
              INITIALIZE SELF-TEST
              SET SELF-TEST COUNTER TO MAXIMUM
            • • • *DATAWC EQ. 4
              INITIATE PROCESSING
              SET PROCESSING INITIATED AND DATA REQUESTED FLAGS
            • • END CASE
            • • *COMMAND EQ. 6
              MULTI-MESSAGE TRANSFER
              • DOWHILE ANOTHER WORD IN ALTERNATE CMUX BUFFER
                • TRANSFER WORD TO MULTI-MESSAGE HOLD BUFFER
                ENDDO
            • ELSE
              • • *COMMAND EQ. 1
                NORMAL DATA TRANSFER
                • IF ANY IS REQUESTING DATA
                  THEN
                    SET DATA REQUESTED FLAG
                  ELSE
                    • IF DATA WORD COUNT FIELD IS ALL ZEROS
                      • THEN
                        • • CHANGE WORD COUNT TO 32
                        • ELSE
                          ENDIF
                          DOWHILE ANOTHER DATA WORD IS AVAILABLE
                            • TRANSFER INPUT WORD TO HOLD BUFFER
                            • ZERO INPUT BUFFER
                          ENDDO
                          PROCESS THE COMPLETED DATA TRANSFER
                          • ZERC THE HOLDING BUFFER FOR COMPLETE DATA TRANSFERS
                        • ENDIF
                      • END CASE
                    • ENDIF
                  ENDDO
                  SAVE 4 SETS OF HEADING SIN/COS
                END OF PROGRAM
```

SUBROUTINE CMUXC01

SUBROUTINE CMUXC01

ABSTRACT  
THIS ROUTINE PROCESSES COMPLETED DATA TRANSFERS FROM THE AYK  
TO THE CMUX. MAD AND ACOUSTICS FLAGS AND ATO/SO DISPLAY  
BUFFERS ARE UPDATED.

CODING HISTORY  
1. PROGRAMMED--ALEX PODLECKI (CSC) 12/30/77

END OF ABSTRACT

TE PROSECUTOR INITIATED OR SELF-TESTED FOR SUSPICION

```

    • THEN
      • SET EXIT FLAG
    • ELSE
      • CONTINUE PROCESSING
    • ENDIF
      • EXTRACT BUFFER COUNT FROM HEADER WORD 1
      • IF BUFFER COUNT IN ERROR
        • THEN
          • SET BUFFER COUNT ERROR FLAG
        • ELSE
          • SET EXIT FLAG
        • ENDIF
          • CONTINUE PROCESSING HEADER WORD 1
          • IF IPL DATA IS BEING RECEIVED
            • THEN
              • IF UNREASONABLE BUFFER ADDRESS
                • THEN
                  • SET HEADER WORD ERROR FLAG
                • ELSE
                  • SET IPL OCCURRED FLAG
                • ENDIF
                  • SET EXIT FLAG
            • ELSE
              • CONTINUE ONTO NEXT HEADER WORD
            • ENDIF
              • IF EXIT FLAG NOT SET
                • THEN
                  • DOWHILE DATA BLOCK IS IN BUFFER AND NO ERRORS
                    • • HEADER WORD 2 PROCESSING
                    • • EXTRACT BLOCK COUNT
                    • • IF THIS NEXT BLOCK IS WITHIN THE HOLDING BUFFER
                      • • THEN
                        • • CASE OF DISPLAY DATA (IITYPE)
                          • • • • * IITYPE EQ. 8
                            • • • • DISPLAY DATA BIT CODE IS 1000
                            • • • • ACOUSTICS DISPLAY DATA
                            • • • • SAVE ACOUSTICS DATA TYPE AND DISPLAY ZONE
                            • • • • CONTENTS
                            • • • • HEADER WORD 3 BREAKDOWN
                          • ELSE
                            • • * IITYPE EQ. 1
                              • • DISPLAY DATA BIT CODE IS 0001
                              • • MAD DISPLAY DATA
                              • • SET MAD DATA FLAG
                              • • SAVE RE-SCALE FACTOR
                            • * IITYPE EQ. 4
                              • • DISPLAY DATA BIT CODE 0100
                              • • AUTO DISPLAY DATA
                              • • EXTRACT AUTO BUFFER ADDRESS
                              • • IF UNREASONABLE ADDRESS
                                • • THEN
                                  • • • SET HEADER WORD ERROR FLAG
                                • • ELSE
                                  • • • SET EXIT FLAG
                            • • DOWHILE AUTO DATA REMAINS IN THIS BLOCK
                          • ELSE
                            • • • SET EXIT FLAG
                        • ELSE
                          • • • SET EXIT FLAG
                      • ELSE
                        • • • SET EXIT FLAG
                    • ELSE
                      • • • SET EXIT FLAG
                  • ELSE
                    • • • SET EXIT FLAG
                • ELSE
                  • • • SET EXIT FLAG
              • ELSE
                • • • SET EXIT FLAG
            • ELSE
              • • • SET EXIT FLAG
          • ELSE
            • • • SET EXIT FLAG
        • ELSE
          • • • SET EXIT FLAG
      • ELSE
        • • • SET EXIT FLAG
    • ELSE
      • • • SET EXIT FLAG
  • ELSE
    • • • SET EXIT FLAG

```



SUBROUTINE CHUX2

SUBROUTINE CHUX2

ABSTRACT

THIS ROUTINE PERFORMS CHUX OUTPUT PROCESSING

CODING HISTORY

1. PROGRAMMED--ALEX POLECKI (CSC) 11/04/78

END OF ABSTRACT

PAGE 1

```
IF SELF-TEST IS IN PROGRESS
  THEN
    * DECREMENT SELF-TEST COUNTER
    * IF SELF-TEST HAS NOT TIMED OUT
    *   *SELF-TEST TIMED OUT, SETUP OUTPUT OF
    *     RT AND BIT STATUS WORDS
    *   ELSE
    *     *SELF-TEST NOT TIMED OUT
    ENDIF
  ELSE
    * CONTINUE PROCESSING
    * IF BUFFER COUNT ERROR HAS OCCURRED
    *   THEN
    *     *SET BIT 12 OF FIRST RT STATUS WORD
    *   ELSE
    *     *LEAVE RT STATUS WORD ALONE
    *   ENDIF
    * IF HEADER WORD ERROR
    *   THEN
    *     *SET BIT 12 IN SECOND RT STATUS WORD
    *   ELSE
    *     *LEAVE RT STATUS WORD ALONE
    *   ENDIF
    * IF POWER OFF/ON TRANSIENT HAS OCCURRED
    *   THEN
    *     *SET FLAGS TO PROCESSING HALTED
    *   ELSE
    *     *ENDIF
    *     *IF BIT STATUS HAS CHANGED
    *     *THEN
    *       *PLACE NEW FAULTS INTO OUTPUT BUFFER
    *     *ELSE
    *       *OMIT RT STATUS WORDS FROM OUTPUT
    *     ENDIF
    *     SET UP RT STATUS WORD
    *     IF ANY OF THE MESSAGE ERROR BITS ARE ON
    *       THEN
    *         *SET BIT 10 OF RT STATUS WORD
    *       ELSE
    *         *LEAVE RT STATUS WORD ALONE
    *       ENDIF
    *     IF ANY OF THE *BIT* TEMP-HIGH BITS ARE ON
    *       THEN
    *         *SET BIT 6 OF THE RT STATUS WORD
    *       ELSE
    *         *LEAVE RT STATUS WORD ALONE
    *       ENDIF
    *     IF ANY OF THE OTHER ERROR BITS ARE ON
    *       THEN
    *         *SET BIT 0 OF RT STATUS WORD
    *       ELSE
    *         *LEAVE RT STATUS WORD ALONE
    *       ENDIF
    *     IF DATA REQUESTED, PROCESSING STARTED, IPL OCCURRED
    *       AND NOT SELF-TESTING
```

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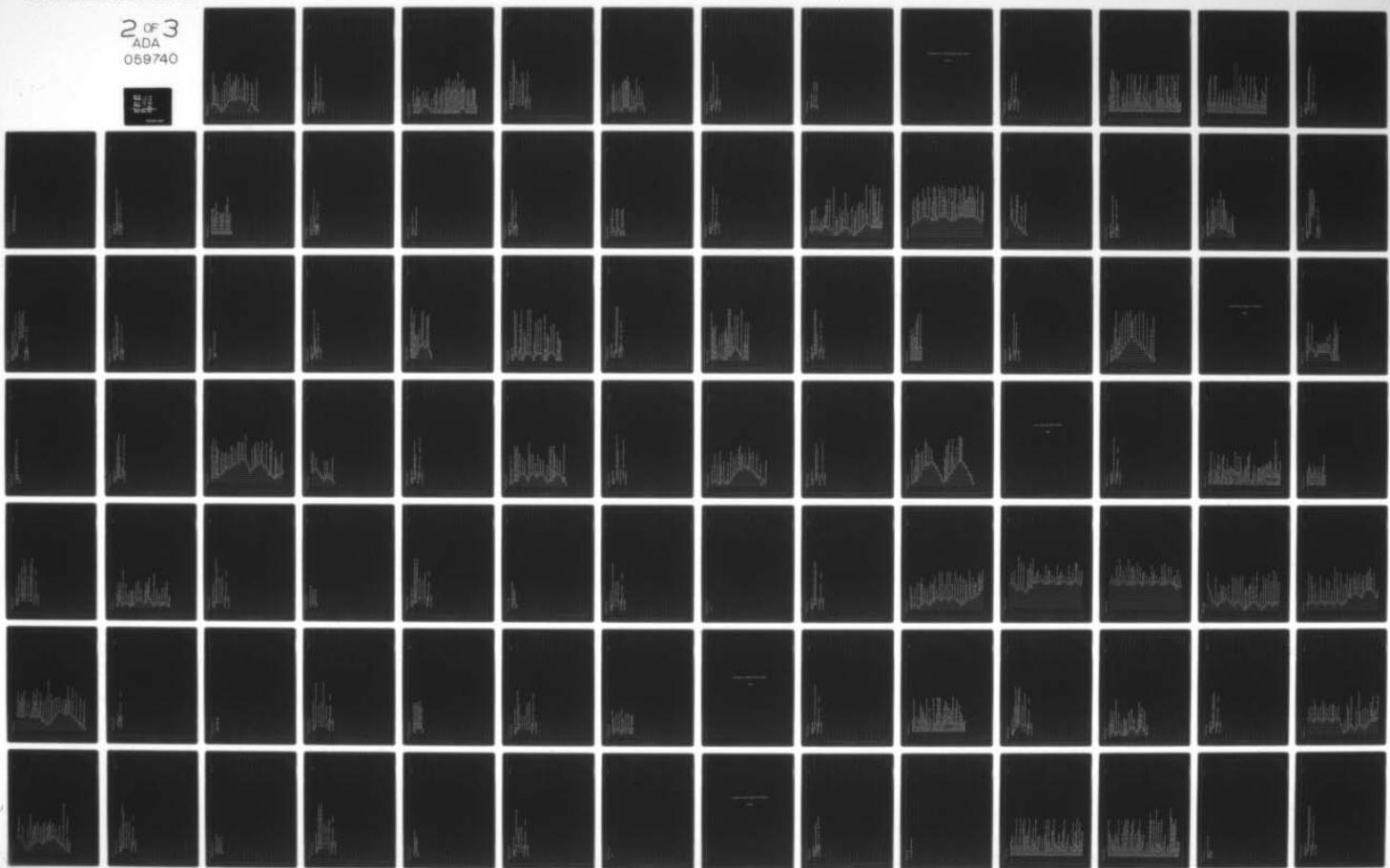
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```
.THEN
    • CONSTRUCT CMUX OUTPUT NORMAL DATA TRANSFER
    • SET WORD COUNT IN RT STATUS
    • SET RT DATA AVAILABLE BIT
.ELSE
    • CMIT OUTPUT DATA
.ENDIF
IF PREVIOUS OUTPUT READ BY PP
.THEN
    • IF AOP HAS TAKEN THE PREVIOUS BUFFER
    .THEN
        • • IF THERE IS NEW DATA TO BE SENT TO AOP
        .THEN
            • PUT RT STATUS WORD INTO OUTPUT BUFFER
            • PACK OUTPUT BUFFER
            • CONSTRUCT HEADER WORD
            • SAVE CURRENT *BIT* STATUS*
            • RESET CP DATA AVAILABLE BIT
            • IF DATA IS BEING TRANSMITTED TO AOP
            • THEN
                • • SET DATA SENT STATUS FLAG
            • ELSE
                • • FLAG NOT SET
            • ENDIF
            • SET FLAG THAT THIS DATA HAS NOT BEEN
            • ACKNOWLEDGED / REQUESTED YET
        ELSE
            • LEAVE OUTPUT BUFFER EMPTY
.ENDIF
.ELSE
    • • AOP HAS NOT TAKEN LAST BUFFER
    • • SET ERROR WORDS 2 AND 3
.ENDIF
.ELSE
    • • PP DID NOT TAKE BUFFER, SET ERROR WORD 1
.ENDIF
```

SUBROUTINE CMXDATA

ABSTRACT

THIS ROUTINE CONSTRUCTS THE 31 WORD DATA ARRAY USED AS THE  
CMUX NORMAL DATA TRANSFER TO THE AVK

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI (CSC) 01/10/78

END OF ABSTRACT

```

WORD 1 - ELECTRONIC ALTIMETER
USE HEL0(15)
WORD 2 - TACAN RANGE
PACK TACAN RANGE WITH MSB = 327.68
WORD 3 - TACAN BEARING
IF VALID BEARING DATA
  . THEN
    . . IF LESS THAN 180 DEGREES
    . . . THEN
      . . . . PACK BEARING AS IS
    . . . ELSE
      . . . . PACK BEARING - 180
    . . ENDIF
  . ELSE
    . . SEND "NO DATA"
  . ENDIF
WORD 4,5 - ATO STICK X,Y
DOFOR ATO X,Y STICK VOLTAGES
  . . PACK VOLTAGE WITH LSB=0.0195
ENDDO
WORD 6,7 - SO STICK X,Y
DOFOR SO X,Y STICK VOLTAGES
  . . PACK VOLTAGES WITH LSB=0.0195
ENDDO
WORD 8,9 - PITCH SINE,COSINE
CONVERT PITCH SINE TO 2'S COMPLEMENT BINARY
STORE INTO CMUX TEMPORARY BUFFER
CONVERT PITCH COSINE TO 2'S COMPLEMENT BINARY
STORE INTO CMUX TEMPORARY BUFFER
WORD 10,11 - ROLL SINE,COSINE
CONVERT ROLL SINE TO 2'S COMPLEMENT BINARY
STORE INTO CMUX TEMPORARY BUFFER
CONVERT ROLL COSINE TO 2'S COMPLEMENT BINARY
STORE INTO CMUX TEMPORARY BUFFER
WORD 12-27 - HEADING 4 SAMPLES, 2 SOURCES, SINE,COSINE
DOUNTIL 4 SAMPLES GENERATED
  . . CONVERT SINE TO 2'S COMPLEMENT BINARY
  . . STORE AS BOTH HEADING SINES
  . . CONVERT COSINE TO 2'S COMPLEMENT BINARY
  . . STORE AS BOTH HEADING COSINES
ENDDO
WORD 28 - INDICATED AIRSPEED
PACK HEL0(21) CONVERTED TO KNOTS
WORD 29 - BAROMETRIC ALTITUDE
PACK HEL0(15)
WORD 30 - OUTSIDE AIR TEMPERATURE
IT'S ALWAYS 25 DEGREES CENTIGRADE
WORD 31 - LATEST MAD CONVERSION
PACK GAMMAS

```

```
FUNCTION MUXPACK( SOURCE, N, SIGBIT)
ABSTRACT
  THIS FUNCTION PACKS A REAL INTO A BINARY OF REQUESTED SIZE
  THE RESULT HAS THE SIGN BIT EXTENDED THROUGH 60 BITS
SOURCE = REAL VALUE TO BE PACKED
```

N = NUMBER OF BITS IN RESULT

SIGBIT = REAL VALUE OF MSB OR LSB IN RESULT  
( MSB IF POSITIVE, LSB IF NEGATIVE)

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI (CSC) 01/27/78

END OF ABSTRACT

```
INITIALIZE RESULT VALUE  
WORK ONLY WITH POSITIVE SOURCE VALUES  
IF LSB VALUE HAS SUPPLIED  
    • THEN  
        • CALCULATE THE MSB VALUE  
    • ELSE  
        • USE THE MSB VALUE SUPPLIED  
ENDIF  
DO UNTIL ALL BITS DETERMINED IN RESULT  
    • SHIFT PREVIOUS RESULT OVER ONE BIT  
    • DETERMINE VALUE OF NEXT BIT IN RESULT  
    • MERGE IN NEXT BIT WITH PREVIOUS BITS  
    • CALCULATE NEW REMAINDER FROM SOURCE VALUE  
    • CALCULATE REAL VALUE OF NEXT BIT  
ENDDO  
IF INITIAL VALUE WAS NEGATIVE  
    • THEN  
        • COMPLEMENT RESULT  
    • ELSE  
        • IF RESULT HAS SPILLED OVER INTO SIGN BIT  
            • • THEN  
                • • SET RESULT TO *N* ONES  
            • • ELSE  
                • • LEAVE RESULT AS IS  
            • ENDIF  
ENDIF
```

FUNCTION K2SCOMP

FUNCTION K2SCOMP( NUMBER )

ABSTRACT

OBTAINS THE 2'S COMPLEMENT FORM OF A 1'S COMPLEMENT NUMBER

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI (CSC) C1/34/78

END OF ABSTRACT

```
IF NUMBER IS NEGATIVE
  THEN
    • 2'S COMPLEMENT = 1'S COMPLEMENT + 1
  ELSE
    • 2'S COMPLEMENT = 1'S COMPLEMENT
ENDIF
```

COMMUNICATION SYSTEM CONTROL GROUP MODULE

(CSCG)

PROGRAM DRIVER

PROGRAM DRIVER  
ABSTRACT

DRIVER PROGRAM FOR CSCG SOFTWARE MODULE.

CODING HISTORY

1. PROGRAMMED J. MANGES

CSC MARCH, 1978

END OF ABSTRACT

```
SET INITIAL CONDITIONS           (SOFTWARE CONTROL)
MAKE SURE UHF AUTO IS ON
INITIALIZE DATA WORDS TO INDICATE UHF-1 IS IN OPTI MODE
SET DATA WORDS TO INDICATE DATA LINK IS IN ASW MODE
SET ALL RECEIVER SIGNAL STRENGTHS TO MAXIMUM
ENDDO

ASSIGN THE BUOY IN CHUTE 1 TO SONO RCVR A
ASSIGN THE BUOY IN CHUTE 2 TO SONO RCVR B
AND ETC.

ENDDO

CHECK INITIALIZATION
CHECK ACTION OF ERROR WORDS
ERROR WORD 2
SET STATUS SENT FLAG TO 1
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
ERROR WORD 3
SENT DATA SENT FLAG TO 1
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
ERROR WORD 1
SET DATA AVAILABLE FLAGS TO OPPOSITE VALUES
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
RESET ERROR WORDS AND FLAGS
CHANGE IN BIT STATUS WORD
SET A BIT IN THE BIT STATUS WORD
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
RESET FLAGS
CSCG SELF TEST SEQUENCE
SET COMMAND WORD INTO THE INPUT BUFFER
SET BUFFER POINTER
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
RESET FLAGS
DECREMENT THE BIT COUNTER
DO WHILE I IS LESS THAN 147
ENDDO
DO WHILE I IS LESS THAN THREE
ENDDO

CSCG INITIALIZATION SEQUENCE
SET INITIALIZE TERMINAL COMMAND IN INPUT BUFFER
SET BUFFER POINTER
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
SET INITIATE PROCESSING COMMAND IN INPUT BUFFER
SET BUFFER POINTER
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
RESET FLAGS
CSCG NORMAL DATA TRANSFER SEQUENCE
SET NORMAL DATA TRANSFER COMMAND IN INPUT BUFFER
SET BUFFER POINTER
SET DATA SENT FLAG TO 1
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS
RESET FLAGS
SET NORMAL DATA TRANSFER COMMAND IN INPUT BUFFER
SET TEST DATA WORD BLOCK IN INPUT BUFFER
SET BUFFER POINTER
CHECK VARIABLES, CALL CSCG, AND CHECK THE RESULTS
RESET FLAGS
CSCG DISCRETES
```

CHANGE UHF MODE  
CHANGE SWITCH SETTING FROM OPI TO ADF MODE  
CHECK VARIABLES, CALL CSCCG, AND CHECK THE RESULTS  
RESET FLAGS

CHANGE UHF MODE  
CHANGE SWITCH SETTING FROM ADF MODE TO OPI MODE  
CHECK VARIABLES, CALL CSCCG, AND CHECK THE RESULTS

RESET FLAGS  
SET UHF CHANNEL TO 1  
RESET FLAGS  
SET UHF-1 CHANNEL NUMBER TO 1  
SET UHF CHANNEL TO 6  
SET UHF-1 CHANNEL NUMBER TO 6  
RESET FLAGS  
SET UHF CHANNEL TO 18  
SET UHF-1 CHANNEL NUMBER TO 18  
RESET FLAGS

SET UHF CHANNEL TO 32  
SET UHF-1 CHANNEL NUMBER TO 32  
RESET FLAGS

CSCCG EXTERNAL INPUTS

D/L MODE  
SET D/L MODE TO ASMD  
CHECK VARIABLES, CALL CSCCG, AND CHECK THE RESULTS  
RESET FLAGS  
SONOBUOY RECEIVER SIGNAL STRENGTH  
SET THE POSITION OF THE HELO  
SET THE POSITION OF THE BUOYS  
CHECK VARIABLES, CALL CSCCG, AND CHECK THE RESULTS  
RESET FLAGS  
SHIFT HELO POSITION  
CHECK VARIABLES, CALL CSCCG, AND CHECK THE RESULTS  
RESET FLAGS  
SHIFT HELO ALTITUDE  
CHECK VARIABLES, CALL CSCCG, AND CHECK THE RESULTS  
OPI BEARING FOR CASS BUOY IN CHUTE 2  
INDICATE CASS BUOY IN CHUTE 2  
SET VHF TRANS. ON  
SET PING TIME  
SET IN WATER FLAG  
SET RF NUMBER FOR BUOY IN CHUTE 2  
SET RF EQUAL TO 10 IN KEYSET  
MAKE SURE UHF IN OPI MODE  
CHECK VARIABLES, CALL CSCCG, AND PRINT THE RESULTS

SUBROUTINE FLAGS

SUBROUTINE FLAGS  
ABSTRACT

THIS ROUTINE RESETS THE VALUES OF THE BUFFER AND DATA  
FLAGS TO A STATE IN WHICH THE PACKPP ROUTINE MAY BE CALLED.

CODING HISTORY  
1. PROGRAMMED -

J. MANGES CSC APRIL 11, 1978

END OF ABSTRACT

SUBROUTINE FLAGS

RESET OUTPUT BUFFER FULL FLAGS  
EQUATE DATA AVAILABLE AND PP DATA AVAILABLE FLAGS

SUBROUTINE PRINT  
ABSTRACT  
PRINT DISPLAYS THE VALUES OF ALL RELEVANT CSCC VARIABLES  
WHEN CALLED BY THE DRIVER PROGRAM.  
CODING HISTORY  
1. PROGRAMMED J. MANGES CSC DEC 1977  
END OF ABSTRACT

```
      WRITE OUT THE VALUES OF THE FLAGS
      WRITE OUT BIT BY BIT THE RT WORDS
      WRITE OUT THE DATA WORDS
      WRITE OUT THE CONTENTS OF THE INPUT BUFFER
      DO WHILE I IS LESS THAN TWENTY
      ENDOU
      WRITE OUT THE DATA LINK MODE
      WRITE OUT THE OPTI BEARING
      WRITE OUT THE DISCRETE ARRAY
      DO WHILE I IS LESS THAN THREE
      ENDDO
      WRITE OUT THE VALUE OF THE BIT COUNTER
      WRITE OUT THE VALUES OF THE INPUT BUFFER POINTERS
      WRITE OUT THE ERROR FLAGS
      DO WHILE I IS LESS THAN THREE
      ENDDO
```

SUBROUTINE BITS

PAGE 1

SUBROUTINE BITS(JVALUE,NUM)

ABSTRACT  
THIS SUBROUTINE PRINTS OUT BIT BY BIT THE FIRST 16 BITS  
OF THE WORD JVALUE.

CODING HISTORY  
PROGRAMMED 1. J. MANGES CSC 12/28/77  
END OF ABSTRACT

SUBROUTINE BITS

```
DO WHILE I IS LESS THAN 16
  * ENDOF
  ENDDO
  WRITE OUT THE VALUES OF THE BIT ARRAY
```

SUBROUTINE DATAWDS

ABSTRACT

THIS SUBROUTINE PRINTS OUT ALL THE CSCG DATA WORDS WHEN  
CALLED BY THE PRINT SUBROUTINE.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC FEB. 1978  
END OF ABSTRACT

```
DO WHILE J IS LESS THAN 17
  * DO WHILE I IS LESS THAN SIXTEEN
    * * ENDDO
    DO WHILE J IS LESS THAN TWENTY NINE
      * DO WHILE I IS LESS THAN SIXTEEN
        * * ENDDO
        DO WHILE J IS LESS THAN SEVENTEEN
          DO WHILE J IS LESS THAN TWENTY-NINE
            ENDDO
```

SUBROUTINE CSCG

SUBROUTINE CSCG  
ABSTRACT

SOFTWARE SIMULATION OF THE DATA INFORMATION TRANSFER SET.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC JAN-MARCH 1978

END OF ABSTRACT

```

    *   • CHECK FOR BUFFER WRAP AROUND
    *   • IF IB IS GREATER THAN NUMMDS
    *   • .THEN
    *   •     • RESET POINTER TO BEGINNING
    *   • .ELSE
    *   •     • CHECK FOR EOI
    *   • ENDIF
    *   • CHECK FOR EOI
    *   • IF IB EQUALS IF
    *   • .THEN
    *   •     • RESET NWOUTR(6)
    *   •     • BUFFER PROCESSING IS COMPLETED
    *   •     • JUMP TO BIT COUNTER PROCESSING SECTION
    *   • .ELSE
    *   •     • CONTINUE TO READ IN FROM INPUT BUFFER
    *   • ENDIF
    ELSE
    •     • NOTHING IN INPUT BUFFER SO SKIP INPUT PROCESSING THIS CALL
ENDIF
DO BIT COUNTER PROCESSING
IF BIT IS IN PROGRESS
    THEN
        • DECREASE THE BIT COUNTER BY ONE
        • CHECK FOR END OF BIT
        • IF NCOUNTR IS EQUAL TO ZERO
        • .THEN
            • BIT HAS ENDED SO SET RECEIVE BUSY BIT TO ZERO
        • .ELSE
            • BIT IS ON SO CONTINUE
        • .ENDIF
    ELSE
        • CONTINUE ON- BIT NOT IN PROGRESS
    ENDIF
CHECK FOR QUIESCENT STATE
IF CSCG NOT IN A QUIESCENT STATE
    THEN
        • CHECK FOR BIT SELF TEST IN PROGRESS
        • IF BIT IS NOT ON OR HAS ONLY JUST BEGUN
        • .THEN
            • CHECK FOR MANUAL OR AUTO UHF MODE
            • IF UHF IS IN MANUAL MODE
                THEN
                    • READ IN OTPI/AD MODE SETTING AND CHANNEL SELECTION
                    • FROM DISCRETES
                ELSE
                    • LEAVE UHF-1 SETTINGS AS RECEIVED VIA SOFTWARE
            ENDIF
            • UPDATE STATUS OF CSCG PERIPHERALS AND MAKE DATA WORD CHA
            • (0/L MODE AND SONOBUOY RCVR SIGNAL STRENGTH)
            • OUTPUT SONOBUOY RECEIVER UNIT CHANNEL SELECTIONS TO
            • SONO30V ROUTINE
            • OUTPUT OTPI BEARING TO DTOA ROUTINE
            • CHECK TO SEE IF FP DATA AVBL FLAG AND DATA AVBL FLAG
            • ARE EQUAL
            • IF IPPDATA IS EQUAL TO IDATAVB

```

```
      . THEN
      .   . CHECK OUTPUT BUFFER FULL FLAGS
      .   . IF IBFUL1(6) AND IBFUL2(6) ARE ZERO
      . THEN
      .   .   . INITIALIZE WORD COUNTER TO ONE
      .   .   . CHECK FOR CHANGE IN RT STATUS WORD
      .   .   . IF IUPS NOT EQUAL TO ZERO
      . THEN
      .   .     . LOAD THE INPUT ARRAY
      .   .     . SET THE T/F BIT IN THE RT STATUS WORD
      .   .     . RESET THE WORD COUNTER
      .   .     . RESET THE VALUE OF IOLDBSW
      . ELSE
      .   .     . NO 0 TO 1 TRANSITIONS IN RT STATUS WORD
      .     . RESET THE VALUE OF IOLDBSW
      . ENDIF
      .   . RESET THE HEADER WORD BITS
      .   . CHECK TO SEE IF THE HEADER WORD HAS CHANGED
      .   . IF HEADER WORD HAS CHANGED SINCE THE LAST CALL
      .   . OR TRANSMIT DATA WORDS FLAG IS UP
      . THEN
      .   .     . PUT THE DATA WORD BLOCK INTO THE INPUT AR
      .   .     . DO WHILE I IS LESS THAN TWENTY-NINE
      .   .     . ENDDO
      .   .     . PUT THE DATA WORD COUNT ONTO THE RT STATUS
      .   .     . INCREMENT THE WORD COUNTER
      .   .     . SET TRANSMIT DATA WORDS FLAG TO ZERO
      .   .     . SET THE DATA SENT FLAG
      . ELSE
      .   .     . NO CHANGE IN THE DATA WORDS SO CONTINUE
      . ENDIF
      .   . CHECK TO SEE IF INPUT ARRAY IS NON-EMPTY OR
      .   . RT STATUS WORD HAS CHANGED
      .   . IF NPPWD5 IS GREATER THAN ONE OR RT STATUS
      .   . HAS CHANGED OR TRANSMIT RT STATUS WORD FLAG IS
      . THEN
      .   .     . PACK THE NEW WORDS
      .   .     . CALCULATE NPPDCT- THE PP WORD COUNT
      .   .     . CALCULATE NBYTE- THE BYTE COUNT
      .   .     . ZERO OUT LOADTPP(16)
      .   .     . PUT THE PP WORD COUNT ONTO THE FIRST BYTE
      .   .     . PUT THE BYTE COUNT ONTO THE SECOND BYTE
      .   .     . PACK THE RT STATUS WORD
      .   .     . CALL THE PACKING ROUTINE
      .   .     . ZERO OUT THE DATA WORD COUNT
      .   .     . ZERO OUT THE T/F BIT IN THE RT STATUS WORD
      .   .     . RESET THE VALUE OF IOLDRT
      .   .     . SET TRANSMIT RT STATUS WORD FLAG TO ZERO
      .   .     . RESET THE DATA AVAILABLE FLAG
      .   .     . SET THE STATUS SENT FLAG
      . ELSE
      .   .     . NO CHANGES IN RT WORDS SINCE LAST CSCG CALL
      . ENDIF
      . ELSE
      .   .     . DATA OR STATUS SENT FLAG IS STILL UP
      .   .     . OR" THE VALUES OF STATUS AND DATA SENT
```

\* \* \* \* \* FLAGS ONTO THE APPROPRIATE BIT IN  
\* \* \* \* \* THE ERROR WORDS  
\* \* \* \* \* ENDIF  
\* \* \* \* \* ELSE  
\* \* \* \* \* \* FLAGS ARE NOT EQUAL SO DON'T PACK DATA  
\* \* \* \* \* \* SET THE SIXTH BIT IN ERROR WORD i TO 1  
\* \* \* \* \* ENDOF  
\* \* \* \* \* ELSE  
\* \* \* \* \* \* bit IS IN PROGRESS SO RETURN  
\* \* \* \* \* ENDOF  
\* \* \* ELSE  
\* \* \* \* CSCC IS IN A QUIESCENT STATE SO RETURN  
\* \* ENDOF

SUBROUTINE CSCGNDP

SUBROUTINE CSCGNDP  
ABSTRACT

NORMAL DATA PROCESSING ROUTINE FOR CSCG SUBROUTINE.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC MARCH, 1976  
END OF ABSTRACT

```
CHECK FOR DIRECTION OF DATA WORD FLOW
IF K IS EQUAL TO ZERO
  THEN
    • DATA WORD FLOW IS AYK TO CSCG
    • READ IN DATA WORD BLOCK FROM THE INPUT BUFFER
    • DO WHILE L IS LESS THAN 17
      • IF IB IS GREATER THAN NUMWDS
        • THEN
          • • WRAP AROUND TO BEGINNING OF BUFFER
        • ELSE
          • • CONTINUE TO INCREMENT IB IN A NORMAL MANNER
        • ENDIF
      • • SET BUFFER ELEMENT INTO DATA WORD ARRAY
      • • ZERO OUT THE BUFFER ELEMENT JUST READ
      • • FILL UP THE IOATIN ARRAY
      • • SAVE THE VALUE OF IB
    • ENDDO
    • RESET VALUE OF IB
  ELSE
    • DATA FLOW IS CSCG TO AYK
    • • RESET DATA SENT FLAG
  ENDIF
```

SUBROUTINE SETABIT

PAGE 1

SUBROUTINE SETABIT(JWORD, NBIT, NUM)

ABSTRACT

SETABIT SETS A SPECIFIED BIT TO 0 OR 1 IN A GIVEN WORD  
CALLING PARAMETERS- 1. JWORD- WORD IN WHICH BIT IS TO BE SET  
2. NBIT- BIT NUMBER OF BIT TO BE RESET  
(THE FIRST BIT IN JWORD IS BIT 0)  
3. NUM- THE RESET VALUE OF THE BIT

CODING HISTORY

1. PROGRAMMED J. MANGES 12/19/77

END OF ABSTRACT

SUBROUTINE READBIT

SUBROUTINE READBIT(JWORD,NBIT,NEWWORD)  
ABSTRACT

READBIT EXTRACTS AND RIGHT JUSTIFIES A GIVEN BIT WITHIN A  
GIVEN WORD.

CALLING PARAMETERS-

1. JWORD- WORD CONTAINING BIT TO BE READ
2. NBIT- NUMBER OF BIT TO BE READ  
(THE FIRST BIT IN JWORD IS BIT 0)
3. NEWWORD- RIGHT JUSTIFIED RETURN VALUE  
OF BIT.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC 12/19/77  
END OF ABSTRACT

SUBROUTINE PACKPP(NR1,NPPWCS)

ABSTRACT

PACKPP WRITES OUT THE HEADER WORD IN THE OUTPUT ARRAY  
AND THE NON-ZERO CONTENTS OF THE INPUT ARRAY.

CODING HISTORY

1. PROGRAMMED J. HANGES CSC DEC. 1977  
END OF ABSTRACT

SUBROUTINE PACKPP

DO WHILE I IS LESS THAN NPPWDS+200  
ENDDO

PAGE 2

SUBROUTINE SONOINF

PAGE 1

SUBROUTINE SONOINF  
ABSTRACT

THIS ROUTINE OUTPUTS SONOBUOY RECEIVER UNIT CHANNEL SELECTION  
TO THE SONOBOY ROUTINE.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC MARCH 1978

END OF ABSTRACT

```
OUTPUT SONOBUOY RECEIVER UNIT CHANNEL SELECTIONS TO SONOBOY RCUFIN  
OBTAIN SWITCH FUNCTION VALUES FROM DATA WORDS  
TRANSLATE THE SWITCH FUNCTION VALUES INTO CHANNEL NUMBERS  
AND INSERT INTO THE IRFCH ARRAY  
DO WHILE K IS LESS THAN EIGHT  
    DO WHILE I IS LESS THAN 32  
        IF NKCVR(K) EQUALS ICHAN(I,I)  
            THEN  
                PLACE THE CHANNEL NUMBER INTO THE IRFCH ARRAY  
                CONTINUE THE PROCESS FOR THE NEXT RECEIVER UNIT  
                GO TO 200  
            ELSE  
                CONTINUE TO LOOK FOR THE CHANNEL NUMBER  
                CORRESPONDING TO THE SWITCH FUNCTION VALUE  
            ENDIF  
        ENDDO  
    ENDDO
```

SUBROUTINE HEADER

SUBROUTINE HEADER  
ABSTRACT

THIS SUBROUTINE SETS BITS IN THE OUTGONG HEADER DATA WORD TO INDICATE CHANGES IN DATA WORDS SINCE THE LAST CSCG CALL.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC MARCH 1978  
CHECK TO SEE WHICH OUTGOING DATA WORDS HAVE CHANGED SINCE THE LAST CSCG CALL  
DO WHILE I IS BETWEEN TWO AND THIRTEEN  
IF IDATOUT(I) HAS CHANGED

THEN  
SET THE APPROPRIATE HEADER WORD BIT TO INDICATE A CHANGE  
ELSE  
SET THE APPROPRIATE HEADER WORD BIT TO INDICATE NO CHANGE  
ENDIF

ENDDO

DO WHILE I IS LESS THAN 2  
IF IDATOUT(I+13) OR IDATOUT(I+14) HAS CHANGED

THEN  
SET THE HEADER WORD BIT TO INDICATE A CHANGE  
ELSE  
SET THE HEADER WORD BIT TO INDICATE NO CHANGE  
ENDIF

ENDDO

CHECK FOR CHANGES IN THE REMAINING DATA WORDS NOT COVERED BY THE HEADER WORD  
DO WHILE L IS LESS THAN TWENTY-NINE

IF IDATOUT(L) HAS CHANGED  
THEN  
SET FLAG TO TRANSMIT THE DATA WORDS

ELSE

CONTINUE TO LOOK FOR DATA WORD CHANGES  
ENDIF

ENDDO

RESET THE VALUES OF THE OLD DATA WORDS  
RESET THE VALUE OF TOLDAT(I)  
DO WHILE J IS LESS THAN 29  
ENDDO

SUBROUTINE PERIPH

SUBROUTINE PERIPH

ABSTRACT  
PERIPH UPDATES THE SONOBUOY RECEIVER SIGNAL STRENGTH AND THE  
CURRENT D/L MODE SETTING AND SETS THE APPROPRIATE DATA WORD 3

CODING HISTORY  
1. PROGRAMMED J. MANGES CSC MARCH 1978  
END OF ABSTRACT

## SUBROUTINE PERIPH

PAGE 2

```
SET THE CONSTANT C=DMAX/7 WHERE DMAX IS THE DISTANCE AT WHICH
SONOBUOY SIGNAL STRENGTH JUST REACHES ZERO
UPDATE PERIPH EQUIPMENT OPERATING STATUS
CHECK STATUS OF DATA LINK MODE (ASW OR ASMD)
IF D/L MODE IS ASW
  THEN
    • SET BIT 0 IN IDATOUT(18) TO 1
  ELSE
    • SET BIT 0 IN IDATOUT(18) TO 0
  ENDIF
  UPDATE SONO RCVRS 1.0-2-SIGNAL STRENGTH
  LOOP THRU FOR EIGHT SONOBUOY RECEIVER UNITS
  DO WHILE K IS LESS THAN EIGHT
    • CALCULATE THE DISTANCE FROM HELO TO BUOY ASSIGNED TO RCVR UNI
    • ASSIGN A NUMBER (0-7) TO THE SIGNAL STRENGTH FOR EACH RECEIVE
    • DO WHILE N IS LESS THAN SEVEN
      • • • IF DIST(K) GE IN-1)*C AND LT N*C
        • • • THEN
          • • •   • ASSIGN SIGNAL STRENGTH LEVEL &-N TO DIST(K)
        • • • ELSE
          • • •   • CONTINUE LOOPING THROUGH DISTANCE INTERVALS
        • • • ENDIF
      • • • ENDDO
    • • • SINCE LOOP IS EXHAUSTED DIST(K) IS SO LARGE THAT ISIGSTR(K)=0
  ENDDO
  ZERO OUT STATUS WORD 18
  INSERT SIGNAL STRENGTH FOR RECEIVER UNITS A,B,E,F
  ZERO OUT STATUS WORD 19
  INSERT SIGNAL STRENGTH FOR RECEIVER UNITS C,D,G,H
```

SUBROUTINE UDICP

SUBROUTINE UDICP  
ABSTRACT

THIS SUBROUTINE DETECTS CHANGES IN SWITCH SETTINGS FOR UHF  
MODE AND CHANNEL SELECTION AND RESETS THE APPROPRIATE BITS  
IN THE OUT-GOING DATA WORDS.

CODING HISTORY

1. PROGRAMMED- J. MANGES CSC MARCH 1978

END OF ABSTRACT

UPDATE UHF-1 MODE SELECTION (OTPI OR ADF)  
CHECK MODE SELECT SWITCH SETTING  
RESET DATA WORD BITS IN STATUS WORD NO. 20  
UPDATE UHF-1 CHANNEL SELECTION  
BLANK OUT THE CHANNEL SELECTION FIELD IN IDATOUT(13)  
CHECK UHF-1 CHANNEL SELECT UNITS SWITCH SETTING AND COPY IT  
INTO THE DATA WORD  
CHECK THE UHF-1 CHANNEL SELECT TENS SWITCH SETTING AND COPY IT  
INTO THE DATA WORD

SUBROUTINE DTOAINF

SUBROUTINE DTOAINF  
ABSTRACT

THIS ROUTINE OUTPUTS OPII BEARING TO THE DTOA SUBROUTINE.

CODING HISTORY

1. STOLEN FROM HELONAV SUBROUTINE MAY, 1978

END OF ABSTRACT

```
CHECK UHF-1 MODE  
IF UHF IS IN OTPI MODE  
  THEN  
    READ RF CHANNEL SELECTION FROM DISCRETES  
    FIND A LAUNCHED AND ACTIVE BUOY TUNED TO THE ABOVE RF CHANNEL  
    LOOP THRU FOR 32 BUOYS  
    DO WHILE I IS LESS THAN 32  
      IF BUOY IS STILL ACTIVE AND IN THE WATER  
        THEN  
          IF TIME TO PING AND TIME SINCE LAST PING OK  
            THEN  
              IF BUOY IS CASS MAKE SURE VHF TRANS. IS ON  
              THEN  
                IF SWITCH SETTING COINCIDES WITH BUOYRF N  
                  THEN  
                    SET THE CHUTE NUMBER OF THE BUOY PRE  
                      TUNED TO THE UHF RADIO  
                      CALCULATE THE OTPI BEARING  
                ELSE  
                  CONTINUE TO LOOP THRU THE BUOYS  
                ENDIF  
              ELSE  
                IF BUOY IS CASS-TYPE AND VHF TRANS. NOT ON  
                  ENDIF  
              ELSE  
                OVER 20 SEC SINCE LAST PING AND NO NEW PING YE  
                  ENDIF  
              ELSE  
                IF BUOY NOT STILL ACTIVE OR NOT IN THE WATER  
                  ENDIF  
                ENDIF  
              ENDIF  
            ENDIF  
          ENDIF  
        ENDIF  
      ENDIF  
    ENDIF  
  ENDIF  
ELSE  
  LOOP IS EXHAUSTED-NO BUOY TUNED TO UHF  
ELSE  
  UHF NOT IN OTPI MODE SO NO OTPI BEARING DETERMINATION  
ENDIF
```

MULTIFUNCTION CONTROL SET MODULE

(MFCS)

```
DO UNTIL THERE IS NO MORE DATA
  . DO UNTIL ALL ID POSSIBILITIES HAVE BEEN TESTED
    . . IF ID MATCHES
    . . . THEN
      . . . . SET DATA TYPE INDEX AND EXIT LOOP
      . . . ELSE
      . . . ENDIF
    . . ENDDO
    . CASE DATA TYPE (IDX)
    . . *IDX *EQ. 1
    . . . INDISCRETES
    . . . *IDX *EQ. 2
    . . . DATA FROM AYK
    . . . *IDX *EQ. 3
    . . . NEW BIT STATUS
    . . . *IDX *EQ. 4
    . . . RI STATUS WORD CHANGE
    . . . *IDX *EQ. 5
    . . . PP DATA AVAIL BIT CHANGED
    . . END CASE
  END DO
  RESET OUTDISCRETE ARRAY *ICUT*
  CALL THE MFCS MODULE TO PROCESS THE CURRENT DATA SET
  PRINT MFCS' OUTPUT BUFFERS AND FLAGS
  DO UNTIL ALL *NIND* WORDS ARE RESET TO ZERO
  END DO
```

```
DO UNTIL ALL WORDS HAVE BEEN EXPANDED
  . . DO UNTIL ALL BITS HAVE BEEN EXPANDED FOR A GIVEN WORD
    . . END DO
  END DO
```

SUBROUTINE MFCS

SUBROUTINE MFCS  
ABSTRACT

THIS ROUTINE PROCESSES SWITCH CLOSURE DATA FOR THE  
MULTIFUNCTION CONTROL SETS, ATO AND SO. DATA IS TRANSFERRED  
BETWEEN THE SETS AND THE AOP.

CODING HISTORY  
1. PROGRAMMED -- ROBERT J. HUBER NOVEMBER 1977 (CSC)  
END OF ABSTRACT

```
DO WHILE IKEYSET EQUAL FROM ONE(AYK) TO TWO (SO)
    • RESET OUTPUT BUFFER WORD COUNTER AND BUFFER WORD ONE
    • SET INPUT BUFFER POINTER
    • LOOP THRU AYK INPUT BUFFER UNTIL A WORD WITH ZERO
        IS ENCOUNTERED -- BUFFER EMPTY INDICATOR
    • IF THE 1-TH WORD OF BUFFER NOT ZERO
        • THEN
            • DECODE AOP COMMAND WORD
            • IF MODE/DISCRETE DATA COMMAND
                THEN
                    • DETERMINE TYPE OF DATA
                    • IF DATA WORD COUNT IS ONE
                        • THEN
                            • INITIATE KEYSET
                        ELSE
                            • TEST FOR INITIATE PROCESSING
                            • IF DATA WORD COUNT IS FOUR
                                • THEN
                                    • INITIATE PROCESSING
                                ELSE
                                    • TEST FOR INITIATE SELF-TEST
                                    • IF DATA WORD COUNT IS THREE
                                        • THEN
                                            • INITIATE SELF-TEST MODE
                                            • SET RECEIVE BUSY BIT
                                        ELSE
                                            • COMMAND NOT PROCESSED BY KEYSETS
                                            • ENDIF
                                        • ENDIF
                                    ELSE
                                        • TEST FOR NORMAL DATA TRANSFER
                                        • THEN
                                            • PROCESS NORMAL DATA TRANSFER
                                            • IF RECEIVE/TRANSMIT FLAG IS ZERO
                                                • THEN
                                                    • RECEIVE DATA (CALL MFCSENDX)
                                                ELSE
                                                    • TRANSMIT DATA TO AYK
                                                    • RESET OUTPUT BUFFER FULL FLAG
                                                • ENDIF
                                            ELSE
                                                • COMMAND NOT PROCESSED BY KEYSETS
                                            • ENDIF
                                        • ENDIF
                                    • INCREMENT BUFFER WORD COUNT POINTER
                                    • AND ZERO WORD JUST PROCESSED IN IRTBUFF ARRAY
                                • ENDIF
                            ELSE
                                • CHECK QUIESCENT AND SELF-TEST FLAGS
                                • IF KEYSET IN QUIESCENT STATE
                                    • THEN
                                        • SET RETURN FLAG
                                    ELSE
                                        • TEST FOR SELF-TEST IN PROGRESS
                                        • THEN
```

```

        • DECREMENT COUNTER BY 200 MSEC
        • IF SELF-TEST NOT COMPLETED
        • THEN
        •     • SET RETURN FLAG
        • ELSE
        •     • ENCLIF
        • ELSE
        •     • ENDIF
        • ELSE
        •     • ENDIF
        • IF RETURN FLAG IS NOT SET
        • THEN
        •     • PROCESS NORMAL KEYSET
        • ELSE
        •     • RETURN
        • ENDIF
        • SET KEYSET INPUT BUFFER COUNTER
ENDO

```

SUBROUTINE MFCSDNX

SUBROUTINE MFCSDNX  
ABSTRACT

THIS ROUTINE PROCESSES SWITCH DATA FROM THE AYK TO  
THE SIMULATION HARDWARE KEYSETS

CODING HISTORY

1. PROGRAMMED ROBERT J. HUBER NOVEMBER 1977 (CSC)

END OF ABSTRACT

DETERMINE WHICH KEVSET THE DATA IS FOR  
IF IT'S THE ATO KEVSET

```
  THEN
    . BREAK DOWN SWITCH LIGHTING DATA FOR ATO KEYSET
    . ZERO FIRST FIVE WORDS OF DATA TRANSFER AND
      THE COMMAND WORD THEN INCREMENT BUFFER POINTER
    . DO WHILE THERE ARE WORDS TO BE ZEROED
      . IF POINTER AT WRAP AROUND POINT
        . THEN
          . . RESET POINTER TO *1*
        . ELSE
          . . POINTER NOT RESET
        . ENDIF
      . ENDDO
      DO WHILE I IS A VALID ATO SWITCH NUMBER 10 THRU 73
        . IF INPUT BUFFER POINTER CHANGED
          . THEN
            . . ZERO PREVIOUS BUFFER WORD
            . ELSE
              . . TAKE NO ACTION
            . ENDIF
          . IF POINTER AT WRAPAROUND POINT
            . THEN
              . . RESET POINTER TO *1*
            . ELSE
              . . POINTER NOT RESET
            . ENDIF
          . ENDDO
          . ZERO FINAL BUFFER WORD
        . ELSE
          . INSERT SWITCH LIGHTING DATA FOR THE SO KEYSET
          . SWITCH INFO FOR THE SG KEVSET IS SEQUENTIAL IN
            THE *IOUT* ARRAY
          . DC UNTIL NEXT TEN INPUT WORDS LOCATED AND SAVED
            . IF POINTER AT WRAP AROUND POINT
              . THEN
                . . RESET POINTER TO *1*
              . ELSE
                . . POINTER NOT RESET
              . ENDIF
            . ENDDO
            DO UNTIL INPUT BUFFER IS ZEROED FOR THIS TRANSFER
          . ENDIF
        . ENDIF
```

SUBROUTINE MFCSPRC

SUBROUTINE MFCSPRC  
ABSTRACT

THIS ROUTINE PROCESSES SWITCH CLOSURE DATA FROM THE ATO AND  
SO KEYSETS TO BE SENT TO THE AYK-14 ACP

PROGRAMMING HISTORY

1. PROGRAMMED -- ROBERT J. HUBER NOVEMBER 1977 (CSC)

END OF ABSTRACT

```
IF ATO FAULT BIT SET HIGH
  THEN
    • SET UP BIT TO BE TRANSMITTED TO AOP
  ELSE
    • SET OLD 911 TO NEW BIT
  ENDIF
  CHECK FOR SW CLOSURE DATA TO BE SENT TO AOP
  IF THERE IS KEYSWITCH DATA
  THEN
    • SETUP OUTPUT BUFFER TO AOP
  ELSE
    • ELSEIF
      IF THERE IS DATA TO BE OUTPUT
      THEN
        • IF THE CP AND PP DATA AVAIL FLAGS EQUAL
        • THEN
          • • IF STATUS SENT FLAG CLEAR
            THEN
              • • IF DATA SENT FLAG CLEAR
                • • THEN
                  • • • SETUP OUTPUT BUFFER FOR AOP
                  • • • • RESET OUTPUT BUFFER WORD COUNTER
                  • • • • SET STATUS SENT FLAG
                  • • • • IF DATA HAS BEEN SENT
                    • • • • • THEN
                      • • • • • • SET DATA SENT FLAG
                    • • • • • ELSE
                    • • • • • ENDIF
                    • • • • • COMPLEMENT CP DATA AVAIL FLAG
                    • • • • • SET OLD BIT TO NEW BIT
                    • • • ELSE
                      • • • • SET DATA SENT ERROR FLAG
                    • • • ENDIF
                  • • ELSE
                    • • • SET STATUS SENT ERROR FLAG
                  • • ENDIF
                • • ELSE
                  • • • SET PP ERROR FLAG
                • • ENDIF
              • • ENDIF
            • ELSE
              • • NO OUTPUT TO AOP THIS CYCLE
```

SUBROUTINE MFCSIND

SUBROUTINE MFCSIND  
ABSTRACT

THIS ROUTINE PROCESSES DISCRETES FROM THE KEYSETS  
(ATO AND SO) TO BE SENT TO THE AYK-14 AOP

CODING HISTORY

1. PROGRAMMED -- ROBERT J. HUBER NOVEMBER 1977 (CSC)

END OF ABSTRACT

```
IF THE SO KEYSET IS BEING PROCESSED
  THEN
    DECODE SO DISCRETES
    TRANSFER SO INDISCRETES INTO WORKING ARRAY
    DO UNTIL ALL INDISCRETES ARE SCANNED
      • IF SO INDISCRETE HAS *HI* BIT(S)
        THEN
          DO UNTIL ALL BITS ARE TESTED
            • IF THE J-TH BIT IS *1*
              THEN
                • INCREMENT WORD COUNT FOR RT STATUS
                • AND PUT KEY VALUE INTO HOLDING
                  AFRAY
                • IF DATA WORD COUNT IS TWO
                  THEN
                    • SET INDIS TO ZERO
                    • ELSE
                      • ENDIF
                    • ELSE
                      • ENDIF
                    • ENDDO
                  • ELSE
                    • ENDIF
                  • ENDDO
                • ELSE
                  • ENDIF
                • ENDDO
              • ELSE
                • ENDIF
              • ENDDO
            • ELSE
              • ENDIF
            • ENDDO
          • ELSE
            PROCESS ATO KEYSWITCH CLOSURES
            TRANSFER INDISCRETES INTO WORKING ARRAY FOR ATO
            DO WHILE THERE ARE KEYWORDS FOR THE ATO KEYSET
              • IF ANY OF THE BITS ARE SET IN THE INDISCRETE WORD
                THEN
                  • EXTRACT SWITCH CLOSURE DATA
                  DO WHILE J IS ONE OF THE SIXTEEN BITS OF DATA
                    • IF THE BIT IS ON
                      THEN
                        • IF IT'S AN ATO KEY SWITCH
                          • THEN
                            • INCREMENT WORD COUNT FOR RT STATUS
                            • WORD AND HOLDING ARRAY, THEN PUT
                              SWITCH NUMBER INTO HOLDING ARRAY
                            • ELSE
                              • ENDIF
                            • ELSE
                              • ENDIF
                            • ENDDO
                          • ELSE
                            • ENDIF
                          • ENDDO
                        • ELSE
                          • ENDIF
                        • ENDDO
                      • ELSE
                        • ENDIF
                      • ENDDO
                    • ELSE
                      • ENDIF
                    • ENDDO
                  • ELSE
                    • ENDIF
                  • ENDDO
                • ELSE
                  • ENDIF
                • ENDDO
              • ELSE
                • ENDIF
              • ENDDO
            • ELSE
              • ENDIF
            • ENDDO
          • ELSE
            • ENDIF
          • ENDDO
        • ELSE
          • ENDIF
        • ENDDO
      • ELSE
        • ENDIF
      • ENDDO
    • ELSE
      • ENDIF
    • ENDDO
  • ELSE
    • ENDIF
  • ENDDO
```

MAD SIGNAL PROCESSOR MODULE

(MSP)

PROGRAM MSPORIV

PROGRAM MSPORIV  
ABSTRACT

THIS PROGRAM IS A DRIVER TEST PROGRAM FOR THE MSP MODULE.

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

END OF ABSTRACT

```
ZERO INPUT BUFFER  
DO WHILE ANOTHER INPUT BUFFER WORD AVAILABLE  
    • INSERT ZERO WORD  
ENDDO  
LOCKON DETECT (SYSTEM READY) SET  
ALTITUDE = 512 FEET  
PRELIMINARY EVENT FLAG ON  
TIME OF PRELIMINARY EVENT = 100 SECONDS  
CURRENT TIME = 101 SECONDS  
R/V = 1.0  
CONFIRMED DETECT FLAG ON FOR 12,*  
TIME OF CONFIRMED DETECT = 100 SECONDS  
SLANT RANGE = 7 FEET  
DEGREES TO RADIANS  
MSB GAMMAS = 16, LSB GAMMAS = 15  
ROLL = 22.5 DEGREES  
HEADING = 11.25 DEGREES  
GROUND SPEED = 64 KNOTS  
LONGITUDE = 160 BAMS  
LATITUDE = 5.625 BAMS  
    • = 87 DEGREES 10.95 MINUTES (SOUTH)  
CHANGE IN POSITION  
DELTA X = +1 FOOT DELTA Y = -1 FOOT  
NO INITIAL FAULTS  
INITIALIZE CP,PP DATA AVAILABLE WORDS  
RESPONSE TO NO COMMANDS  
    •  
IPL SEQUENCE  
1. CONTROL COMMAND  
2. MULTI-MESSAGE TRANSFER  
3. NORMAL DATA TRANSFER  
DO WHILE ADDITIONAL IPL WORDS REQUIRED  
    • INSERT DUMMY IPL WORD IN INPUT BUFFER  
ENDDO  
4. NULL  
SELF-TEST SEQUENCE  
DO WHILE RT SAYS ITS BUSY  
    • EXECUTE MSP  
ENDDO  
INITIALIZATION SEQUENCE  
1. INITIALIZE TERMINAL  
2. TRANSMIT BIT STATUS  
3. INITIATE PROCESSING  
ALSO EXECUTE WITH NO INPUT  
DATA TRANSFER SEQUENCE  
9 WORDS TO BE TRANSFERRED  
WORD 1 - ALTITUDE = 512 FEET  
WORD 2 - SPEED = 64 KNOTS  
WORD 3 - HEADING = 11.25 DEGREES  
WORD 4 - ROLL = 22.5 DEGREES  
WORD 5 - MSB = 15  
WORD 6 - HAD LS9 = 15  
WORD 7 - POSITION = 5.625 BAMS LATITUDE, 160 BAMS LONGITUDE  
WORD 8 - ALTITUDE COMPENSATION = -7.0 FEET  
WORD 9 - OPTION = 0  
SEND DATA TO MSP  
SET UP REQUEST FOR DATA FROM MSP
```

```
SEND REQUEST TO MSP
SET UP CHANGE OF OPTION TO 1
 1 WORD TO BE TRANSFERRED
WORD 1 - OPTION = 1
SEND DATA TO MSP
SET UP CHANGE OF OPTION TO 2
 1 WORD TO BE TRANSFERRED
WORD 1 - OPTION = 2
SEND DATA TO MSP
SEND REQUEST TO SEND DATA
SET UP NULL INPUT
SEND TO MSP
ERROR PROCESSING SECTION
SEND NULL INPUT WITH ERROR BIT ACTIVATED
END OF PROGRAM
```

## SUBROUTINE XMSP(IN,LWA)

ABSTRACT  
THIS ROUTINE PERFORMS THREE FUNCTIONS

1. IT PRINTS CONTENTS OF CURRENT INPUT BUFFER
2. IT EXECUTES THE MSP MODULE
3. IT PRINTS THE CONTENTS OF THE RESULTANT OUTPUT BUFFER AND RESETS THE PP BIT TO SIGNIFY ACCEPTANCE.

IN - POINTED TO FIRST WORD OF INPUT

LWA - POINTER TO LAST WORD ADDRESS OF INPUT BUFFER  
(NOTE - INPUT BUFFER IS CIRCULAR TERMINATED BY ZERO WORD)

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

11/07/77  
END OF ABSTRACT

```
PRINT INPUT BUFFER
DO WHILE SOMETHING IN INPUT BUFFER
    • EXPAND INPUT WORD
    • PRINT INPUT WORD BIT-BY-BIT
ENDDO
IF EMPTY INPUT BUFFER AND PRINT MESSAGES SELECTED
    • THEN
        • PRINT INFORMATIVE MESSAGE
    • ELSE
        • OMIT MESSAGE
    • ENDIF
EXECUTE THE MSP MODULE
PRINT OUTPUT BUFFER
IF OUTPUT BUFFER EMPTY
    • THEN
        • IF PRINT MESSAGES SELECTED
            • .THEN
                • PRINT INFORMATIVE MESSAGE
            • .ELSE
                • OMIT MESSAGE
            • ENDIF
        • ELSE
            • PRINT HEADER WORD
            • DO WHILE SOMETHING IN OUTPUT
                • EXPAND OUTPUT WORD
                • PRINT OUTPUT WORD BIT-BY-BIT
            • ENDDO
            • SET PP BIT
        • ENDIF
    • ENDIF
    IF ERROR BIT SET OR PRINT MESSAGES SELECTED
        • THEN
            • PRINT ERROR STATUS
        • ELSE
            • OMIT MESSAGE
        • ENDIF
    IF ERROR WORD BIT IS SET
        • THEN
            • PRINT THE ERROR WORD
        • ELSE
            • DO NOT PRINT THE ERROR WORD
        • ENDIF
    END OF ROUTINE
```

SUBROUTINE ADVANCE(POINT,LWA)

ABSTRACT

THIS ROUTINE INCREMENTS A POINTER BY 1. IF THE POINTER WAS  
ALREADY SET TO AN LWA, THE POINTER IS RESET TO 1.

POINTER - CURRENT VALUE OF POINTER

LWA - LAST WORD ADDRESS FOR POINTER

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

11/34/77

END OF ABSTRACT

```
IF POINTER IS LESS THAN LWA
  • THEN
    • INCREMENT POINTER
  • ELSE
    • SET POINTER TO FWA
ENDIF
```

SUBROUTINE EXPAND(IN,IN,OUT)

ABSTRACT

THIS ROUTINE EXPANDS A WORD INTO AN N WORD ARRAY SUCH THAT  
WORD 1 CONTAINS BIT N-1, WORD 2 CONTAINS BIT N-2, ...  
AND WORD N CONTAINS BIT 0 ( RIGHT JUSTIFIED WITH ZERO FILL )

N - NUMBER OF BITS TO BE EXPANDED

IN - INPUT WORD TO BE EXPANDED

OUT - OUTPUT ARRAY TO RECEIVE EXPANSION

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

11/07/77

END OF ABSTRACT

SUBROUTINE EXPAND

DO WHILE ANOTHER BIT TO BE EXPANDED  
    • MASK OUT DESIRED BIT  
    • SET UP FOR NEXT BIT  
ENDDO

PAGE 2

SUBROUTINE PACKPP

PAGE

SUBROUTINE PACKPP( NRT, N )

ABSTRACT

THIS ROUTINE IS A DUMMY SUBSTITUTE FOR THE ACTUAL PACKPP.

NRT - NUMBER CORRESPONDING TO RT

N - NUMBER OF WORDS TO BE \*PACKED\*

CODING HISTORY

1. PROGRAMMED--ALEX POOLECKI

END OF ABSTRACT

11/07/77

## SUBROUTINE PACKPP

PAGE 2

EXIT

SUBROUTINE MSP

SUBROUTINE MSP  
ABSTRACT

THIS ROUTINE SENDS EVENT AND CONTACT MESSAGES TO AN/AYK-14  
FROM MADMOO DATA AND VERIFIES ALTITUDE, SPEED, HEADING  
AND ROLL.

CODING HISTORY

1. PROGRAMMED—ALEX PODLECKI

10/26/77  
END OF ABSTRACT

PAGE 1

```
MAIN LOOP FOR INPUT PROCESSING
IF AN/AWK-14 COMMAND
  . THEN
    • RESET STATUS SENT FLAG
  . ELSE
    • DO NOT RESET STATUS SENT FLAG
ENDIF
DO WHILE SOMETHING IN INPUT BUFFER
  • CRACK COMMAND WORD INTO BASIC FIELDS
  • IF POINTER IS LESS THAN LWA
    . THEN
      • INCREMENT POINTER
    . ELSE
      • SET POINTER TO FWA
    . ENDIF
  • IF COMMAND IS A MODE/DISCRETE
    . THEN
      PROCESS MODE/DISCRETES
      • IF MODE/DISCRETE IS INITIALIZE RT
        THEN
          • INITIALIZE RT
        . ELSE
          • CONTINUE PROCESSING MODE/DISCRETES
        . ENDIF
      • IF MODE/DISCRETE IS INITIATE SELF-TEST
        THEN
          • INITIATE SELF-TEST
        . ELSE
          • CONTINUE PROCESSING MODE/DISCRETES
        . ENDIF
      • IF MODE/DISCRETE IS INITIATE PROCESSING
        THEN
          • INITIATE PROCESSING
        . ELSE
          • CONTINUE PROCESSING MODE/DISCRETES
        . ENDIF
      • OTHER MODE/DISCRETES ARE NO-OPS
      • CONTINUE PROCESSING OTHER COMMANDS
    . ENDIF
  • IF COMMAND IS A NORMAL DATA TRANSFER
    . THEN
      • PROCESS NORMAL DATA TRANSFERS
      • IF BC IS REQUESTING DATA
        THEN
          • IIU HAS TRANSFERRED PREVIOUS OUTPUT
          • RESET DATA SENT FLAG
        . ELSE
          • DO NOT RESET DATA SENT FLAG
          • BC IS SENDING DATA
          • IF IPL IS IN PROGRESS
            . THEN
              • IPL IS BEING TERMINATED
              • DO WHILE IPL WORDS IN EUFFER
                • IGNORE IPL WORDS
                • IF *IN* IS LESS THAN *LWA*
```

```

        THEN
        * INCREMENT * IN*
        ELSE
        ENDIF
        IF OBSERVED WORD COUNT MATCHES CONTROL COMMAND
        THEN
        * SET * IN* TO *FWA*
        NO MULTI-MESSAGE WORD COUNT ERROR
        ELSE
        MULTI-MESSAGE WORD COUNT ERROR
        ENDIF
        ELSE
        INPUT DATA IS TO BE PROCESSED
        DO WHILE INPUT DATA IN BUFFER
        CRACK IDENT FIELD FOR DATA WORD
        CASE MODE VALUE (IDENT)
        GO TO (40C,410,420,430,440,450,460,470)
        IDENT + 1
        * IDENT EQ 0
        DECODE ALTITUDE
        IF WITHIN TOLERANCE
        THEN
        * NO ERROR
        ELSE
        * ERROR
        ENDIF
        SET TOLERANCE ERROR STATUS
        * IDENT EQ 1
        DECODE GROUND SPEED
        IF WITHIN TOLERANCE
        THEN
        * NO ERROR
        ELSE
        * ERROR
        ENDIF
        SET TOLERANCE ERROR STATUS
        * IDENT EQ 2
        DECODE HEADING
        IF WITHIN TOLERANCE
        THEN
        * NO ERROR
        ELSE
        * ERROR
        ENDIF
        SET TOLERANCE ERROR STATUS
        * IDENT EQ 3
        DECODE ROLL
        IF ROLL IS NEGATIVE
        THEN
        * CONVERT TO 1'S COMPLEMENT
        EXTEND SIGN AND EVALUATE
        ELSE
        EVALUATE AS IS
        ENDIF
    
```

```
        * THEN
        *     • NO ERROR
        *     • ELSE
        *         • ERROR
        * ENDIF
        SET TOLERANCE ERROR STATUS
        * IDENT EQ 4
        DECODE 1ST WORD OF TOTAL MAD FIELD
        IF *IN* IS LESS THAN *LWA*
        THEN
        *     • INCREMENT *IN*
        *
        *     • RESET *IN* TO *FWA*
        * ENDIF
        DECODE 2ND WORD OF TOTAL MAD FIELD
        * IDENT EQ 5
        OBTAIN CURRENT POSITION
        CONVERT LATITUDE TO BAMS
        CONVERT LONGITUDE TO BAMS
        IF LONGITUDE IS WEST
        THEN
        *     • SUBTRACT DEGREES FROM 360
        *
        * ELSE
        *     • LEAVE DEGREES ALONE
        * ENDIF
        DECODE LONGITUDE
        IF WITHIN TOLERANCE
        THEN
        *     • NO ERROR
        *     • ELSE
        *         • ERROR
        * ENDIF
        SET TOLERANCE ERROR STATUS
        DECODE LATITUDE
        IF WITHIN TOLERANCE
        THEN
        *     • NO ERROR
        *     • ELSE
        *         • ERROR
        * ENDIF
        SET TOLERANCE ERROR STATUS
        * IDENT EQ 6
        DECODE ALTITUDE COMPENSATION
        IF SIGN BIT = 1
        THEN
        *     • MAKE VALUE NEGATIVE
        *
        * ELSE
        *     • LEAVE VALUE POSITIVE
        * ENDIF
        * IDENT EQ 7
        DECODE OPTION
        ENCASE
        IF *IN* IS LESS THAN *LWA*
        THEN
        *     • INCREMENT *IN*
        *
        * ELSE
```



```
        * IF LOCKON DETECT NOT SET ( SYSTEM NOT READY )
        * THEN
        *   * SET FLAG TO SKIP OUTPUT THIS CYCLE
        *   * TURN SYSTEM READY BIT OFF
        * ELSE
        *   * TURN SYSTEM READY BIT ON
        * ENDIF
        * IF TRAIL NOT OUT
        * THEN
        *   * SET FLAG TO SKIP OUTPUT THIS CYCLE
        *   * TURN TRAIL BIT OFF
        * ELSE
        *   * TURN TRAIL BIT ON
        * ENDIF
        * IF MULTI-MESSAGE ERROR HAS OCCURRED
        * THEN
        *   * SET BIT 2 IN BIT STATUS WORD
        * ELSE
        *   * LEAVE BIT 2 OFF
        * ENDIF
        * IF BIT STATUS HAS CHANGED (BIT CHANGES LOW TO HIGH)
        * THEN
        *   * PLACE RT WITH T/F BIT SET AND NEW FAULTS
        *   * INTO OUTPUT BUFFER
        * ELSE
        *   * CHANGE OLD BIT STATUS TO NEW BIT STATUS
        * ENDIF
        * IF OUTPUT DATA SHOULD BE SENT
        * THEN
        *   * CASE MODE VALUE (OPTION)
        *   * GO TO 1 820, 840, 860, 880, OPTION+1
        *   * *OPTION EQ 0
        *   * PROCESS MAGNETOMETER DATA
        *   * IF PRELIMINARY EVENT FLAG ON
        *   * THEN
        *   *   * SET RT DATA AVAILABLE
        *   *   * COMPUTE PRELIMINARY TIME LATE
        *   *   * RESET FLAGS TO ZERO
        *   *   * INSERT INTO OUTPUT BUFFER
        *   * ELSE
        *   *   * OMIT PRELIMINARY EVENT DATA
        * ENDIF
        * DOWHILE MAD EVENT POSSIBLE
        *   * IF CONFIRM DETECT FLAG ON
        *   *   * SET RT DATA AVAILABLE
        *   *   * COMPUTE FINAL TIME LATE
        *   *   * INSERT INTO OUTPUT BUFFER
        *   *   * INSERT SLANT RANGE INTO OUTPUT
        *   *   * RESET FLAG TO ZERO
        *   * ELSE
        *   *   * OMIT CONFIRM DETECT DATA
        * ENDDO
        * *OPTION EQ 1
```

```

    * TRANSMIT DIGITAL MAGNETOMETER DATA
    * PROCESS AN/A/YK-14 DATA
    * SET RT DATA AVAILABLE
    * SEND 2 WORDS OF TOTAL MAD FIELD
    * SEND ALTITUDE COMPENSATION
    * IF ALTITUDE COMPENSATION IS POSITIVE
    . THEN
        * SET SIGN BIT TO 0
    ELSE
        * SET SIGN BIT TO 1
    ENDIF
    * OPTION EQ 2
    * TRANSMIT DIGITAL MAGNETOMETER DATA
    SET RT DATA AVAILABLE
    SEND 2 WORDS OF TOTAL MAD FIELD
    SEND ALTITUDE COMPENSATION = ALTITUDE
    * OPTION EQ 3
    * PROCESS AN/A/YK-14 DATA
    THIS OPTION IS TREATED AS A NO-OP
    ENDCASE
    * SET WORD COUNT IN PT STATUS
    * OMIT ALL OUTPUT DATA THIS CYCLE
    ENDIF
    * IF RT STATUS HAS CHANGED OR IF SOMETHING IS IN OUTPUT BUFFER
    THEN
        * PUT RT STATUS WORD INTO OUTPUT BUFFER
        * IF STATUS SENT FLAG IS RESET
        . THEN
            * IF DATA SENT FLAG IS RESET
            . THEN
                * IF DATA IN OUTPUT BUFFER
                . THEN
                    * SET DATA SENT FLAG
                ELSE
                    * DO NOT SET FLAG
                ENDIF
                * PACK OUTPUT BUFFER
                * CONSTRUCT HEADER WORD
                * CHANGE OLD BIT STATUS TO NEW BIT STATUS
                * SET CP DATA AVAILABLE BIT
                * SET STATUS SENT FLAG
            ELSE
                * SET APPROPRIATE BIT IN ERROR WORD 2
            ENDIF
        ELSE
            * SET APPROPRIATE BIT IN ERROR WORD 2
        ENDIF
    ELSE
        * DO NOT PUT RT INTO OUTPUT BUFFER
    ENDIF
    * SET APPROPRIATE BIT IN ERROR WORD 1
ENDIF

```

SURFACING SETS

PAGE

- VALUE = 0 OR 1
- CODING HISTORY
- 1. PROGRAMMED--ALEX PODLECKI
- END OF ABSTRACT

10/20/77

SUBROUTINE SETAII

ZERO OUT OLD VALUE  
MERGE IN NEW VALUE

PAGE 2

SUBROUTINE MSPPACK(N, SOURCE, LSB, RESULT)  
ABSTRACT

THIS ROUTINE PACKS A REAL INTO A BINARY OF REQUESTED SIZE.

N = NUMBER OF BITS IN RESULT

SOURCE = REAL VALUE TO BE PACKED

LSB = REAL VALUE OF LEAST SIGNIFICANT BINARY BIT IN RESULT

RESULT = BINARY OUTPUT WORD

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

10/26/77

END OF ABSTRACT

CALCULATE VALUE OF MOST SIGNIFICANT BIT  
DO WHILE MORE BITS REQUIRED IN RESULT  
    • SHIFT PREVIOUS RESULT OVER ONE BIT  
    • DETERMINE IF NEXT BIT SHOULD BE SET  
    • MERGE IN WITH PREVIOUS RESULT  
    • CALCULATE REMAINDER FROM SOURCE VALUE  
    • CALCULATE VALUE OF NEXT BIT  
ENDDO

SUBROUTINE LOCATE

SUBROUTINE LOCATE(X,Y,ZLAT,ZLONG)

ABSTRACT

THIS ROUTINE COMPUTES CURRENT LATITUDE AND LONGITUDE  
USING DELTA X AND DELTA Y FROM GRP

X - DELTA X (FEET)

Y - DELTA Y (FEET)

ZLAT - RESULTANT LATITUDE (DEGREES)

ZLONG - RESULTANT LONGITUDE (DEGREES)

CODING HISTORY

1. STOLEN FROM AIAKEY -- ALEX PODLECKI 11/28/77

END OF ABSTRACT

SUBROUTINE LOCATE

```
CONVERT GRP LATITUDE TO DEGREES
IF LATITUDE IS SOUTH
  • THEN
    • MAKE DEGREES NEGATIVE
  • ELSE
    • LEAVE SIGN AS POSITIVE
ENDIF
CONVERT GRP LONGITUDE TO DEGREES
IF LONGITUDE IS WEST
  • THEN
    • MAKE DEGREES NEGATIVE
  • ELSE
    • LEAVE SIGN AS POSITIVE
ENDIF
ADD DELTA X TO LATITUDE
ADD DELTA Y TO LONGITUDE
```

NAVIGATION INTERFACE UNIT MODULE

(NIU)

PROGRAM NIU01V

PROGRAM NIU01V  
ABSTRACT

THIS PROGRAM IS A DRIVER TEST PROGRAM FOR THE NIU1 MODULE.

CODING HISTORY

1. PROGRAMMED---ALEX PODLECKI

END OF ABSTRACT

PAGE 1

```
ZERO INPUT BUFFER
DOWHILE ANOTHER INPUT BUFFER WORD AVAILABLE
    * INSERT ZERO WORD
ENDDO

DEGREES TO RADIANS
NO INITIAL FAULTS
INITIALIZE CP,PP DATA AVAILABLE WORDS
INITIALIZE STATUS/DATA SENT FLAGS
SELECT TACAN FOR PILOT/AUTO
RESPONSE TO NO COMMAND
SELF-TEST SEQUENCE
INSERT INITIATE SELF-TEST INTO INPUT BUFFER
EXECUTE NIU
DOWHILE NIU1 APPEARS TO BE BUSY
    * EXECUTE NIU1
ENDDO

INSERT TRANSMIT BIT STATUS INTO INPUT BUFFER
EXECUTE NIU
INITIALIZATION SEQUENCE
INSERT INITIALIZE TERMINAL INTO INPUT BUFFER
INSERT TRANSMIT BIT STATUS INTO INPUT BUFFER
INSERT INITIATE PROCESSING INTO INPUT BUFFER
EXECUTE NIU
DATA TRANSFER SEQUENCE
NORMAL DATA TRANSFER OF 6 WORDS
WORD 1 - TACTICAL RANGE = 1.0078125 MILES
WORD 2 - TACTICAL BEARING = 180.010986
WORD 3 - DRIFT ANGLE = 90.010986
WORD 4 - PILOTS HEADING = 180.0
WORD 5 - ATOS HEADING = 180.0
WORD 6 - CONTROL DATA WORD
INSERT TRANSMIT BIT STATUS COMMAND INTO BUFFER
EXECUTE NIU1
REQUEST DATA TRANSFER SEQUENCE
INSERT REQUEST FOR DATA INTO INPUT BUFFER
EXECUTE NIU
EXECUTE NIU WITH NULL INPUT 5 TIMES
ERROR PROCESSING SECTION
SET DOPPLER FAULT BIT
EXECUTE NIU1
END OF PROGRAM
```

## SUBROUTINE XNIU(LWA)

## ABSTRACT

THIS ROUTINE PERFORMS 3 FUNCTIONS OF THE CURRENT INPUT BUFFER

1. IT PRINTS THE CONTENTS OF THE CURRENT INPUT BUFFER
2. IT EXECUTES THE NIUI MODULE
3. IT PRINTS THE CONTENTS OF THE RESULTANT OUTPUT BUFFER AND RESETS THE PP BIT TO SIGNIFY ACCEPTANCE

IN - POINTER TO FIRST WORD OF INPUT

LWA - POINTER TO LAST WORD ADDRESS OF INPUT BUFFER

## CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

11/11/77

END OF ABSTRACT

```
PRINT INPUT BUFFER
DO WHILE SOMETHING IN INPUT BUFFER
    • EXPAND INPUT WORD
    • PRINT INPUT WORD BIT-BY-BIT
ENDO
IF EMPTY INPUT BUFFER AND PRINT MESSAGES SELECTED
    THEN
        • PRINT INFORMATIVE MESSAGE
    ELSE
        • OMIT MESSAGE
ENDIF
EXECUTE THE NIUI MODULE
PRINT OUTPUT BUFFER
IF OUTPUT BUFFER EMPTY
    THEN
        • IF PRINT MESSAGES SELECTED
            • THEN
                • PRINT INFORMATIVE MESSAGE
            • ELSE
                • OMIT MESSAGE
            • ENDOF
        • ELSE
            • PRINT HEADER WORD
            • DO WHILE SOMETHING IN THE OUTPUT BUFFER
                • EXPAND OUTPUT WORD
                • PRINT OUTPUT WORD BIT-BY-BIT
            • ENDO
        • • TOGGLE PP DATA AVAILABLE BIT
ENDIF
END OF ROUTINE
```

SUBROUTINE NIU1

SUBROUTINE NIU1

ABSTRACT

THIS ROUTINE UPDATES FTM BEARING FOR HELOINP  
AND TRANSFERS AN/AYK-14 NAVIGATION DATA TO DTOA.

CODING HISTORY  
1. PROGRAMMED--ALEX PCDLECKI

END OF ABSTRACT

```

        * THEN
          *   * INCREMENT *IN*
          * ELSE
          *   * SET *IN* TO *FWA*
        ENDIF
        TRANSFER PILOTS HEADING TO DIOA
        IF *IN* LESS THAN *LWA*
        THEN
          * INCREMENT *IN*
        ELSE
          * SET *IN* TO *FWA*
        ENDIF
        TRANSFER ATO HEADING TO DIOA
        IF *IN* LESS THAN *LWA*
        THEN
          * INCREMENT *IN*
        ELSE
          * SET *IN* TO *FWA*
        ENDIF
        IGNORE CONTROL DATA WORD
        IF *IN* LESS THAN *LWA*
        THEN
          * INCREMENT *IN*
        ELSE
          * SET *IN* TO *FWA*
        ENDIF
      ENDIF
    ENDIF
  ENDIF
  ENDCASE
ENDDO

OUTPUT PROCESSING
THEN
  DECREMENT TIME LEFT IN SELF-TEST
  IF SELF-TEST HAS TIMED OUT
  THEN
    *SET UP OUTPUT OF RT AND BIT STATUS WORDS
    *ELSE
    *ENDIF
  ELSE
    *IF BIT STATUS HAS CHANGED
    *THEN
      *PLACE RT WITH T/F BIT SET AND NEW FAULTS FOR
      *INTO OUTPUT BUFFER
    *ELSE
    *ENDIF
    *SET OLD BIT TO NEW BIT
  ELSE
    *IF OUTPUT DATA SHOULD BE SENT
    *THEN
      *IF TIME FOR 1 HZ DATA
      *THEN
        *SET RT DATA AVAILABLE BIT
        *SET RT WORD COUNT
        *PLACE EQUIPMENT STATUS WORDS INTO
        *OUTPUT BUFFER
        *IF TACAN SELECTED
        *THEN
          *SET TACAN BITS IN STATUS WORD 2
      *ENDIF
    *ENDIF
  *ENDIF
ENDIF

```

```
* * ELSE
*   * SET COMPUTER SELECTED BITS
* ENDIF
* ELSE
*   * NO OUTPUT THIS CYCLE
* ENDIF
* ELSE
*   * NO DATA READ BY PP
* IF ANSWER-1 HAS NOT REQUESTED PREVIOUS DATA
* THEN
*   * OUTPUT THIS CYCLE
*   * CHECK FOR RT STATUS CHANGE
*   * IF RT STATUS HAS CHANGED
*   * THEN
*     * PUT RT INTO OUTPUT BUFFER
*   * ELSE
*     * LEAVE OUTPUT ALONE
* ENDIF
* SEND DATA IN BUFFER TO IIU
* IF SOMETHING IN OUTPUT BUFFER
* THEN
*   * PACK BUFFER FOR PP
*   * CONSTRUCT HEADER WORD
*   * RESET CP DATA AVAILABLE BIT
*   * IF DATA HAS BEEN SENT
*   * THEN
*     * * SET DATA SENT FLAG
*   * ELSE
*     * * FLAG NOT SET
*   * ENDIF
* ELSE
*   * NO DATA TO BE OUTPUT
* ENDIF
* ELSE
*   * SET ERROR WORD WHEN STATUS OR DATA SENT FLAG NOT RESET
* ELSE
*   * SET ERROR WORD 1 - DATA NOT ACCEPTED BY PP
* ENDIF
END OF MODULE
```

SUBROUTINE ADVANCE

SUBROUTINE ADVANCE (POINTER,LWA)

ABSTRACT  
THIS ROUTINE INCREMENTS A POINTER BY 1. IF THE POINTER WAS  
ALREADY SET TO AN LWA, THE POINTER IS RESET TO 1.

POINTER - CURRENT VALUE OF POINTER

LWA - LAST WORD ADDRESS FOR POINTER

CODING HISTORY

1. PROGRAMMED--ALEX POOLECKI

11/04/77

END OF ABSTRACT

IF POINTER IS LESS THAN LWA  
• THEN  
•     INCREMENT POINTER  
• ELSE  
•     SET POINTER TO FWA  
ENDIF

SUBROUTINE EXPAND

ABSTRACT

THIS ROUTINE EXPANDS A WORD INTO AN N WORD ARRAY SUCH THAT  
WORD 1 CONTAINS BIT N-1, WORD 2 CONTAINS BIT N-2, ...  
AND WORD N CONTAINS BIT 0 (RIGHT JUSTIFIED WITH ZERO FILL.)

N - NUMBER OF BITS TO BE EXPANDED

IN - INPUT WORD TO BE EXPANDED

OUT - OUTPUT ARRAY TO RECEIVE EXPANSION

CODING HISTORY

1. PROGRAMMED--ALEX PODLECKI

11/07/77

END OF ABSTRACT

DOWHILE ANOTHER BIT TO BE EXPANDED  
    • MASK OUT DESIRED BIT  
    • SET UP FOR NEXT BIT  
ENDDO

SUBROUTINE PACKPP

SUBROUTINE PACKPP( NRT, N )  
ABSTRACT

THIS ROUTINE IS A DUMMY SUBSTITUTE FOR THE ACTUAL PACKPP.

NRT - NUMBER CORRESPONDING TO RT

N - NUMBER OF WORDS TO BE \*PACKED\*

CODING HISTORY

1. PROGRAMMED---ALEX PODLECKI

11/07/77  
END OF ABSTRACT

SUBROUTINE BACKPP

EXIT

PAGE 2

ORDNANCE LAUNCH CONTROL SET MODULE

(OLCS)

PROGRAM DRIVER

PROGRAM DRIVER

ABSTRACT

DRIVER PROGRAM TO TEST OLCS SUBROUTINE.

CODING HISTORY

1. PROGRAMMED J. HANGES CSC

DEC, JAN 1977.78

END OF ABSTRACT

PROGRAM DRIVER

SET INITIAL CHUTE LOADING

PAGE 2

CHECK INITIALIZATION  
CHECK ACTION OF ERROR WORDS  
ERROR WORD 2  
SET STATUS SENT FLAG TO 1  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
ERROR WORD 3  
SENT DATA SENT FLAG TO 1  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
ERROR WORD 1  
SET DATA AVAILABLE FLAGS TO OPPOSITE VALUES  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET ERROR WORDS AND FLAGS  
CHANGE IN BIT STATUS WORD  
SET A BIT IN THE BIT STATUS WORD  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
OSRU SELF TEST SEQUENCE  
SET COMMAND WORD INTO THE INPUT BUFFER  
SET BUFFER POINTER  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
DECREMENT THE BIT COUNTER  
DO WHILE I IS LESS THAN 372  
ENDDO  
DO WHILE I IS LESS THAN 3  
ENDDO  
OSRU INITIALIZATION SEQUENCE  
SET INITIALIZE TERMINAL COMMAND IN INPUT BUFFER  
SET BUFFER POINTER  
SET INITIATE PROCESSING COMMAND IN INPUT BUFFER  
SET BUFFER POINTER  
RESET FLAGS  
OSRU NORMAL DATA TRANSFER SEQUENCE  
SET NORMAL DATA TRANSFER COMMAND IN INPUT BUFFER  
SET BUFFER POINTER  
SET DATA SENT FLAG  
OSRU DISCRETE  
TORPEDO MANUAL LAUNCH COMMAND  
SET MASTER ARM ON  
SET TORPEDO ARM ON  
SET MANUAL TORPEDO FIRE DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
TORPEDO AWAY SIGNAL  
DO WHILE I IS LESS THAN SEVEN  
ENDDO  
RESET DISCRETE  
RESET FLAGS  
ATTEMPT TO FIRE TORPEDO WITH MASTER ARM OFF  
SET MASTER ARM OFF  
SET MANUAL TORPEDO FIRE DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET DISCRETE  
ATTEMPT TO FIRE TORPEDO WITH TORPEDO ARM OFF  
SET TORPEDO ARM OFF  
SET MANUAL TORPEDO FIRE DISCRETE

CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
ATTEMPT TO FIRE THREE TORPEDOES  
SET ARM AND FIRE DISCRETES  
FIRE THE SECOND TORPEDO  
RESET TORPEDO FIRE  
CALL SETABIT1A(TOG(1),2,0)  
ATTEMPT TO FIRE A THIRD TORPEDO  
SET TORPEDO FIRE DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET DISCRETES

RESET FLAGS  
SONOBUOY SELECT AND LAUNCH MODE  
SET SONOBUOY AUTO SELECT AND LAUNCH MODE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
SET SONOBUOY MANUAL LAUNCH AND SELECT DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

MANUAL SONOBUOY SELECT CHUTE 19  
SET MANUAL SONOBUOY SELECT CHUTE 19 DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

SET MASTER ARM ON  
SET MANUAL SONOBUOY LAUNCH DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET SONOBUOY LAUNCH COMMAND  
SONOBUOY AWAY SIGNAL  
DO WHILE I IS LESS THAN SEVEN  
ENDDO

RESET FLAGS  
RESET ALL DISCRETES  
RESET FLAGS

SEQUENCE 1- AUTO SELECT MODE, AUTO LAUNCH COMMAND (CHUTE 1)  
SET SONOBUOY AUTO SELECT AND LAUNCH MODE DISCRETE  
SET MASTER ARM ON  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

SET CONTROL COMMAND DATA TRANSFER COMMAND WORD IN INPUT BUFFER  
SET BUFFER POINTER  
SET CONTROL COMMAND DATA WORD IN INPUT BUFFER  
SET BUFFER POINTER  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
SONOBUOY AWAY SIGNAL  
DO WHILE I IS LESS THAN SEVEN  
ENDDO

RESET DISCRETES  
RESET FLAGS

SEQUENCE 2- MANUAL SELECT MODE, MANUAL LAUNCH COMMAND (CHUTE 16)  
SET SONOBUOY MANUAL SELECT AND LAUNCH MODE DISCRETE  
SET SONOBUOY MANUAL SELECT CHUTE 16 DISCRETE  
SET SONOBUOY MANUAL LAUNCH COMMAND DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
RESET LAUNCH COMMAND  
SONOBUOY AWAY SIGNAL

```
DO WHILE I IS LESS THAN SEVEN
ENDO
CALL PRINT
CALL OLC5
```

SUBROUTINE FLAGS

SUBROUTINE FLAGS

ABSTRACT

THIS ROUTINE RESETS THE VALUES OF THE BUFFER AND DATA AVAILABLE  
FLAGS TO A STATE IN WHICH THE PACKPP ROUTINE MAY BE CALLED.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC APRIL 11, 1974

END OF ABSTRACT

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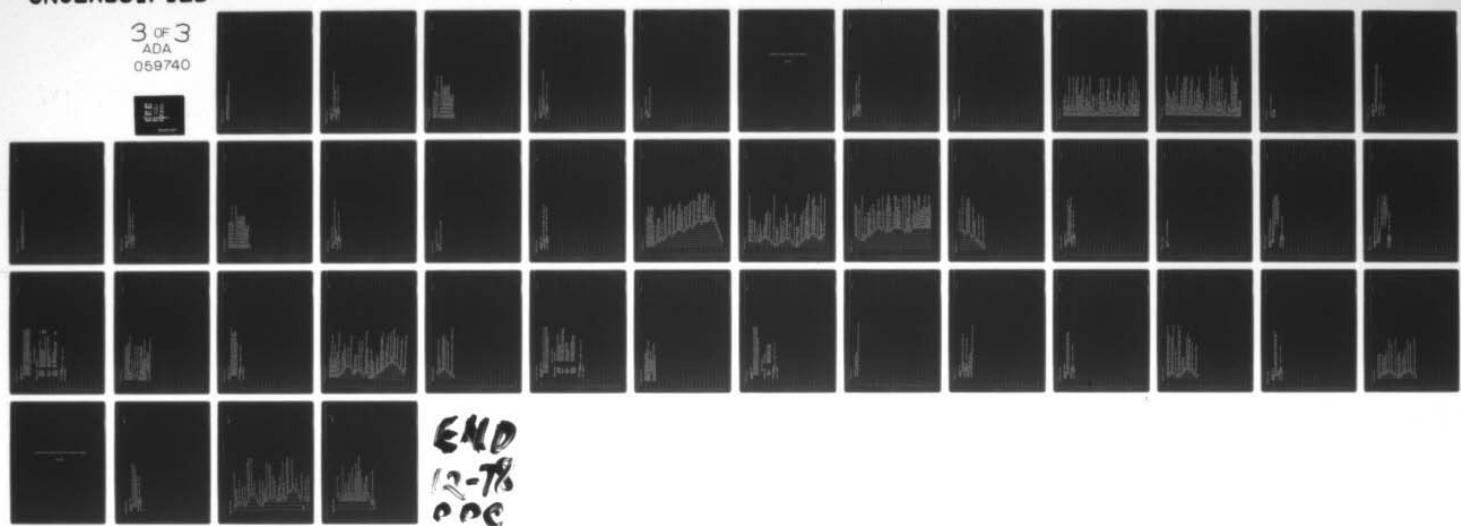
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SUBROUTINE FLAGS

RESET OUTPUT BUFFER FULL FLAGS  
EQUATE DATA AVAILABLE AND PP DATA AVAILABLE FLAGS

SUBROUTINE PRINT

SUBROUTINE PRINT

ABSTRACT  
PRINT DISPLAYS THE VALUES OF ALL RELEVANT OLD'S VARIABLES  
WHEN CALLED BY THE DRIVER PROGRAM

COODING HISTORY

1. PROGRAMMED J. MANGES CSC DEC 1977

END OF ABSTRACT

PAGE 1

```
      WRITE OUT THE VALUES OF THE FLAGS
      WRITE OUT BIT BY BIT THE 37 WORDS
      WRITE OUT BIT BY BIT THE CONTENTS OF THE INPUT BUFFER
      DO WHILE I IS LESS THAN FIFTEEN
      ENDOO
      WRITE OUT BIT BY BIT THE VALUES OF THE DISCRETE ARRAY
      WRITE OUT THE VALUES OF THE BUOYIC ARRAY
      WRITE OUT THE SONOBUOY SPLASH POINTS
      WRITE OUT THE SONOBUOY WATER ENTRY TIMES
      WRITE OUT THE VALUE OF THE SELECTED BUOY
      WRITE OUT THE VALUE OF THE BIT COUNTER
      WRITE OUT THE TORPEDO AWAY SIGNAL COUNTERS
      WRITE OUT THE BUFFER POINTERS
      WRITE OUT THE ERROR WORDS
      DO WHILE I IS LESS THAN THREE
      ENDOO
```

SUBROUTINE BITS

SUBROUTINE BITS(JVALUE,NUM)

ABSTRACT

THIS SUBROUTINE PRINTS OUT BIT BY BIT THE FIRST 16 BITS  
OF THE WORD JVALUE.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC 12/28/77  
END OF ABSTRACT

```
DO WHILE I IS LESS THAN 16
    • ENDIF
ENDDO
WRITE OUT THE VALUES OF THE BIT ARRAY
```

ORDNANCE LAUNCH CONTROL SET MODULE

(OLCS)

PROGRAM DRIVER

PROGRAM DRIVER

ABSTRACT

DRIVER PROGRAM TO TEST OLCS SUBROUTINE.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC DEC, JAN 1977, 78

END OF ABSTRACT

PROGRAM DRIVER

SET INITIAL CHUTE LOADING

PAGE - 2

CHECK INITIALIZATION  
CHECK ACTION OF ERROR WORDS  
ERROR WORD 2  
SET STATUS SENT FLAG TO 1  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
ERROR WORD 3  
SENT DATA SENT FLAG TO 1  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
ERROR WORD 1  
SET DATA AVAILABLE FLAGS TO OPPOSITE VALUES  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET ERROR WORDS AND FLAGS  
CHANGE IN BIT STATUS WORD  
SET A BIT IN THE BIT STATUS WORD  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
OSRU SELF TEST SEQUENCE  
SET COMMAND WORD INTO THE INPUT BUFFER  
SET BUFFER POINTER  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
DECREMENT THE BIT COUNTER  
DO WHILE I IS LESS THAN 372  
ENDO  
DO WHILE I IS LESS THAN 3  
ENDO  
OSRU NORMAL DATA TRANSFER SEQUENCE  
SET NORMAL DATA TRANSFER SEQUENCE IN INPUT BUFFER  
SET BUFFER POINTER  
SET DATA SENT FLAG  
OSRU DISCRETES  
TORPEDO MANUAL LAUNCH COMMAND  
SET MASTER ARM ON  
SET TORPEDO ARM ON  
SET MANUAL TORPEDO FIRE DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS  
TORPEDO AWAY SIGNAL  
DO WHILE I IS LESS THAN SEVEN  
ENDO  
RESET DISCRETE  
RESET FLAGS  
ATTEMPT TO FIRE TORPEDO WITH MASTER ARM OFF  
SET MASTER ARM OFF  
SET MANUAL TORPEDO FIRE DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET DISCRETES  
ATTEMPT TO FIRE TORPEDO WITH TORPEDO ARM OFF  
SET TORPEDO ARM OFF  
SET MANUAL TORPEDO FIRE DISCRETE

CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
ATTEMPT TO FIRE THREE TORPEDOES  
SET ARM AND FIRE DISCRETE'S  
FIRE THE SECOND TORPEDO  
RESET SONOBUOY FIRE  
CALL SETABIBI(STAT0G11), 2,0  
ATTEMPT TO FIRE A THIRD TORPEDO  
SET TORPEDO FIRE DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET DISCRETES

RESET FLAGS  
SONOBUOY SELECT AND LAUNCH MODE  
SET SONOBUOY AUTO SELECT AND LAUNCH MODE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
SET SONOBUOY MANUAL LAUNCH AND SELECT DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

MANUAL SONOBUOY SELECT CHUTE 19  
SET MANUAL SONOBUOY SELECT CHUTE 19 DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

SONOBUOY MANUAL LAUNCH COMMAND  
SET MASTER ARM ON  
SET MANUAL SONOBUOY LAUNCH DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET SONOBUOY LAUNCH COMMAND  
SONOBUOY AWAY SIGNAL  
DO WHILE I IS LESS THAN SEVEN  
ENDDO

RESET FLAGS  
RESET ALL DISCRETES

RESET FLAGS  
SEQUENCE 1- AUTO SELECT MODE, AUTO LAUNCH COMMAND (CHUTE 1)  
SET SONOBUOY AUTO SELECT AND LAUNCH MODE DISCRETE  
SET MASTER ARM ON  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

SET CONTROL COMMAND DATA TRANSFER COMMAND WORD IN INPUT BUFFER  
SET BUFFER POINTER  
SET CONTROL COMMAND DATA WORD IN INPUT BUFFER  
SET BUFFER POINTER  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

SONOBUOY AWAY SIGNAL  
DO WHILE I IS LESS THAN SEVEN  
ENDDO

RESET DISCRETES  
RESET FLAGS

SEQUENCE 2- MANUAL SELECT MODE, MANUAL LAUNCH COMMAND (CHUTE 16)  
SET SONOBUOY MANUAL SELECT AND LAUNCH MODE DISCRETE  
SET SONOBUOY MANUAL SELECT CHUTE 16 DISCRETE  
SET SONOBUOY MANUAL LAUNCH COMMAND DISCRETE  
CHECK VARIABLES, CALL OLCS, AND CHECK THE RESULTS  
RESET FLAGS

RESET LAUNCH COMMAND  
SONOBUOY AWAY SIGNAL

PROGRAM DRIVER

```
DO WHILE I IS LESS THAN SEVEN
ENDO
CALL PRINT
CALL OLCS
```

SUBROUTINE FLAGS

SUBROUTINE FLAGS

ABSTRACT

THIS ROUTINE RESETS THE VALUES OF THE BUFFER AND DATA AVAILABLE  
FLAGS TO A STATE IN WHICH THE PACKPP ROUTINE MAY BE CALLED.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC APRIL 11, 1976

END OF ABSTRACT

SUBROUTINE FLAGS

RESEY OUTPUT BUFFER FULL FLAGS  
EQUATE DATA AVAILABLE AND PP DATA AVAILABLE FLAGS

SUBROUTINE PRINT

SUBROUTINE PRINT

ABSTRACT  
PRINT DISPLAYS THE VALUES OF ALL RELEVANT OLCS VARIABLES

WHEN CALLED BY THE DRIVER PROGRAM

CODING HISTORY

1. PROGRAMMED J. MANGES CSC DEC 1977

END OF ABSTRACT

```
      WRITE OUT THE VALUES OF THE FLAGS
      WRITE OUT BIT BY BIT THE RT WORDS
      WRITE OUT BIT BY BIT THE CONTENTS OF THE INPUT BUFFER
      DO WHILE I IS LESS THAN FIFTEEN
      ENDDO
      WRITE OUT BIT BY BIT THE VALUES OF THE DISCRETE ARRAY
      WRITE OUT THE VALUES OF THE BUOYIC ARRAY
      WRITE CUT THE SONOBUOY SPLASH POINTS
      WRITE CUT THE SONOBUOY WATER ENTRY TIMES
      WRITE OUT THE VALUE OF THE SELECTED BUOY
      WRITE OUT THE VALUE OF THE BIT COUNTER
      WRITE CUT THE TORPEDO AWAY SIGNAL COUNTERS
      WRITE CUT THE BUFFER POINTERS
      WRITE OUT THE ERROR WORDS
      DO WHILE I IS LESS THAN THREE
      ENDDO
```

SUBROUTINE BITS

SUBROUTINE BITS(JVALUE,NUM)

ABSTRACT  
THIS SUBROUTINE PRINTS OUT BIT BY BIT THE FIRST 16 BITS  
OF THE WORD JVALUE.

CODING HISTORY

1. PROGRAMMED J. HANES CSC 12/26/77  
END OF ABSTRACT

SUBROUTINE BITS

```
DO WHILE I IS LESS THAN 16
    • • ENDIF
    ENDDO
    WRITE OUT THE VALUES OF THE BIT ARRAY
```

SUBROUTINE QLCS

SUBROUTINE QLCS

ABSTRACT

SOFTWARE SIMULATION OF ORDNANCE LAUNCH CONTROL SET.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC NOV-FEB, 1977-78

END OF ABSTRACT

DESIGNATE UPPER LIMIT FOR BIT COUNTER INPUT BUFFER  
 DESIGNATE NUMBER OF WORDS IN CIRCULAR INPUT BUFFER  
 DESIGNATE OLCs BIT IN IDAW(1) AND IDAW(2)  
 INPUT PROCESSING- READ FROM CIRCULAR INPUT BUFFER  
 LOCALIZE THE PRESENT VALUES OF THE BUFFER POINTERS  
 IF INPUT BUFFER IS NOT EMPTY

- THEN
  - CLEAR STATUS SENT FLAG
  - CHECK FOR NORMAL DATA TRANSFER
  - IF IRIBUFF (1B,7) EQUALS 1460628

• THEN

• ELSE

• CHECK FOR CONTROL COMMAND DATA TRANSFER

• IF IRIBUFF (1B,7) EQUALS 1442413

• THEN

- SET THE CONTROL COMMAND DATA WORD
- PROCESS THE CONTROL COMMAND DATA WORDS

• ELSE

- CHECK FOR INITIATE TERMINAL

• IF IRIBUFF (1B,7) EQUALS 1440018

• THEN

- OVERRIDE BIT IF ON
- RESET STATUS AND DATA SENT FLAGS
- SET PP AND RT DATA AVBL BITS EQUAL
- SET RECEIVE BUSY FLAG TO 0
- SET QUIESCENT STATE FLAG

• ELSE

- CHECK FOR INITIATE PROCESSING

• IF IRIBUFF (1B,7) EQUALS 144004B

• THEN

- RESET QUIESCENT STATE FLAG
- SET FLAG TO TRANSMIT DATA WORDS

• ELSE

- CHECK FOR INITIATE BIT SELF TEST

• IF IRIBUFF (1B,7) EQUALS 144003B

• THEN

- INITIALIZE COUNTER FOR BIT
- SET RECEIVE BUSY BIT IN RT STATUS WORD
- SET FLAG TO TRANSMIT RT STATUS WORD

• ELSE

- CHECK FOR INVALID OLCs WORD
- SET ERROR FLAG IF IRIBUFF (1B,7) IS IDENTICALLY ZERO OR IS A CONTROL COM DATA WORD
- IF IRIBUFF (1B,7) NOT EQUAL TO ZERO

• THEN

- SET ERROR FLAG

• ELSE

- IF IRIBUFF (1B,7) IS ZERO
- ENDIF

• ENDIF

• ENDIF

• ENDIF

• ENDIF

• ENDIF

```
    • INCREMENT POINTER AND ZERO OUT THE BUFFER WORD JUST READ
    • CHECK FOR BUFFER WRAP AROUND
    • IF IB IS GREATER THAN NUMWDS
    • THEN
        • RESET POINTER POSITION
    • ELSE
        • CHECK FOR EOI
    ENDIF
    • CHECK FOR EOI IN BUFFER
    • IF IB EQUALS IF
    • THEN
        • RESET NWURTR(17)
        • BUFFER PROCESSING IS COMPLETED
        • JUMP TO THE BIT PROCESSING SECTION
    • ELSE
        • CONTINUE TO LOOK AT INPUT BUFFER
    ENDIF
    • ELSE
        • NOTHING IN INPUT BUFFER SO SKIP INPUT PROCESSING THIS CYCLE
    ENDIF
DO BIT COUNTER PROCESSING
IF BIT IS IN PROGRESS
    • THEN
        • DECREASE THE BIT COUNTER BY ONE
        • CHECK FOR END OF BIT
        • IF NCOUNTR IS EQUAL TO ZERO
        • THEN
            • BIT HAS ENDED SO SET RECEIVE BUSY BIT TO 0
            • SET FLAG TO TRANSMIT DATA WORDS
        • ELSE
            • BIT IS ON SO CONTINUE
        ENDIF
    ELSE
        • CONTINUE ON AS BIT IS NOT IN PROGRESS
    ENDIF
CHECK FOR QUIESCENT STATE
IF OLCS NOT IN A QUIESCENT
    • THEN
        • CHECK FOR BIT SELF TEST IN PROGRESS
        • IF BIT IS NOT ON OR HAS ONLY JUST BEGUN
        • THEN
            • UPDATE ANY MANUAL INPUTS FROM THE QASP
            • DO SONOBUDY AND TORPEDO AWAY SIGNAL PROCESSING
            • CHECK TO SEE IF NECESSARY TO MAKE SPLASH OR WET CALCULATI
            • IF SBCALC NOT EQUAL TO ZERO
            • THEN
                • MAKE SPLASH POINT CALCULATIONS FOR SONOBUDY'S
                • MAKE WATER ENTRY TIME CALCULATIONS FOR SONOBUDYS
                • RESET CALCULATION-NECESSARY INDICATOR
            ELSE
                • NO CALCULATION NECESSARY SO CONTINUE
            ENDIF
        • CHECK TO SEE IF NECESSARY TO MAKE TSPLASH OR WRP CALCUL
        • IF TCALC EQUALS ONE
        • THEN
            • MAKE WATER ENTRY TIME CLACULATION FOR TORPEDOS
```



```

    • SET THE STATUS SENT FLAG
    • ELSE
    •     • NO CHANGES IN RT WORDS SINCE LAST QLCS CA
    • ENDIF
    • ELSE
    •     • OUTPUT BUFFER FULL FLAGS ARE STILL UP
    •     • "OR" THE VALUES OF STATUS SENT AND DATA SENT
    •     • FLAGS CNTO THE APPROPRIATE ERROR WORD BITS
    • ENDIF
    • ELSE
    •     • FLAGS ARE NOT EQUAL SO DON'T PACK DATA
    •     • SET BIT IN ERROR WORD
    • ENDIF
    • ELSE
    •     • BIT IS STILL IN PROGRESS SO RETURN
    • ENDIF
    • ELSE
    •     • QLCS IN A QUIESCENT STATE SO RETURN
    • ENDIF

```

SUBROUTINE PACKPP

ABSTRACT

PACKPP WRITES OUT THE HEADER WORD IN THE OUTPUT ARRAY  
AND THE NON-ZERO CONTENTS OF THE INPUT ARRAY.  
THIS IS A JUMMY SUBROUTINE FOR THE ACTUAL PACKPP ROUTINE.  
CODING HISTORY  
1. PROGRAMMED J. MANGES CSC DEC 1977  
END OF ABSTRACT

PAGE 1

SUBROUTINE PACKPP

DO WHILE I IS LESS THAN NPPHOS+240  
ENDDO

PAGE= 2

## SUBROUTINE SETABIT(JWORD,NBIT,NUM)

## ABSTRACT

SETABIT SETS A SPECIFIED BIT TO 0 OR 1 IN A GIVEN WORD  
CALLING PARAMETERS- 1. JWORD- WORD IN WHICH BIT IS TO BE SET  
2. NBIT- BIT NUMBER OF BIT TO BE RESET  
3. NUM THE RESET VALUE OF THE BIT

CODING HISTORY  
1. PROGRAMMED J. MANGES 12/19/77  
END OF ABSTRACT

## SUBROUTINE READBIT(JWORD,NBIT,NEWWORD)

ABSTRACT  
READBIT EXTRACTS AND RIGHT JUSTIFIES A GIVEN BIT WITHIN A  
GIVEN WORD  
CALLING PARAMETERS-

1. JWORD- WORD CONTAINING BIT TO BE READ
2. NBIT- NUMBER OF BIT TO BE READ  
(THE FIRST BIT IN WORD IS BIT 0)
3. NEWRD- RIGHT JUSTIFIED RETURN VALUE  
OF THE GIVEN BIT

CODING HISTORY  
1. PROGRAMMED J. MANGES CSC 12/19/77  
END OF ABSTRACT

## SUBROUTINE SPLASH

## SUBROUTINE SPLASH

#### ABSTRACT

THIS SUBROUTINE CALCULATES SONOBUOY SPLASH POINTS FOR THE QLCS SUBROUTINE. EQUATIONS USED IN THIS ROUTINE ARE TAKEN FROM APPENDIX D OF THE PROGRAM PERFORMANCE SPECIFICATION FOR LAMPS MK III AVIONICS OPERATIONAL PROGRAM. SPLASH ALSO RESETS VALUES IN THE CHUTE ARRAY AND BITS IN THE QLCS DATA WORDS AFTER A SONOBUOY LAUNCH.

SPLASH III AVIONICS OPERATIONAL PROGRAM.

TABLE OF VARIABLES

VARIABLE NAME	DESCRIPTION
HELO(21)	TRUE HELO AIRSPEED IN FEET/SECOND
HELO(11)	HELO HEADING IN RADIANS
HELO(2)	COSINE OF HELO HEADING
HELO(3)	SINE OF HELO HEADING
VL	SONG LAUNCHER SPEED IN FEET PER SECOND
DCC	DEVICE DRAG COEFFICIENT IN FEET SQRD/LB
HELO(15)	LAUNCH ALTITUDE IN FEET
C1-C9	EQN CONSTANTS
WIND(2)	WIND SPEED IN KNOTS
WIND(11)	WIND DIRECTION IN ANGULAR DEGREES
HELO(13)	HELO LAUNCH COORDINATES IN FEET
HELO(14)	
CODING HISTORY	
1. PROGRAMMED J. MANGE 11/29/77	
END OF ABSTRACT	

CONTINUOUS HISTORY

- 1: PROGRAMMED J. MANGES 11/29/77

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CHANGE WIND ANGULAR MEASUREMENT TO RADIANS  
CHANGE WIND VELOCITY MEASUREMENT TO FT/SEC  
SET THE VALUE OF DDC (DEVICE DRAG COEFFICIENT)  
RESET BITS IN THE SONOBUOY INVENTORY FIELDS OF THE OLCS  
DATA WORDS  
IF ISELBY IS LESS THAN 10  
    • THEN  
        • SET THE APPROPRIATE BIT IN DATA WORD 1  
    • ELSE  
        • SET THE APPROPRIATE BIT IN DATA WORD 2  
    ENDIF  
    SET "IN WATER" FLAG FOR THE LAUNCHED BUOY  
    RESET LAUNCH INDICATOR BIT IN DATA WORD ONE  
    CALL SETABIT (IDATWD1,2,0)  
    CALCULATE VS-THE RELEASE TRUE AIRSPEED IN FEET/SEC  
    CALCULATE K THE DRAG FACTOR  
    • • L ARMS SPASH POINT IN FEET  
    • • T ARMS TIME OF FLIGHT  
    CALCULATE THE SONOBUOY SPLASH POINT COORDINATES (GRS)

SUBROUTINE UDOASP

ABSTRACT

UDOASP UPDATES INPUTS FROM THE ORDNANCE ARM AND SELECT PANEL  
AND RESETS THE APPROPRIATE BITS IN THE OSRU DATA WORDS  
UDOASP ALSO DETECTS SONOBUOY AND TORPEDO MANUAL LAUNCH  
COMMANDS AND SETS FLAGS TO INDICATE TO THE MAIN PROGRAM  
THAT AN ORDNANCE CALCULATION IS NECESSARY.

CODING HISTORY  
1. PROGRAMMED J. MANGES CSC 12/20/77

END OF ABSTRACT

```
INITIALIZE TORPEDO COUNTER
CHECK FOR SONOBUOY AUTO OR MANUAL SELECT-LAUNCH MODE
RESET DATA WORD BITS
CHECK FOR SONOBUOY MANUAL LAUNCH COMMAND
RESET DATA WORD BIT TWO
CHECK SONOBUOY SELECT DISCRETE
CHECK TO SEE IF WANT TO SKIP MANUAL SELECTION THIS CYCLE
IF SKIP FLAG IS NOT UP
  THEN
    • CHECK THE UNITS CHUTE BITS
    • DO WHILE I IS BETWEEN SIX AND FIFTEEN
      • • IF IATOTOG(1) BIT 1 IS ON
        • • THEN
          • • • SET THE VALUE OF ISELBY
          • • ELSE
            • • • LEAVE VALUE OF ISELBY BETWEEN 0 AND 9
          • • ENDIF
        • • ENDIF
      • • CHECK THE TENS CHUTE BIT
      • • IF TENS CHUTE BIT IS ON
        • • THEN
          • • • INCREMENT THE VALUE OF ISELBY BY TEN
        • • ELSE
          • • • LEAVE VALUE OF ISELBY BETWEEN 0 AND 9
        • • ENDIF
      • • ENDIF
    • • SKIP MANUAL SELECTION THIS CYCLE AS HAVE RECEIVED AUTO
    • • SELECTION FROM SUBROUTINE CONTROL
    • • RESET ISKIP FLAG
  ENDIF
MAKE SURE TORPEDO LAUNCH BIT IS ZERO
CHECK MASTER ARM STATUS
IF MASTER ARM IS ON
  THEN
    • CHECK TORPEDO ARM STATUS
    • • IF TORPEDO ARM IS ON
      • • THEN
        • • • CHECK FOR A TORPEDO MANUAL LAUNCH COMMAND
        • • • • TRANSITION FROM OFF TO ON OF IATOTOG(1), BIT 2
        • • • • IF IUPS NOT EQUAL TO ZERO
          • • • • THEN
            • • • • • INCREMENT THE TORPEDO COUNTER
            • • • • • IF HAVE NOT ALREADY FIRED BOTH TORPEDES
              • • • • • THEN
                • • • • • • SET TORPEDO CALCULATIONS NECESSARY FLAG
                • • • • • • TCALC=1.
                • • • • • SET THE TORPEDO LAUNCH BIT IN DATA WORD ONE
                • • • • • • SET TORPEDO AWAY SIGNAL COUNTER
                • • • • • ELSE
                  • • • • • • HAVE FIRED BOTH TORPEDOES THIS RUN
                • • • • • ENDIF
              • • • • ELSE
                • • • • • • NO CALCULATION NECESSARY SO PROCEED
              • • • • ENDIF
            • • • • ELSE
              • • • • • • TORPEDO ARM NOT ACTIVATED SO NO TORPEDO LAUNCH
            • • • • ENDIF
          • • • • ENDIF
        • • • • ENDIF
      • • • ENDIF
    • • ENDIF
  ENDIF
```

SUBROUTINE "DOAASP

```
    • ENDIF
    •     • CHECK FOR A SONOBUOY MANUAL LAUNCH COMMAND
    •     • IF IANSWER EQUALS ONE
    •     •     • THEN
    •     •     •     • SET SONOBUOY CALCULATIONS NECESSARY FLAG
    •     •     •     •     • SET SONOBUOY LAUNCH INDICATOR IN DATA WORD 2
    •     •     •     •     • INITIALIZE SONOBUOY AWAY SIGNAL COUNTER
    •     •     •     • ELSE
    •     •     •     •     • NO CALCULATION NECESSARY SO PROCEED
    •     •     •     • ENDIF
    •     • ELSE
    •     •     •     •     • MASTER ARM NOT ACTIVATED SO NO SONOBUOY OR TORPEDO LAUNCH
    • ENDIF
```

**SUBROUTINE TSPLASH****SUBROUTINE TSPLASH****ABSTRACT**

THIS SUBROUTINE CALCULATES TORPEDO SPLASH POINTS FOR THE OLCS SUBROUTINE. EQUATIONS USED IN THIS ROUTINE ARE TAKEN FROM APPENDIX D OF THE PROGRAM PERFORMANCE SPECIFICATION FOR LAMPS MK III AVIONICS OPERATIONAL PROGRAM.

TABLE OF VARIABLES

VARIABLE NAME	DESCRIPTION
HELO(1)	TRUE HELO AIRSPEED IN FEET/SECOND
HELO(2)	COSINE OF HELO HEADING
HELO(3)	SINE OF HELO HEADING
VL	TORPEDO LAUNCHER SPEED IN FEET PER SEC
GAMMA	TORPEDO LAUNCHER ANGLE IN ANGULAR DEGREES
TDCC	DEVICE DRAG COEFFICIENT
HELO(15)	LAUNCH ALTITUDE IN FEET
C1-C9	EQN CONSTANTS
WIND(2)	WIND SPEED IN FEET/SECOND
WIND(1)	WIND DIRECTION IN ANGULAR DEGREES
HELO(13)	HELO LAUNCH COORDINATES IN FEET
HELO(14)	

## CODING HISTORY

1. PROGRAMMED J. MANGES CSC DEC. 1977

END OF ABSTRACT

CHANGE WIND MEASUREMENT TO RADIANS  
CHANGE WIND SPEED MEASUREMENT TO FT/SEC  
CALCULATE VS-THE RELEASE TRUE AIRSPEED IN FEET/SEC  
CALCULATE K THE DRAG FACTOR  
• L ARMS SPLASH POINT IN FEET  
• T TIME OF FLIGHT  
CALCULATE THE TORPEDO SPLASH POINT COORDINATES  
SET TORPEDO SYMBOL ACTIVE FLAG

SUBROUTINE MET

SUBROUTINE MET  
ABSTRACT

THIS SUBROUTINE CALCULATES THE WATER ENTRY TIME OF SONOBUOYS FOR THE OLCS SUBROUTINE. EQUATIONS USED IN THIS ROUTINE ARE TAKEN FROM APPENDIX D OF THE PROGRAM PERFORMANCE SPECIFICATION FOR LAMPS III AERONICS OPERATIONAL PROGRAM.

TABLE OF VARIABLES

VARIABLE NAME	DESCRIPTION
DDC	DEVICE DRAG COEFFICIENT
HELO(15)	LAUNCH ALTITUDE IN FEET
TIME	PRESENT TIME IN SECONDS
CODING HISTORY	
1. PROGRAMMED	J. MANGES CSC DEC, 1977
END OF ABSTRACT	

SUBROUTINE WET

CALCULATE K THE DRAG FACTOR  
IF THE TIME OF FLIGHT  
WATER ENTRY TIME IS EQUAL TO THE PRESENT TIME PLUS THE TIME OF FLI

PAGE 2

ROUTINE TWET  
SCHOOL

ABSTRACT THIS SUBROUTINE OF TORPEDOS.

- THIS SUBROUTINE CALCULATES THE WATER ENTRY TIME  
 • OF TORPEDOS.  
 OGING HISTORY  
 • 1. PROGRAMMED J. MANGES CSC APRIL, 1978  
 NO OF ABSTRACT  
 CALCULATE K THE DRAG FACTOR  
 • T THE TIME OF FLIGHT  
 WATER ENTRY TIME IS EQUAL TO PRESENT TIME PLUS THE TIME

SUBROUTINE CONTROL

SUBROUTINE CONTROL

ABSTRACT  
THIS SUBROUTINE EXTRACTS AUTO SELECT AND AUTO LAUNCH  
INFORMATION FROM INCOMING CONTROL COMMAND DATA WORDS.

CODING HISTORY

1. PROGRAMMED J. MANGES CSC 12/29/77  
ENC OF ABSTRACT

```
EXTRACT AUTO SELECT COMMAND FIELD FROM CONTROL COMMAND DATA WORD  
IF IASCFLD IS BETWEEN ONE AND TWENTY FIVE INCLUSIVE  
  THEN  
    * RECORD THE CHUTE NUMBER OF THE SELECTED BUOY  
    * SET FLAG TO SKIP ANY MANUAL CHUTE SELECT SETTINGS THIS CYCLE  
    * ELSE  
      * NO AUTO SELECT COMMAND INDICATED  
ENDIF  
EXTRACT AUTO LAUNCH COMMAND FIELD FROM CONTROL COMMAND DATA WORD  
IF AUTO LAUNCH COMMAND FIELD INDICATES SONOBUOY AUTO LAUNCH  
  THEN  
    * CHECK FOR MASTER ARM  
    * IF MASTER ARM IS ON  
      * THEN  
        * SET SONOBUOY CALCULATIONS NECESSARY FLAG  
        * SET LAUNCH INDICATOR BIT IN DATA WORD 1 TO ONE  
        * INITIALIZE SONOBUOY AWAY SIGNAL COUNTER  
      * ELSE  
        * NO LAUNCH AS MASTER ARM IS NOT ON  
      * ENDIF  
    * ELSE  
      * NO CALCULATION NECESSARY SO PROCEEDED  
    ENDIF
```

SUBROUTINE UD00H

SUBROUTINE UD00H  
ABSTRACT

THIS ROUTINE GENERATES SONOBUOY AND TORPEDO AWAY SIGNALS  
AND RESETS THE APPROPRIATE BITS WITHIN THE OSRU DATA  
WORDS.

CODING HISTORY

1. PROGRAMMED J. MANCES CSC 12/22/77  
END OF ABSTRACT

```
SONOBUOY AWAY SIGNAL PROCESSING
IF COUNTER IS GREATER THAN ZERO
  . THEN
    • ZERO OUT SONOBUOY AWAY BIT
    • DECREMENT THE COUNTER
    • CHECK FOR A ZERO COUNTER
    • IF COUNTER IS NOW EQUAL TO ZEFO
      • THEN
        • SET THE SONOBUOY AWAY BIT IN DATA WORD 1
      • ELSE
        • COUNTER STILL POSITIVE SO CONTINUE
      • ENDIF
    • ELSE
      • ZERO OUT THE SONOBUOY AWAY BIT IN DATA WORD 1
    • ENDIF
  TORPEDO AWAY SIGNAL PROCESSING
  IF COUNTER IS GREATER THAN TO ZERO
    . THEN
      • DECREMENT THE COUNTER
      • CHECK FOR A ZERO COUNTER
      • IF COUNTER IS NOW EQUAL TO ZERO
        • THEN
          • SET THE TORPEDO AWAY BIT IN DATA WORD 1
        • ELSE
          • COUNTER STILL POSITIVE SO CONTINUE
        • ENDIF
      • ELSE
        • ZERO OUT THE TORPEDO AWAY BIT IN DATA WORD ONE
      • ENDIF
```

INPUT/OUTPUT EXECUTIVE AND DATA COLLECTION MODULE

(IOEXEC)

SUBROUTINE IOEXEC

SUBROUTINE IOEXEC  
ABSTRACT

THIS ROUTINE TAKES PACKED DATA FROM THE LIU VIA THE PP  
PROGRAM • HANDS OFF THE PACKED DATA TO THE DATA COLL  
ROUTINE AND THEN UNPACKS THE DATA AND DELIVERS IT  
TO THE VARIOUS REMOTE TERMINAL MODULES.

PROGRAM HISTORY  
1. PROGRAMMED : ROBERT J. HUBER (CSC)  
END OF ABSTRACT

ROUTINE IOEXEC

```
DO UNTIL ALL RT INPUT BUFFERS HAVE BEEN SERVICED
  * DECODE THE COMMAND WORD
  * IF RT ADDRESS INVALID
    * THEN
      * SET FLAG TO BYPASS THIS DATA
    * ELSE
      * CONTINUE PROCESSING
    * ENDIF
    * IF RT DATA IS BEING SAVED
      * THEN
        * DO UNTIL ALL DATA STORED IN DATA COLLECTION BUFFER
          * IF DATA COLLECTION INDEX LESS THAN MAX BUFFER SIZE
            * THEN
              * INCREMENT INDEX AND STORE DATA IN D.C. BUFFER
            * ELSE
              * SET ERROR FLAG
            * ENDIF
          * ENDDO
        * ELSE
          * DATA NOT COLLECTED FOR THIS RT
        * ENDIF
      * CASE OF SURADDRESS/MODE (ISAM)
        * *ISAM *EQ. 0
        * MODE/DISCRETE DATA
        * IF CMND IS INIT TERM, INIT PROC, OR INIT SELF-TEST
          * THEN
            * UNPACK DATA AND INSERT INTO RT INPUT BUFFER
            * INCREMENT LAST-WORD-IN POINTER (INPTR)
          * ELSE
            * MODE/DISCRETE NOT PROCESSED
            * RESET STATUS SENT FLAG
          * END-IF
        * *ISAM *EQ. 1
        * NORMAL DATA TRANSFER
        * IF T/R FLAG IS R-TO-AUP TRANSFER
          * THEN
            * TRANSFER RT'S OUTPUT BUFFER TO DATACOL BUFFER
            * IF RTDATA IS BEING SAVED
              * THEN
                * DO UNTIL ALL DATA STORED IN DATA COLL BUFFER
                  * IF DATA COLLECTION INDEX LESS THAN MAX BUFFER
                    * THEN
                      * INCREMENT INDEX AND STORE DATA IN D.C.
                    * ELSE
                      * SET ERROR FLAG
                    * ENDIF
                  * ENDDO
                * ELSE
                  * DATA NOT COLLECTED FOR THIS RT
                * ENDIF
              * ELSE
                * TAKE NO DATACOL ACTION
              * ENDIF
            * Do WHILE DATA IS TO BE UNPACKED
          * ENDIF
        * ENDIF
      * ENDIF
    * ENDIF
  * ELSE
    * ENDIF
```

SUBROUTINE IOEXEC

```
* DO WHILE A WORD IS UNPACKED
*   END-DO
*   * * * * *
*ISAM *EO*2 INCREMENT *IP* FOR A STRAGGLING STATUS WORD
*ISAM *EO*3 RETRANSMIT LAST MESSAGE
*ISAM *EO*4 TRANSMIT LAST COMMAND
* THESE COMMANDS NOT PROCESSED BY THE
* RT MODULES
* RESET OUTPUT BUFFER FULL (STATUS ONLY) FLAG
*ISAM *EO*5 CONTROL COMMAND DATA TRANSFER
* UNPACK AND INSERT COMMAND WORD INTO RT-S BUFFER
* INCREMENT LAST-WORD-IN POINTER FOR RT
* UNPACK/INSERT CONTROL COMMAND DATA WORD INTO RT-S BUFFER
* INCREMENT THE AYK OUTPUT BUFFER POINTER
* AROUND STRAGGLING STATUS WORD
*ISAM *EO*6 MULTI-MESSAGE TRANSFER
* DO WHILE DATA IS TO BE UNPACKED
*   DO WHILE A WORD IS UNPACKED
*     END-DO
*   ENDCASE
*   INCREMENT THE AYK OUTBUFFER(IAYKBUF) POINTER
END DO WHILE
```